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1968-5

A Similarity Model for Flow in a Turbulent Boundary Layer

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A SIMILARITY MODEL FOR FLOW IN A TURBULENT BOUNDARY LAYER

A Thesis

Presented to the Department of Mechanical Engineering Science Brigham Young University

> In Partial Fulfillment of the Requirements for the Degree Master of Science

> > by

E. Clark Lemmon

May 1968

This thesis, by E. Clark Lemmon, is accepted in Its present form by the Department of Mechanical Engineering Science of Brigham Young University as satisfying the thesis requirement for the degree **of Master of Science.**

2 *MM* **Date**

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CHAPTER I

INTRODUCTION

One of the basic goals in engineering is to generate models which will provide a means for analytically predicting observed **phenomenon. Such a model is often modified several times to obtain better results. The purpose of th is study was to generate a model** for an equilibrium turbulent boundary layer for steady flow over a flat plate and compare the results obtained by using the model with **experimental data. Part of the objective was to also suggest ways in which the model could be modified to obtain better results.**

The significance of this project is that it provides a method to obtain a model of the variation of the eddy diffusivity across the boundary layer that will yield a velocity profile which is in **agreement with experimental data.**

The model of the eddy diffusivity across the boundary layer obtained will only be an approximation. However, since the simplified model of the eddy diffusivity will yield a good approximation to the velocity profile it will be useful. This model of the varia**tion can then be used in other applications, such as the determina**tion of the temperature profile in natural convection.

The model was generated by reducing the equation of motion from a partial differential equation to an ordinary differential

 \mathbf{I}

equation by an affine transformation. A similarity solution similar to the solution obtained by Blasius for a laminar layer flowing over a flat plate was obtained. The transformed governing equation obtained was found to be dependent on the behavior of the eddy diffusivity within the boundary layer. The modeling of this behavior is of particular significance, and will be discussed later in detail. **The results obtained with the model generated are compared with experimental data, and methods of Improving the model are suggested.**

CHAPTER 1 I

BACKGROUND MATERIAL

Flow In a turbulent boundary layer is of major in terest because It occurs in a large number of practical fluid and heat transfer **problems,,**

The motion of the fluid Is extremely complex; however there is a certain degree of regularity when the motion is viewed statically, **without an attempt to describe the detailed motion of an Individual** particle. In the past, this statistical approach has been used by **correlating a vast amount of experimental data. This without making an attempt to predict turbulent velocity profiles by application of the equations of motion.**

For purely laminar flow the shear stress at any point in the boundary layer is given by

$$
\gamma = \rho \nu \frac{du}{dy}
$$

In the region very near the wall the shear stress will vary only slightly from the shear stress at the wall, and thus in this region

$$
\gamma\approx\gamma_o
$$

Integrating and expressing the result in dimensionless form,

$$
du = (r_0 / \rho \nu) dy
$$

u = (r_0 / \rho \nu) y + C
u / [r_0 / \rho = y | r_0 / \rho / \nu + C

But at $y = 0$, $u = 0$, therefore $C = 0$ and the result is

$$
u/\sqrt{r_{0}/p}
$$
 = $y/\sqrt{r_{0}/p}/p$

The term $\sqrt{\frac{1}{6}}$ is usually called the shear velocity since it has the **dimensions of velocity and is denoted by u*. The two dimensionless groups are usually represented by the symbols u+ and y+ where**

$$
u^+= u/u^*
$$
 and $y^+=y u^*/y$

which gives for the region very near the wall In laminar flow

$$
u^+ = y^+ \tag{1}
$$

In a fully developed equilibrium turbulent boundary layer the flow is often divided into three different regions. The region In **contact with the wall Is termed the viscous sublayer. The Intermediate region Is often called the buffer zone and the outer region Is usually referred to as the fully turbulent region.**

Two laws that have given some order and meaning to turbulent flow data are the "law of the wall" attributed to Prandtl [1] and the "velocity defect law" introduced by von Karman [2]. The first pertains to the region close to the wall where the effect of viscosity is directly felt and the second pertains to the bulk of the shear **layer or turbulent core where the viscous forces become negligible.**

In the viscous sublayer the "law of the wall" postulates that the time-averaged velocity at a point in this region is a function prim arily of local or near-local conditions and does not depend very strongly on conditions at some faraway point. A list of the measurable quantities upon which the time-averaged velocity in this boundary

region might possibly depend should Include the distance from the surface y; the shear stress at the surface, γ_p ; and the viscosity and **density of the fluid,** *2/* **and^ . That is**

$$
\overline{\mu} = \overline{\mu} (\gamma, \overline{\gamma}_{0}, \nu_{1, \rho}).
$$

By application of dimensional analysis this relation can be reduced to a function of two dimensionless groups, as follows

$$
\pi / |T_0|_p = f(\sqrt{|T_0|_p}/p)
$$

The two dimensionless groups are simply u⁺ and y⁺. This gives a final **result**

$$
wt = f(\gamma^+) \qquad (2)
$$

which is known as the "law of the wall."

Assuming th at a ll the pertinent variables have been included, the above relationship implies that if turbulent velocity profiles are measured over a wide range of Reynolds numbers it should be possible **to plot u+ versus y+ , and a ll the data should fall on a single curve.**

The validity of Equation (2) for purely laminar flow has already been demonstrated. Here $f(y^+)$ is simply y^+ .

Nikuradse [3] and others have observed that within the viscous **sublayer that**

$$
u^+ = v_j^+
$$

Hence, the viscous sublayer is laminar-like in that $u^+ = y^+$, as is true for a laminar boundary layer.

The "velocity defect law" postulates that the reduction in velocity $(U_{\infty} - u)$ at a distance y is the result of a tangential stress **at the wall, independent of how this stress arises but dependent on the distance** *S* **+o which the e ffe c t has diffused from the wall. The form**

of the relationship Is

$$
\cup_{\omega}-\bar{x}=g(\sqrt{r_{\circ}}\sqrt{r_{\circ}}\sqrt{r_{\circ}})
$$

which can be reduced by dimensional analysis to

$$
(\nu_{\infty} - \bar{\alpha}) / (\overline{\nu_{e}} / \bar{\rho} = q (4/5) \tag{3}
$$

This Is the "velocity defect law."

Experimental results have shown that the regions of validity of **the law of the wall and the velocity defect law overlap one another. Millikan C4H has shown th at If there Is any region of overlap In which both laws are valid, then the functions f and g must be logarithms. A simple way to arrive at this conclusion Is to reexamine Equations (2) and (3), w ritten in the following forms:**

$$
u/u^* = f[\frac{(\gamma/5)(\delta u^*/\mu)}{\mu/2}]
$$

Since these are two expressions for the same quantity, and since a multiplying factor inside a function must have the same effect as an **additive factor outside a function, the functions f and g must be** logarithms. The first formula is usually written in the form

$$
\omega^+ = k \log y^+ + C \tag{4}
$$

Kestin and Richardson [5] have plotted data from several different sources on u⁺, y⁺ coordinates. Their results appear in Figure 1. **At very small values of y+ the data tend to approach Equation (I),** while for all y⁺ greater than about twenty-five or thirty an equation **of the form of Equation (4) fits the data very welt.**

Figure 2 shows three curves which have been proposed by various Investigators to fit the experimental data shown in Figure 1. These **investigators have described the universal turbulent velocity behavior**

Fig. I. -- Comparison of the law of the wall with experimental data. (After Kestin and Richardson [5])

Fig. 2. -- Empirical representations of the law of the wall.

near the wall in terms of one, two, or three separate algebraic equations, Martinelli [6] gives three equations to represent the data. They are

$$
y^{+} < 5
$$
 $u^{+} = y^{+}$
\n $5 < y^{+} < 30$ $u^{+} = -3.05 + 5.00 \ln(y^{+})$ (5)
\n $y^{+} > 30$ $u^{+} = 5.5 + 2.5 \ln(y^{+})$

Deissler [7], using Van Driest's [8] modification near the wall, gives two equations to fit the data which are **in the set of t**

$$
y^{+}226
$$
 $y^{+}=\sqrt{\frac{\pi}{2(0.019)}}exp(\frac{1}{2}(0.019)(kt)^{2})erf(\sqrt{\frac{0.019}{2}}ut)$
 $y^{+}>26$ $u^{+} = 3.8 + 2.78 ln(y^{+})$ (6)

Finally, Spalding [9] gives a single equation for all y⁺, which is **\i (7)**

CHAPTER 111

MATHEMATICAL MODEL

If the density and viscosity are constant, and if the body forces and pressure gradient in the x direction are zero, the governing equa**tions fo r steady two dimensional flow over a flat plate In a laminar boundary layer given by Schllchtlng [103 are**

Continuity

$$
\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0
$$
 and

Momentum (x direction)

$$
4\frac{\sqrt{2}}{4}x + \sqrt{2}x = \frac{2}{\sqrt{6}}x + \frac{2}{x^2}x
$$

Subject to the boundary conditions

y=0 : u = v = 0 $y = \omega$: $\mu = U_{\infty}$

These two equations can be combined to give

$$
\frac{\partial u^2}{\partial x} + \frac{\partial uv}{\partial y} = D \frac{\partial^2 u}{\partial y^2}
$$
 (9)

Governing Equation

It is generally assumed that the motion in a turbulent boundary layer can be separated into a mean flow whose components are \overline{u} and \overline{v} , and a superposed turbulent flow whose components are u' and v', the mean values of which are zero. Making this assumption the velocities **become**

10

LB)

$$
V = \overline{V} + V^{\perp}
$$

$$
V = \overline{V} + V^{\perp}
$$

Equation (9) than becomes

 Λ

$$
\frac{\partial}{\partial x}(\overline{u}+u^{1})^{2}+\frac{\partial}{\partial y}(\overline{u}+u^{1})(\overline{v}+v^{1})=\nu\frac{\partial^{2}}{\partial y^{2}}(\overline{u}+u^{1})
$$
 (10)

!f Equation (10) Is now time-averaged the resulting relationship Is

$$
\frac{\partial}{\partial x}(\overline{u})^2 + \frac{\partial}{\partial y}(\overline{u}\overline{v}) + \frac{\partial}{\partial y}(\overline{u})^2 + \frac{\partial}{\partial y}(\overline{u}^T\overline{v}) = \nu \frac{\partial^2}{\partial y^2}\overline{v}
$$
 (11)

Comparing Equation (II) with Equation (9) shows that two terms are added as a consequence of turbulence. Experimental results [II] have shown that

$$
\frac{\partial^2(u^1)^2}{\partial x^2} < < \frac{\partial(u^1v^1)}{\partial y^1}
$$

Equation (I!) then becomes when rearranged

$$
\frac{\partial}{\partial x}(\overline{u})^2 + \frac{\partial}{\partial y}(\overline{u}\,\overline{v}) = \nu \frac{\partial^2(\overline{u})}{\partial y^2} - \frac{\partial(u'v')}{\partial y} \tag{12}
$$

and Is called the mean momentum equation with fluctuations. If the turbulent momentum f!u< (1^) or Reynolds stress is defined as

$$
\gamma_t = -\rho \overline{(\mu'v')}
$$

Then by analogy to the laminar momentum flux

$$
\Upsilon_{t} = -M_{t} \frac{\partial \overline{W}}{\partial \overline{Y}}
$$

where

$$
Mf = -\sqrt{N_1N_1}\sqrt{3\alpha} \times 3\lambda
$$

The last term on the right hand side of Equation (12) can be expressed as follows:

$$
-\frac{1}{2y}(\overline{uv}u) = +\frac{1}{2y}(\overline{u}u + \frac{1}{2y})
$$

$$
= \frac{1}{2} \left(\frac{1}{4} \frac{1}{2} \frac{1}{4} \frac{1}{4} \right)
$$

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Making th is substitution Equation (12) then becomes

$$
\frac{1}{2}(\bar{x})^2 + \frac{1}{2\bar{y}}(\bar{x}\bar{y}) = \nu \frac{1}{2\bar{y}} \bar{y}^2 + \frac{1}{2\bar{y}}(1/2 + \frac{1}{2\bar{y}})
$$

or

$$
\overline{u} = \frac{\partial u}{\partial y} + \overline{v} \frac{\partial u}{\partial y} = \frac{\partial u}{\partial y} [(\nu + \nu_{\epsilon}) \frac{\partial u}{\partial y}] \qquad (13)
$$

The boundary conditions for flow over a flat plate are

$$
y = 0 \quad ; \quad \overline{u} = \overline{v} = 0 \quad ;
$$

$$
y = \infty \quad ; \quad \overline{u} = U_{\infty}.
$$

Equation (13) is the basic equation to be used in th is analysis. From this point on \overline{u} will be replaced by u and \overline{v} by v.

SIMILARITY SOLUTION

One of the significant results of the study is the reduction of Equation (13) from a partial differential equation to an ordinary differential equation by an affine substitution or similarity transformation. This is done by changing the variable x to ζ and y to η **where**

$$
\gamma = A\gamma / x^{n} \quad a \sim b \quad \beta = X
$$

where A and n are arbitrary constants to be chosen later. In potential **flow the velocity u can be determined from the stream function 4p. That is , Contractor** Service $N = 1/1$

$$
u = \frac{\partial}{\partial y} \psi
$$
 and
$$
v = -\frac{\partial \psi}{\partial x}
$$

where

$$
\Psi_{\rho} = U_{\infty} \Psi = U_{\infty} \times^m n \times A
$$

It is now assumed that in the turbulent boundary layer that there exists

a "stream function" $\psi_{\mathbf{t}}$ such that

$$
\psi_{\epsilon} = U_{\infty} \times h f(\eta) / A
$$

where $f(\gamma)$ means some function of γ and in the future will simply be **replaced by f . Therefore, by analogy**

$$
u = \frac{2}{34} \psi_t = U_{\infty} f^{\perp}
$$

and

$$
V = -\frac{\partial}{\partial x} \psi_{k} = \frac{n V_{\infty} x^{n-1}}{A} (\gamma f^{1} - f)
$$

where f' is $\partial (f) / \partial \eta$.

Hence the following relationships result:

$$
\frac{\partial x}{\partial y} = -\frac{\partial y}{\partial x} = -\frac{\partial y}{\partial y} = -\frac{\partial
$$

$$
\frac{\partial}{\partial y} \left[\left(\omega + \nu_{\xi} \right) \frac{\partial \nu_{\xi}}{\partial y} \right] = \nu \frac{\nu_{\infty} A^{2} f^{\prime \prime \prime}}{x^{2n}} + \nu_{\xi} \frac{\nu_{\infty} A^{2} f^{\prime \prime \prime}}{x^{2n}} + \frac{\nu_{\infty} f^{\prime \prime} A^{2}}{x^{2n}} \frac{\partial \nu_{\xi}}{\partial \eta}
$$

This, when substituted into Equation CI3), results in the following:

$$
-U_{\infty} n f''f = (U + U_{\epsilon}) \frac{U_{\infty} A^2 f''}{X^{2n-1}} + \frac{U_{\infty} f'' A^2}{X^{2n-1}} dV_{\epsilon} \qquad (14)
$$

It is obvious from Equation (14) that n should be chosen such that $n = 1/2$. This, after rearrangement, results in the following:

$$
=f^{\prime\prime}f=2(1+\frac{\mu_{2}}{\mu_{2}})\frac{\nu_{1}A^{2}}{\nu_{3}B}f^{\prime\prime\prime}+2\frac{\nu_{1}A^{2}}{\nu_{3}B}f^{\prime\prime\prime}\frac{\partial(\mu_{2}/\nu)}{\partial n}
$$

It follows that A should be chosen as

$$
A^2 = \frac{V\omega}{\mu}
$$

If $n = 1/2$ and $A^2 = \frac{1}{2}$, Equation (14) becomes

$$
-f''f = 2(1 + \frac{\nu_{\epsilon}}{\nu})f'' + 2f'' + \frac{\nu_{\epsilon}}{\nu})
$$
 (15)

14

Equation (15) becomes a nonlinear ordinary differential equation with variable coefficients if it is assumed that $\mathcal{U}_f = \mathcal{U}_f(n)$ only. With this assumption it will be possible to obtain numerical results. For a particular value of x or a specified Re_x the assumption that $\nu_{\epsilon} = \nu_{\epsilon} (\eta)$ should be very good. For more details of the similarity **solution see Appendix B.**

The boundary conditions for the flow case in consideration are

 $f(c) = 0$, $f'(c) = 0$, $f'(c) = 1$ (16) As was mentioned previously, $f = f(\gamma)$, $f' = \frac{\partial f}{\partial n}$, etc. Also $\gamma = \gamma \sqrt{\frac{U_{\infty} \times U}{U}}$, and $f' = U / U_{\infty}$ It is interesting to note that Equation (15) becomes the solution to laminar flow over a flat plate when $\mathcal{U}_{\xi} = 0$. **That Is , Equation (15) becomes** -111

$$
-\beta^{\mu}\varphi = 2 \varphi^{\mu\nu} \tag{17}
$$

which is commonly known as the Blasium solution to flow over a flat **plate subject to the usual boundary conditions.**

CHAPTER IV

NUMERICAL PROGRAM

One commonly used method to numerically solve ordinary differential equations is the method of Runge-Kutta [12]. However, such a method is really for initial-value problems, not boundary-value **problems. Hence, the solution of a boundary-value problem with the** Runge-Kutta method requires that an initial guess be made for the un**known boundary conditions at one end. The correct initial boundary condition guess results in the satisfaction of the boundary conditions** at the other end. The Newton-Raphson method [13,14] reduces the method described from a trial and error art to a convenient numerical iteration.

Hence, in obtaining the numerical solution to Equation (15) with the boundary conditions given by Equation (16) a computer program was written which utilized both the Runge-Kutta method and the Newton-Raphson technique to obtain a solution. In particular, a fourth order **Runge-Kutta method was used. For additional details on program used see Appendix C.**

CHAPTER V

EFFECT OF VARIABLE COEFFICIENTS ON SIMILARITY SOLUTION

From Equation (15) it is seen that the numerical solution of **that equation depends upon the values of the variable coefficients at** any γ . Hence, it is necessary to describe the $\mathcal{U}_\xi/\mathcal{Y}$ variation as a function of η .

Determination of Eddy Diffusivity

At this point it is of major interest to investigate the vari**ance of the eddy diffusivity across the boundary layer. Now the eddy diffusivity can be evaluated in each of the regions of the turbulent boundary layer by application of the following:**

$$
Y/\rho = (\nu_4 + \nu) d\nu/dy \qquad (18)
$$

where \mathcal{Y} has the greatest effect near the wall and $\mathcal{U}_{\mathcal{L}}$ has an increasing effect in going toward the edge of the boundary layer. **Equation (18) can be rearranged as follows:**

$$
1 + \frac{u_{2}}{2} = (\frac{\gamma}{\rho})/2 \frac{du}{dy} = \frac{1}{\frac{du^{+}}{dy^{+}}}
$$

 $\frac{u_{2}}{2} = \left[1/(\frac{du^{+}}{dy^{+}})\right] - 1$ (19)

Now from Equation (5) for $y^+ \leq 5$

$$
4^+=\nu^{+}
$$

then, using Equation (19), for $y^+ \leq 5$

16

 \mathbf{A}

$$
\frac{24}{D} = \frac{1}{\frac{dw^{+}}{dy^{+}}} - 1 = 0
$$

Hence according to Marinelli's formulation

$$
\frac{24}{L}=0
$$
 up to $y^{+}=5$ (20)

Equation (5) also gives for $5 < y^+$ 30

$$
u^{+} = -3.05 + 5.00 \ln y^{+}
$$

which when put into Equation (19) gives

$$
\frac{d_f}{dt} = \frac{1}{\frac{d}{dt}(5\ln y +)} - 1 = \frac{y^+}{5} - 1
$$
 (21)

which is a simple linear variation. Equation (5) for y^+ 30 also yields a similar variation.

The idea that $\frac{1}{2}$ goes to zero at some arbitrary distance from the wall such as $y^+ = 5$ is an oversimplification. Deissler proposed that \mathcal{U} only approaches zero as y^{+} approaches zero. Application of **Equation (19) to Equation (6) given by Deissler gives**

$$
\frac{1}{L} = 0.6119 \, u^{+}y^{+}
$$
 (22)

Van Driest [8] proposed that the wall has a dampening effect on the **variation which Deissler [73 used to obtain the following**

$$
\frac{dy}{dt} = 0.0154 \, \mu^{+}y^{+} \left[1 - \frac{e}{\mu} \left(-6.0154 \, \mu^{+}y^{+} \right) \right] \tag{23}
$$

which has been used very successfully in some heat transfer calculations referred to in Kays [I43» Spalding also takes th is exponential dampening into account as can be seen from Equation (7) and Equation (19) which gives

$$
\frac{1}{L} = \frac{0.4}{9.625} \left[e^{-\frac{4\mu^2}{2}} - 1 - k \mu^+ + \frac{(k \mu^+)^2}{2!} - \frac{(k \mu^+)^2}{3} \right] \qquad (24)
$$

Model of Eddy Dlffuslvity

If $\mathcal{U}_{\mathcal{U}}$ is equal to zero for all χ it would be expected that **the numerical solution obtained would be the same as the one obtained** for the Blasius profile. When this $\mathscr{U}_\mathscr{L}/\mathscr{D}$ variation was used the results obtained compared exactly with the results given by Schlichting [10] for the Blasius solution.

To examine the effect on the solution several different variations of $\mathscr{U}_\ell/\!\!/$ versus γ were tried and compared with a standard curve.

The general type of model of $\mathcal{U}_\ell/\mathcal{U}$ versus γ that was used is **shown In Figure 3.**

Examination of Equation (15) shows that the two values of interest for the variable coefficients are $\frac{d_{\epsilon}}{d_{\epsilon}}$ and $\frac{1}{2}$ (*LU)* at any r . The simple model of variation of $\mathcal{U}_{\mathcal{U}_{f}}$ versus p shown in Figure 3 will pro**vide a means of determining the effects of both coefficients of Equation (15).**

Several figures are included in what follows to show the effect of the \mathscr{U}_ℓ variation on the numerical solution to Equation (15). **Reference to Figure 4 will clarify the general technique to be used.** In Figure 4, the graph on $U \sharp_{\mathcal{U}}$, π coordinates represents the input variation and the graph on f', γ coordinates represents the effect on **the numerical solution of Equation (15). For example, the curve marked** by A on $\frac{df}{dx}$, γ coordinates corresponds to the curve on f', γ coordinates. The reason for presenting the results of this study in the general form shown in Figure 4 is for clarification of the effects of the variation of $\mathcal{U}_{\ell}/\!\!/$ versus ℓ on the solution of Equation (15).

To obtain the solution of Equation (15), the point where the

boundary layer ceases to e xist must be specified. For instance, in a boundary layer that is completely laminar $f'(\omega) = f'(s)$. The numeri**cal solution to Equation (15) is then forced to have the value of** $f' = 1.0$ at $\eta = 5.0$.

Figure 4 shows the effect on the turbulent boundary-layer equation of three different ramp inputs when $\gamma = \infty$ is specified as $\gamma = 8.8$. Input A gives the term $\frac{\partial \mathscr{U}}{\partial \rho}$ a value of about 11.3 while input B **P** λ **gives the slope a value of 113 and input C gives the slope a value of 226. The results plotted show that as the slope is increased from 11.3 to 113 the solution curve is raised but that somewhere between a slope of 113 and 226 the curve reaches a maximum and starts to decrease.** Additional numerical data determined that the slope for which a maximum **was reached was about 133.** The value of $\frac{d\ell}{L}$ at any η is quite a bit different for each input. From Figure 4 it is seen that the solution curve increases as the value of \mathscr{U}_ℓ increases up to a point and then decreases. From Figure 4 it is not clear which term, that is $\frac{\partial (\nu_{\epsilon}, \nu)}{\partial n}$ or $\frac{\partial \nu_{\epsilon}}{\partial n}$ is really controlling the solution. However, **examination of the numerical values, term for term, in the similarity** solution determined that the slope has a much greater effect than the value of $\mathcal{U}_{\mathcal{L}}$ at any η . This will be shown later in the thesis.

CHAPTER VI

CHANGE OF COORDINATES

The results obtained for turbulent flow in this study are compared **with a plot of Spalding's representation of experimental data. Spalding's representation was used because of its convenient form. I t seems to be generally agreed that this curve adequately fits the data, at least within the experimental scatter. The only problem in using** this curve fit is that it is in terms of u^+ and y^+ instead of f^t and γ . It can, however, be shown that (see Appendix A)

$$
m = (y^+) \overline{\left| \frac{2}{C_{\perp}} \right|} \overline{\left| \frac{2}{\sqrt{2} \epsilon x} \right|} \qquad (25)
$$

and

$$
f' = (u^+) \quad \boxed{\frac{C_f}{2}} \tag{2.6}
$$

points is to know the relationship between C_f and Re_x at any particular Re_x. One such relationship that has been shown to be valid for turbulent flow over a flat plate was given by Schultz and Grunow [15]. The **relationship is** Hence, all that is necessary to convert u^+ , y^+ data to f', γ

$$
C_f = 0.370 (log_{10} Re_x)^{-2.58}
$$
 (27)

A comparison of Equation (27) with experimental data Cl6] is shown on Figure 5, which shows the relationship to be in good agreement with experimental data.

Using Equations (25), (26), (27), it is easy to convert Spalding's representation from u^+ , y^+ coordinates to f', \mathcal{V} coordinates for any **value** of Re_x .

CHAPTER VI I

COMPARISON OF SIMILARITY SOLUTION TO EXPERIMENTAL DATA

For flow over a flat plate with zero pressure gradient it has been found experimentally $\begin{bmatrix} 10 \end{bmatrix}$ that it can generally be assumed that **tran sition from laminar to turbulent flow will take place in the range** of Re_x = 3.5xl0⁵ to Re_x = 10⁶. In this analysis it will be assumed that turbulent flow exists at $Re_x = 5 \times 10^5$.

Figure 6 shows flow profiles for various Re_x and the Blasius **profile. All the curves except the Blasius profile are Spalding's u+ , y+ representation transformed to f ' , coordinates. The re la** tionship between the curves with respect to the increasing Re_x is very interesting. It shows that as the Re_x increases, the major part of **the velocity change moves closer to the wall. From this point on a ll** curves will be for a $Re_x = 10^6$.

Figure 7 shows the effect of the inputs shown on Figure 8 on the solution. As may be seen, the slope of the $\mathscr{U}_\ell/\mathscr{U}$ versus ℓ in**creases, and the curve moves up to a certain value and then decreases. As before, the slope at which the maximum occurred, that is the slope at which the solution curve attained its highest value, was found to be about 133.**

Clauser [17], as well as several others, has suggested that the **viscous sublayer of a turbulent boundary layer is about I/ 1000 to**

Fig. 7. -- Input variation effect of Figure 8 on numerical solution.

Fig. 8. — Input variation used to obtain Figure 7.

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N> CD

1/100 of the total thickness of the boundary layer. This suggests that teresting results. In other words, it seems reasonable to think, at effect of such an offset is shown on Figure 10 where Figure 11 shows **the input variation. I t should be pointed out that Figure II is no** longer to scale. As shown, the result is to bend the solution curve in the correct direction. In fact, the influence of a very small offset seems to be very critical. the variation of $\mathscr{U}_\mathscr{L}|_L$ versus λ shown on Figure 9 might yield inleast for a simple model, that $\mathscr{U}_t = O$ in the viscous sublayer. The

Equation (20) suggested that $U_f = o$ up to a value of about **y+ = 5 and Equation (21) suggested that the variation Is linear a fter** $y^+ = 5$. Choosing a value of \mathcal{X} ($y^+ = 5$) as the offset point, and **using a ramp input that would yield the curve with the maximum height,** the results shown in Figure 12 were obtained where Figure 13 illus**trates the input variation. Also plotted on Figure 12 are the curve** fits of Spalding [9] and Diessler [7]. It is very interesting to **notice that the agreement with Curve B is excellent near the wall and near the edge of the boundary layer but that in the middle the agreement is not as good.**

At this point it is clear that the offset has a large influence on the solution curve. Previously it has been shown that the combination of slope and value of $\frac{d\ell}{L}$ also have a large effect. To determine which of the last two variations had the greatest effect, **the solution curves for Figure 14 were found. All three inputs, except** for a small region, have the same value of slope but considerably different values of $\mathscr{U}_{\ell/\ell}$. The solution curves were not plotted because

SO

Fig. 10. ~ Input variation effect of Figure 11 on numerical solution.

UJ

Fig. 11. -- Input variation used to obtain Figure 10. Offset point $(\gamma = \rho_{\rm c}/\rho)$ not to scale.

Fig. 12. -- Input variation effect of Figure 13 on numerical solution.

Figo 13. -- Input variation used to obtain Figure 12. Offset point *(^ - 0■ 0 7* **) not to scale.**

Fig. $14.$ -- Additional Input Variations.

 \sim

they a ll fe ll upon one another. This suggests that the slope has a much greater effect than the value of $\frac{V_f}{V}$.

It was also noted that any of the solution curves obtained from **the Input of Figure 14 fe ll on Curve B of Figure 12 which suggests that the slope has its greatest effect near the offset point.**

Figure 12 shows that the simple model for the variation of $4/7$ versus γ was not completely successful in duplicating either Spalding's or Deissler's representation of the data. Figure 15 shows the same **curves on u+ , y+ coordinates, where the lack of agreement is more obvious.**

To obtain meaningful results it was necessary to use a step size **that was small enough in magnitude so that the behavior near the wall** could be determined. For Re_x = 10^6 the step size used was $\Delta r = 0.02$.

Fig. 15. — Comparison of similarity solution with Spalding's and Deissler's representations.

CHAPTER VIII

DISCUSSION OF RESULTS

The model used to obtain the results reported was based on Equation (20) and Equation (21). As explained in Chapter IV, this is an oversimplification of the actual variation. It seems reasonable to assume that if a more realistic model of the eddy diffusivity **variation had been used that better results would have been obtained. Figure 16 shows the variation that has been proposed by Spalding and the variation used in this thesis. The comparison suggests that the next model to be used should have a general form of the Spalding representation.**

Fig. 16. -- Comparison of eddy diffusivity model used with Spalding's suggested model.

CHAPTER IX

CONCLUSIONS AND RECOMMENDATIONS

The results obtained suggest that it will be possible to obtain a simple model for the variation of the eddy diffusivity which will yield a velocity profile that is in agreement with experimental results. When the working model of the variation is obtained it can be used in **other applications to predict velocity and temperature profiles.**

The similarity solution obtained is not a true similarity solution. A family of curves dependent on Re_x are obtained instead of one universal curve, as is the case in the Blasius similarity solution.

For the diffusivity model tested the two parameters that seemed to have the greatest effect on the solution were the offset point and value of the slope near the offset point. The results also illustrated **that there was the optimal value for the slope of about 133.**

It is recommended that the general type of variation shown in **Figure 16 be used as the next step in obtaining the desired model.**

The numerical method used to obtain the above solutions employs a constant step size procedure. This introduces two problems. The first problem can be easily understood by examination of Figure 6. For a Re_x = 10^6 a step size of at least $\Delta \eta$ = 0.02 must be used to **obtain a part of the linear portion of the curve. However, for Rex** = 10^8 the step size must be reduced to at least $\Delta\eta$ = 0.002. For a

step size of $\Delta r = 0.02$ the time required for execution is about three minutes per solution while for a $\Delta\gamma = 0.002$ the time required is in excess of one hour. Hence, it is suggested that the computer program be rewritten to include a variable step size such that it is very small when $\gamma z o$ and $\Delta \gamma$ increases in size as the value of γ approaches **the edge of the boundary layer. The second problem introduced by the constant step size is that i t is not economical to let the solution seek Its own asymptotic value of f '. Hence the present program requires** convergence to f^t = 1.0 at some specified . A variable step size pro**gram w ill greatly reduce the computational time required per run. With this added f l e x ib i li t y , the numerical integration can be expected to** seek its natural asymptote, based upon initial slope (f¹¹(0)) and diffusivity profile. This will allow the determination of an acceptable $\mathcal{U}_\xi(\eta)$ profile without prior information on the boundary layer thickness.

Appendiv A
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(\begin{array}{c}\n\end{array})
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\

When gives

\n
$$
h = y \left| \frac{\overline{v_{\omega}}}{\overline{v_{\chi}}} \right| = \frac{y}{v} \left| \frac{\overline{r_{\omega}}}{\overline{r_{\omega}}}\right| \left| \frac{\overline{r_{\omega}}}{\overline{r_{\omega}}}\right| \left| \frac{\overline{v_{\omega}}}{\overline{v_{\chi}}}\right|
$$
\n
$$
= y + \left| \frac{1}{\overline{c_{f}}} \right| \left| \frac{\overline{r_{\omega}}}{\overline{r_{\omega}}}\right|
$$
\n
$$
= y + \left| \frac{1}{\overline{c_{f}}} \right| \left| \frac{\overline{r_{\omega}}}{\overline{r_{\omega}}}\right|
$$
\nAlso,

\n
$$
w^{+} = w \left| \frac{\overline{r_{\omega}}}{\overline{r_{\omega}}}\right|
$$
\n
$$
Awd = f' = w / v_{\omega}
$$

THEREFORE

$$
f' = \frac{u}{u_{\infty}} = \left(u \overline{f_{\infty}} \right) \left(\overline{f_{\infty}} \overline{f_{\infty}} \right)
$$

$$
= u^+ \overline{f_{\infty}} \overline{f_{\infty}}
$$

$$
= u^+ \overline{f_{\infty}}
$$

$$
= u^+ \overline{f_{\infty}}
$$

 \overline{a}

$$
APPENDIX
$$

$$
S_{IMILARY} SOLUTION
$$

$$
THE GOVERNING EQUATION S ARE CONTINUITY
$$
\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0
$$
$$

From the following equations:

\n
$$
M \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \frac{\partial}{\partial y} \left[U + L_{z} \right) \frac{\partial u}{\partial y}
$$
\nNow that $X \rightarrow \mathbb{E}$ and $y \rightarrow R$ where

\n
$$
X \rightarrow \mathbb{E}
$$
\n
$$
M \circ U = \frac{A}{X} \circ R
$$
\n
$$
Y = \frac{A}{X} \circ R
$$
\n
$$
Y = \frac{A}{X} \circ R
$$
\n
$$
Y = \frac{X^{n} R}{A}
$$
\nThus, $4S \circ m \in L$:\n
$$
L = \frac{A}{\sqrt{2}} \circ R
$$
\n
$$
V = \frac{X^{n} R}{A}
$$
\n
$$
M \circ W = S \circ M \circ L
$$
\n
$$
= \frac{A}{\sqrt{2}} \circ M
$$
\n
$$
= \frac{A}{\sqrt{2}} \circ M \circ M
$$
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$$
= \frac{A}{\sqrt{2}} \circ M \circ M
$$
\n
$$
= \frac{A}{\sqrt{2}} \circ M \circ M
$$
\n
$$
= \frac{A}{\sqrt{2}} \circ M
$$

$$
\frac{\partial y}{\partial x} = \frac{y}{x^{n}} \times \frac{y}{x^{n+1}}
$$

$$
\frac{\partial y}{\partial x} = \frac{y}{x} \times \frac{y}{x^{n+1}}
$$

$$
\frac{\partial y}{\partial x} = \frac{y}{x} \times \frac{y}{x^{n+1}}
$$

THE INN S FORMING THE CONDINATES GIVES

\n
$$
\frac{1}{4} + \frac{1}{4} = \frac{1}{4} + \frac{1}{
$$

HENCE $\frac{\partial}{\partial y}((U_4+y)\frac{\partial w}{\partial y}) = U \frac{U_{\infty}A^2 f'''}{X^{2n}} + V_4 \frac{U_{\infty}A^2 f'''}{X^{2n}} + \frac{U_{\infty}f''A^2}{X^{2n}} \frac{\partial U_4}{\partial y}$

Which gives the FOLLOWING FOR THE MOMENTUM E quanoN

$$
-\frac{v_{\infty}f'v_{\infty}f''n\eta}{x}+\frac{n v_{\infty}x^{n-1}(nf'-f)}{x^{2n}}\frac{v_{\infty}f''f}{x^{2n}}-\frac{f''}{x^{2n}}=
$$

WHICH REDUCES TO $- \cup_{\infty}^2 n f''f = (D+D_4) \frac{D_0 A^2 f''}{x^{2n-1}} + \frac{D_0 f'' A^2}{x^{2n-1}} + \frac{1}{24}$ LET $n = \frac{1}{2}$ $x^{2n-1} = 1$ WHICH GIVES $-\frac{u_{\infty}^{2}f''f}{2} = (4t+u)U_{\infty}A^{2}f''' + V_{\infty}f''A^{2}\frac{\partial V_{\infty}}{\partial \eta}$

Device by $U_{\infty}^2/2$

$$
f''f = (U+U_4) \frac{2A^2}{U_0} f''' + \frac{2A^2}{U_0} f'' \frac{dU_4}{d\pi}
$$

$$
-f''f = (1 + \frac{U_4}{L})^2 \frac{A^2}{U_0} f''' + 2\frac{A^2}{U_0} f'' \frac{dU_4}{d\pi}
$$

$$
I = \frac{1}{2} \int_{0}^{1} \frac{U_4}{d\pi} f''' + 2\frac{A^2}{U_0} f''' \frac{dU_4}{d\pi}
$$

$$
- \frac{1}{2} \int_{0}^{1} f = (1 + \frac{U_4}{L}) f''' + f'' \frac{dU_4}{d\pi}
$$

END OF PROGRAM

The input to the program includes the $\frac{\partial f}{\partial x}$ γ variation, the **step size, and the definition of the edge of the boundary layer. Equation (15) is solved numerically by a fourth order Runge-Kutta method and the resulting boundary conditions are then checked to see** if they are correct. If so, the computation is completed. If not,

a new guess for the initial conditions is made by the Newton-Raphson **method and the program is repeated until the desired solution is ob**tained. For a full explanation of the Runge-Kutta method used with all subroutines associated with it see Carnahan [12]. And for a full **explanation of the Newton-Raphson method used in the program see** Scarborough and Blake [14], and Middlecoff [13]. A listing of the **computer program follows.**

```
MAIN DECK
     DIMENSION Y ( 6 )» SAVEY( 6 ) , P H I<6 ) , F < 6 ) , Y IN T ( 6 ) . YSAVE< 6 )
     N = 3
     R E A D ( 5 * 1 0 0 ) H » X MAX
100 FORMAT ( 2 F 1 0 . 5 )
  1 READ ( 5 , 8 0 ) E l »E2 * E3
 80 FORMAT ( 3 F 1 0 . 5 )
     WRITE ( 6 * 9 0 ) E l »£2 »E3
 90 FORMAT ( 1 H 1 . 3 F 2 0 . 5 )
     X INTE0*0X = X I NT
     Y(1) = 0.0Y(2)=0.0Y(3) = 2.0Y(4) = 0.0Y(5) = 0.0Y(6) = 0.0DO 5 0 0 K = 1 * 6
500 Y IN T ( K) =Y ( K)
     CALL RUNGE ( H * X , X MA X, 1 F R E Q »Y 9 E 1 * E 2 « E 3 )
     ER R 0R =Y(2)-1.000000
     ERROR=ABS(ERROR)
     IF (ERROR.LT.0.000001) GO TO 700
     CALL N R 11 ( Y * H » Y I N T » Y S A V E » X I N T * X )
     CALL RUNGE ( H * X 9XMAX * I F R E Q . Y , E 1 , E 2 9 E 3 )
     ERROR=Y(2 )-1 .0 0 0 0 0 0
     ERROR=ABS<ERROR)
     IF (ERROR.LT.0.00001) GO TO 700
     CALL NR12 ( Y , H 9 YINT,YSAVE,PHINEWsX IN T.X )
     CALL RUNGE ( H , X , X M A X , I FREQ * Y . E 1 , E 2 . E 3 )
     ERROR=Y( 2 ) - l .000000
     ERROR=ABS(ERROR)
     IF (ERROR.LT.0.00001) GO TO 700
600 CONTINUE
     CALL NR21 (Y,H1, YINT, YSAVE, PHINEW, PHIOLD, XINT, X)
     C A L L RUNGE ( H , X , X M A X s I F R E Q . Y , E 1 * E 2 . E 3 )
     ERROR=Y( 2 ) - l .000000
     ERROR=ABS(ERROR)
     IF (ERROR.LT.0.00001) GO TO 700
     CALL N R 2 2 ( Y , H I , Y I NT * PH I O L D , X I N T . X )
     CALL RUNGE ( H 9X , XMAX * I F R E Q «Y 9E1 . E2 9 E 3 )
     ERROR=Y(2 ) - l .000000
     ERROR=ABS(ERROR)
     IF (ERRCR.LT.0.000001) GO TO 700
     GO TO 6 0 0
700 CONTINUE
     GO TO 1
  2 CONTINUE
     STOP
     END
     SUBROUTINE RUNGE ( H 9X * X M A X , I F R E Q 9 Y. £ 1 • E 2 *E 3 )
     DIMENSION Y(6), SAVEY(6), PHI(6), F(6)
     N = 3
     IC=G
```

```
JC = 0KC = 0LC = 0MC = 01 CONTINUE
  CALL FUNC (X, Y, F, E1, E2, E3)CALL PASS2 (Y.SAVEY, PHI, F.N.H.X)
  CALL FUNC (X, Y, F, E1, E2, E3)CALL PASS3 (Y.SAVEY.PHI.F.N.H)
  CALL FUNC (X, Y, F, E1, E2, E3)CALL PASS4 (Y, SAVEY, PHI, F, N, H, X)
  CALL FUNC (XoY, F.E1, E2, E3)
  CALL PASS5 (Y, SAVEY, PHI, F, N, H)
  CALL RECORD (IC, JC, KC, LC, MC, X, Y(1), Y(2), Y(3))
  CONTINUE
  IF (X.GE.XMAX) GO TO 4
  GO TO 1
4 CONTINUE
  RETURN
  END
  SUBROUTINE FUNC (X,Y,F,E1,E2,E3)
  DIMENSION Y(6), F(6)
  CALL NU (X.E1.E2.E3.G)
  CALL PARNU (X.E1.E2.E3.P)
  F(1)=Y(2)F(2)=Y(3)F(3) = -Y(3) * P/G - (Y(1) * Y(3)) / ((2.0) * G)F(4)=Y(4)F(5) = Y(5)F(6) = Y(6)RETURN
  END
  SUBROUTINE PASS2 (Y.SAVEY.PHI.F.N.H.X)
  DIMENSION Y(N), SAVEY(N), PHI(N), F(N)
  DO 1 J=1. N1 SAVEY(J)=Y(J)
  DO 2 J=1,N
2 PHI(J)=F(J)DO 3 J=1. N3 Y(J) = SAVEY(J) + 0.5*H*F(J)X = X + 0.5 + HRETURN
  END
  SUBROUTINE PASS3 (Y.SAVEY.PHI.F.N.H)
  DIMENSION Y(N), SAVEY(N), PHI(N), F(N)
  DO 1 J=1 N1 PHI(J)=PHI(J)+2.0*F(J)
  DO 2 J=1, N2 Y(J) = SAVEY(J) + 0.55*H*F(J)RETURN
  END.
  SUBROUTINE PASS4 (Y.SAVEY, PHI, F.N.H.X)
  DIMENSION Y(N), SAVEY(N), PHI(N), F(N)
  DO 1 J=1 N
```

```
1 PHI(J)=PHI(J)+2.0 *F(J)
  DO 2 J=1.N
2 Y(J) = SAVEY(J) + H*F(J)X = X + 0.5 + HRETURN
  END
  SUBROUTINE PASSS (Y.SAVEY.PHI.F.N.H)
  DIMENSION Y(N), SAVEY(N), PHI(N), F(N)
  DO 1 J=1 N1 PHI(J)=PHI(J)+F(J)
  DO 2 J=1 sN2 Y(J) = SAVEY(J) + (PHI(J)) + H/6.0RETURN
  END
  SUBROUTINE NU (X.E1,E2.E3.G)
  IF (X_0GT_0E1) GO TO 1
  G = 0 of 0
  GO TO 2
1 IF (X.GT.E3) GO TO 3
  G = (E3/(E2-E1)) - E1 *x+1.0
 GO TO 2
3 G=E32 CONTINUE
  RETURN
  END
  SUBROUTINE PARNU (X,E1,E2,E3,P)
  IF (X.LT.E1) GO TO 1
  IF (X.GT.E3) GO TO 1
 P = E3 / (E2 - E1)GO TO 2
1 P = 0.02 CONTINUE
 RETURN
  END
  SUBROUTINE RECORD (IC, JC, KC, LC, MC, X, A, B, C)
  IC=IC+1IF(IC.LT.6) GO TO 1
  IF (IC.LT.51) GO TO 2
  IF(IC.LT.501) GO TO 3
 IF(IC.LT.5001) GO TO 4
 GO TO 5
2 JC=JC+1
 IF (JC.EG.5) GO TO 6
  GO TO 100
6 JC=0GO TO 1
3 KCEKCA1IF(KC.EQ.50) GO TO 7
 GO TO 100
7 KC = 0GO TO I
4 LCELC+1IF(LC.EG.500) GO TO 8
  GO TO 100
```

```
8 LC = 0
    GO TO 1
  5 MC=MC+1
     I F { M C o E O . 5 0 0 0 ) GO TO 9
    GO TO 1 0 0
  9 MC = 0
     GO TO 1
  1 WRITE (6.402) X,A,B,C
402 FORMAT ( 1 H 0 . 4 F 1 0 . 5 )
100 CONTINUE
     RETURN
     END
     SUBROUTINE NR11(Y.H.YINT, YSAVE.XINT, X)
     DIMENSION Y(6), YINT(6), YSAVE(6)
     DO I K = 1 , 6
  1 Y S A V E ( K ) = Y ( K)
    DO 2 K = 1 * 6
  2 Y ( K ) = Y I N T ( K )
     Y (3 )= Y IN T (3 )+ H
     X = X \cdot I \cdot NRETURN
     END
     SUBROUTINE NR12 (Y,H, YINT, YSAVE, PHINEW, XINT, X)
     DIMENSION Y(6), YINT(6), YSAVE(6)
     PH I GLD=YSAVE (2)-1.000000
     PHINEW=Y( 2 ) - l .000000
     D P H I = ( P H I NEW—P H I O L D ) / H
     D Y = —P H I O L D / D P H I
     YINTC3)=YINT(3)+DY
     DO 1 K = 1 « 6
  1 Y ( K } = Y I N T ( K >
     X = X I NT
     RETURN
     END
     SUBROUTINE NR21 (Y, H1, YINT, YSAVE, PHINEW, PHIOLD, XINT, X)
     DIMENSION Y ( 6 ) , Y IN T ( 6 ) , YSAVE<6)
     DO I K = l , 6
  1 Y S A V E ( K ) = Y ( K )
     PHICLD=YSAVE(2)-1 .0 0 0 0 0 0
     HI=-PHIOLD/PHINEW
     DO 2 K = 1 , 6
  2 Y ( K ) = Y I N T < K )
     Y (3)=Y IN T(3)+H 1
     X=XINT
     RETURN
     END
     SUBROUTINE NR22 (Y,H1, YINT, PHIOLD, XINT, X)
     DIMENSION Y(6), YINT(6)
     PHINE W = Y ( 2 ) " 1 . 0 0 0 0 0 0
     D P H I = (P H I N E W - P H I OL D ) / H 1
     D Y=-PHICLD /C PHI 
    YINT(3) = YINT(3) + DYDC 1 K = 1.661 Y(K) = YINTK(K)X=XINT
     RETURN
     END
```
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A SIMILARITY MODEL FOR FLOW IN

A TURBULENT BOUNDARY LAYER

An Abstract of a Thesis

Presented to

The Department of Mechanical Engineering Science

Brigham Young University

In Partial Fulfillment

of the Requirements for the Degree

Master of Science

by

E. Clark Lemmon

May 1968

ABSTRACT

The purpose of this thesis was to reduce the governing equation for flow over a flat plate which is a partial differential equation to an ordinary differential equation by a similarity solution, and **then numerically solve the obtained transformed governing equation. The solution of this equation was found to be dependent on the model**ing of the variation of the eddy diffusivity across the boundary layer. **The results obtained by numerically solving the transformed governing equation were compared with experimental data. The predicted profile** compared very well with the experimental profile near the wall and **in the turbulent core. However, the agreement in the buffer region** was poor. The results obtained implied that a better fit could be obtained if a more complex model of eddy diffusivity as a function of **position were used.**

APPROVED: