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Accuracy of a Simplified Analysis Model

for Modern Skyscrapers

Jacob S. Lee

A thesis submitted to the faculty of Brigham Young University in partial fulfillment of the requirements for the degree of

Master of Science

Richard J. Balling, Chair Paul W. Richards Fernando S. Fonseca

Department of Civil and Environmental Engineering

Brigham Young University

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ABSTRACT

Accuracy of a Simplified Analysis Model for Modern Skyscrapers

Jacob S. Lee Department of Civil and Environmental Engineering, BYU Master of Science

A new simplified skyscraper analysis model (SSAM) was developed and implemented in a spreadsheet to be used for preliminary skyscraper design and teaching purposes. The SSAM predicts linear and nonlinear response to gravity, wind, and seismic loading of "modern" skyscrapers which involve a core, megacolumns, outrigger trusses, belt trusses, and diagonals. The SSAM may be classified as a discrete method that constructs a reduced system stiffness matrix involving selected degrees of freedom (DOF's). The steps in the SSAM consist of: 1) determination of megacolumn areas, 2) construction of stiffness matrix, 3) calculation of lateral forces and displacements, and 4) calculation of stresses. Seven configurations of a generic skyscraper were used to compare the accuracy of the SSAM against a space frame finite element model. The SSAM was able to predict the existence of points of contraflexure in the deflected shape which are known to exist in modern skyscrapers. The accuracy of the SSAM was found to be very good for displacements (translations and rotations), and reasonably good for stress in configurations that exclude diagonals. The speed of execution, data preparation, data extraction, and optimization were found to be much faster with the SSAM than with general space frame finite element programs.

Keywords: Jacob S. Lee, skyscraper, structural analysis, optimization, preliminary design

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1 INTRODUCTION

A new simplified skyscraper analysis model (SSAM) is described herein. The model can be implemented on a spreadsheet. The accuracy of the SSAM has been compared to results from sophisticated space frame and finite element analysis models. Those results will be presented and discussed in this thesis. The SSAM is intended to be used in the preliminary design phase of skyscrapers where a fast, reasonably-accurate model is needed in design iterations. The model can also be used in an educational setting where senior/graduate students are introduced to the behavior and design of skyscrapers.

The SSAM predicts the linear and nonlinear response of "modern" skyscrapers subject to gravity, wind, and seismic loads. Modern skyscrapers are defined herein to be third generation skyscrapers. First generation skyscrapers such as the Empire State Building in New York City consisted of steel braced and unbraced frames. Such skyscrapers had many interior columns obstructing the space. Fazlur Khan is regarded as the father of second generation skyscrapers characterized as framed tubes or tube-in-tube skyscrapers such as the former World Trade Center in New York City. These skyscrapers possess an interior core tube that encloses elevator shafts, and a perimeter tube with many columns. There are no columns in between the core tube and perimeter tube, thus providing unobstructed space. By moving the columns to the perimeter, a system with maximum moment of inertia is created to resist lateral loads. The third generation of skyscrapers coalesces perimeter columns into a few megacolumns to provide an unobstructed view to the outside. Such megacolumns are usually composite members made from steel sections encased in high-stiffness, high-strength concrete. To provide the necessary moment of inertia to resist lateral loads, the megacolumns and core are periodically connected with outrigger trusses, belt trusses, and diagonals. The SSAM is used to analyze core-megacolumn-outriggerbelt-diagonal systems. Some examples of core-megacolumn-outrigger-belt-diagonal skyscrapers will now be given.

The 88-story Jin Mao Tower (see [Figure 1-1\)](#page-12-0), completed in 1999 in Shanghai, China, consists of an octagonal concrete core and eight composite steel/concrete megacolumns. Steel outrigger trusses connect the core and megacolumns at stories 25, 54, and 86 (see [Figure 1-2](#page-13-0) and [Figure 1-3\)](#page-13-1). A belt truss is located at the top of the tower, which is typically called a cap truss.

Figure 1-1: Jin Mao Tower – Shanghai, China © SOM

Figure 1-2: Jin Mao Tower - structural system elevation view (Choi et al. 2012)

Figure 1-3: Jin Mao Tower - typical framing plan (Choi et al. 2012)

Hong Kong's 2 International Finance Centre is an excellent example of a core-mega column-outrigger-belt system (see [Figure 1-4\)](#page-14-0). This 88-story skyscraper completed in 2004 has a core with eight megacolumns shown in red in [Figure 1-5.](#page-15-0) Outrigger and belt trusses are located at stories 33, 55, and 67. The 24m spacing between megacolumns provides unobstructed view to the outside for offices on the perimeter. A typical outrigger-belt truss configuration is shown in [Figure 1-6.](#page-15-1) Belt trusses transfer loads from secondary corner columns to the megacolumns (Choi et al. 2012).

Figure 1-4: Two International Finance Centre (IFC2) - Hong Kong, China © Antony Wood/CTBUH

Figure 1-5: IFC2 - typical floor plan ©Arup

Figure 1-6: IFC2 - typical layout of outrigger and belt trusses (Emporis.com)

The Shanghai Tower is a 126-story 632m tall skyscraper scheduled for completion in 2014 (see [Figure 1-7\)](#page-16-0). Even though the exterior facade has a twisting irregular shape that significantly reduces wind load, the core is square and the composite megacolumns are arranged in a regular circular pattern whose diameter decreases with height (see [Figure 1-8\)](#page-17-0). The outrigger trusses and circular belt trusses occur at nine levels separated by 12 to 15 stories (Mass et al. 2010). Radial trusses extend outward from the megacolumns to support the irregular twisting facade. The space between the perimeter megacolumns and the exterior facade will be used as atria open to the public.

Figure 1-7: Shanghai Tower © Gensler

Figure 1-8: Shanghai Tower - isometric of core, megacolumns, outrigger, and belt trusses © Thornton Tomasetti

The Guangzhou International Finance Center is a 440m high skyscraper with 73 stories of office space and 30 stories of hotel space (see [Figure 1-9\)](#page-18-0). The structure consists of a central core and perimeter diagonals arranged in what is known as a diagrid system. There are no vertical megacolumns, outriggers, or belt trusses in the diagrid system. The diagonals are concrete-filled steel tubes.

Figure 1-9: Guangzhou International Finance Center © Christian Richters

The Shanghai World Financial Center includes core, megacolumns, outrigger trusses, belt trusses, and megadiagonals (see Figures 1-10, 1-11, and 1-12). This mixed lateral load-resisting system was motivated by the need to reduce weight in the structure (Katz et al. 2008). Note that two of the megacolumns split part way up so that there are four megacolumns at the base and six megacolumns after the split.

Figure 1-10: Shanghai World Financial Center (WFC) © Kohn Pederson Fox Associates/CTBUH

Figure 1-11: Shanghai WFC structural system - core, megacolumns, outrigger truss, belt truss, and megadiagonal (Katz et al. 2008)

Figure 1-12: Shanghai WFC structural system elevation views (http://www4.kke.co.jp)

The generic skyscraper in Figures 1-13 and 1-14 will be used throughout this thesis for analysis comparison. The concrete core is shown in yellow, the 16 concrete megacolumns are shown in red, the two-member steel outrigger trusses are shown in green, the 8-member steel belt trusses are shown in blue, and the steel diagonals are shown in black. Multiple configurations of this generic skyscraper will be considered in the thesis:

- 1) core+megacolumns
- 2) core+megacolumns+outriggers
- 3) core+megacolumns+belts
- 4) core+megacolumns+diagonals
- 5) core+megacolumns+outriggers+belts
- 6) core+megacolumns+outriggers+belts+diagonals

The remainder of the thesis is divided into five chapters. Chapter 2 reviews the literature on related approximate analysis methods. Chapter 3 describes the SSAM. Chapter 4 describes the sophisticated linear space frame and nonlinear ADINA models. Chapter 5 presents results from the SSAM, the space frame model, and the ADINA model for the six configurations of the generic skyscraper. Chapter 6 submits conclusions based on the results. The appendix includes a copy of the spreadsheet implementation of the SSAM for the generic skyscraper.

Figure 1-13: Generic skyscraper elevation and plan views

Figure 1-14: Generic skyscraper - outrigger truss, belt truss, and diagonal systems

2 LITERATURE REVIEW

The literature on approximate analysis methods for tall buildings can be subdivided into continuum methods and discrete methods. Continuum methods model tall buildings as vertical cantilevers, and approximate displacements as continuous functions of vertical position using flexure/shear beam theory. Discrete methods construct stiffness or flexibility matrices for the system. The finite element method is an example of a discrete method. Some of the approximate discrete methods surveyed enforce compatibility conditions at the discrete locations of outrigger and belt trusses. Other approximate discrete methods construct reduced system stiffness matrices through the use of substructuring or super-elements. The SSAM is a discrete method that constructs a reduced system stiffness matrix.

2.1 **Continuum Methods for Low/Medium-Rise Buildings**

Bozdogan and Ozturk (2009) proposed an approximate method based on the continuum method idealizing low-rise wall-frame and tube-in-tube structures of 11 stories and 15 stories, respectively, as sandwich beams. Their sandwich beam consists of two vertical Timoshenko cantilever beams attached by horizontal connecting beams in parallel. One beam consists of the sum of the flexural and shear rigidities of shear walls and columns. The second beam consists of the sum of shear rigidities of frames and connecting beams. By solving a set of differential equations for the shear force equilibrium in both beams, continuous equations for displacement and rotation with respect to vertical position are obtained. Bozdogan (2009) also applied this method to dynamic analyses on the same example wall-frame structure.

Potzta and Kollar (2003) discussed the development of replacement beams as sandwich beams in simplifying the analysis of low-rise buildings with combinations of shear walls, coupled shear walls, frames, and trusses. Again, the sandwich beam applies the continuum method by representing the system as a Timoshenko beam that is supported laterally by a beam with bending stiffness. Each lateral load-resisting system is replaced by a continuous cantilever beam with connecting beams between them. The strain energy of the sandwich beam is presented as the strain energies of a Timoshenko beam and of a beam with bending deformation only. An example 7-story building with two coupled shear walls and a frame is used to demonstrate this method. This same procedure is used by Kaviani et al. (2008) who extends the method to structures of variable cross-section.

An approximate hand calculated method for asymmetric wall-frame structures was proposed by Rutenberg and Heidebrecht (1975). Lateral loads from wind or earthquakes produce both lateral deflections and twisting in asymmetric configurations. The flexural walls and frames are modeled as vertical flexural and shear cantilevers where torsional behavior is treated in addition. Coupled torsion-bending differential equations governing the static equilibrium of the structure are solved to obtain continuous functions for story displacements and rotations with height. Their method is applied to a 16-story wall-frame structure.

A new concept to increase the lateral stiffness of wall-frame tall building structures by stiffening a story of the frame system was proposed by Nollet and Smith (1997). The wall-frame structure is modeled using the continuum theory by representing the system as two cantilever beams in parallel by connecting beams. The shear wall, with a modified flexural rigidity, is

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connected to and constrained to have the same deflected shape as the frame by axially rigid connecting links. The rigid links that provide horizontal rigidity represent a continuum between the wall and frame. A continuous displacement function with respect to height was then obtained by modifying and solving the differential equation for bending moment of a cantilever with the added stiffness parameter. An example 20-story wall-frame structure with shear walls and four moment resisting frames was analyzed to verify the method.

Abergel and Smith (1983) developed an approximate method of analysis for non-twisting medium-rise structures composed of shear walls, cores, and identical coupled walls. An alternative to previous approximations is made based on the differential equations of deflection of a cantilever beam. By replacing the coupled wall with a comparable structure where the connecting beams are treated as a continuous medium with equivalent bending and shear properties, a differential equation relating the horizontal loading is derived. The differential equation relating horizontal loading was developed from two previously derived equations for shear walls. A 20-story building with four coupled walls, two shear walls, and a core is used as an example.

Heidebrecht and Smith (1973) present a simple hand method for the static and dynamic analysis of uniform low to medium-rise structures consisting of interacting shear walls and frames. The mathematical model consists of a combination of flexural and shear vertical cantilever beams deforming either in shear or bending and is very similar to other methods where the governing differential equations for flexural and shear beams subject to lateral load are solved. Differently from other approximations, their method has application to nonuniform shear wall-frame structures. The method is applied to a 12-story wall-frame building. Similarly, Hoenderkamp et al. (1984) and Toutanji (1997) use variations of this method by modeling medium-rise buildings with coupled walls and shear walls with frames as flexural and shear vertical cantilevers.

2.2 **Continuum Method for Framed Tubes**

Kwan (1994) developed a simple hand calculation method for the analysis of framed tube structures accounting for shear lag effects. This method assumes that framed tube structures can primarily behave like cantilevered box beams. The framed tube structure is modeled as two web panels and two flange panels. It is assumed that there is uniform stiffness throughout the structure and the differential equation of moment equilibrium in a cantilever beam was solved to obtain continuous functions of displacement and rotation with respect to height. Two examples of a 40-story high-rise and a 15-story low-rise composed of framed tubes are presented. Rahgozar and Sharifi (2009) applied a variation of Kwan's (1994) method on 30, 40, and 50 story framed tube buildings with shear cores and belt trusses.

Takabatake (2012) refers to the one-dimensional rod theory as a method in the preliminary design stage that is most suitable when replacing a high rise structure as a continuous member. This extended rod theory includes the Timoshenko beam theory effects along with longitudinal deformation and shear-lag effects by replacing the structure with an equivalent stiffness distribution. The theory is extended to two-dimensional extended rod theory by considering structural components with different stiffness and mass distributions that are continuously connected. They are modeled as several parallel beams. Governing equations are solved for shear and flexure in a cantilever beam where a continuous displacement function is obtained that satisfies continuity conditions between the parallel beams. A 30-story framed tube is used as an example. Kobayashi et al. (1995) applied Takabatake's (2012) method to a 30 story tube-in-tube example building.

2.3 **Inherent Problems with Continuum Methods**

Note that none of the continuum models surveyed thus far have been applied to buildings with outriggers. This is because continuum models based on cantilever beam theory cannot reproduce the points of contraflexure exhibited in the deflected shapes of tall buildings with outriggers as shown in Figure 2-1 taken from Choi et al. (2012). The bending moment in a cantilever beam loaded laterally in one direction does not change sign, and therefore, points of contraflexure do not exist. Many studies have recognized the possibility that points of contraflexure exist in tall buildings with outriggers.

Figure 2-1: One Liberty Place deflected shape © Thornton Tomasetti

Choi et al. (2012) explain the outrigger-core coupling as follows: "When laterally loaded the outriggers resist core rotation by using perimeter columns to push and pull in opposition, introducing a change in slope of the vertical deflection curve, a portion of the core overturning moment is transferred to the outriggers and, in turn, tension in windward columns and compression in leeward columns... Analysis and design of a complete core-and-outrigger system is not that simple: distribution of forces between the core and the outrigger system depends on the relative stiffness of each element. One cannot arbitrarily assign overturning forces to the core and the outrigger columns. However, it is certain that bringing perimeter structural elements together with the core as one lateral load resisting system will reduce core overturning moment." Kowalczyk et al. (1995) explain the function of outriggers with the following: "…outriggers serve to reduce the overturning moment in the core that would otherwise act as a pure cantilever, and to transfer the reduced moment to columns outside the core by way of a tension-compression couple, which takes advantage of the increased moment arm between these columns." Stafford Smith and Coull (1991) state that, "the outrigger-braced structure, with at most four outriggers, is not strictly amenable to a continuum analysis and has to be considered in its discrete arrangement."

[Figure 2-2](#page-29-0) through [Figure 2-6](#page-30-1) were taken from a study by (Taranath 2005) about the relationship between outrigger location and the existence of points of contraflexure. In Figure 2- 4, the tie-down action of the cap truss generates a restoring couple at the building top, resulting in a point of contraflexure in its deflection curve. [Figure 2-3,](#page-29-1) [Figure 2-4,](#page-29-2) [Figure 2-5,](#page-30-0) and [Figure](#page-30-1) [2-6](#page-30-1) show deflected shape and bending moment diagrams for different vertical locations of a single outrigger truss.

Figure 2-2: Contraflexure in core created by cap truss (Taranath 2005)

Figure 2-3: Behavior of system with outrigger located at z = L (Taranath 2005)

Figure 2-4: Behavior of system with outrigger located at z = 0.75L (Taranath 2005)

Figure 2-5: Behavior of system with outrigger located at z = 0.5L (Taranath 2005)

Figure 2-6: Behavior of system with outrigger located at z = 0.25L (Taranath 2005)

2.4 **Discrete Outrigger Methods**

Hoenderkamp and Bakker (2003) wrote about analyzing high-rise braced frames with outriggers. Three stiffness parameters are considered which represent the frame wall, outriggers and columns at the single story where the outrigger is present. Two degrees of freedom for the braced frame are taken as a rotation and a translation about the vertical axis. The rotation equation assumes the rotation of a free cantilever with respect to height subject to a uniformly distributed load. A third degree of freedom comes from the rotation of the outrigger that produces a restraining moment in the frame. The total rotation of the braced frame at the outrigger level becomes a product of the cantilever rotation reduced by the moment rotation created by the outriggers. The horizontal deflection at the top of the structure is then determined by a compatibility equation for the rotation at the interface of the braced frame and outrigger. The method was tested on three braced-frame-outrigger high-rise buildings of 57.5m, 72m, and 93.6m in height. Hoenderkamp (2008) applies the method to high-rises with outriggers at two levels, and Hoenderkamp (2004) applies the method to high-rises with outriggers and flexible foundations.

Taranath (2005) conceptualizes outriggers as restraining springs located on the cantilever. The ratio of the outrigger moment to the outrigger stiffness is equated to the rotation of a uniformly loaded cantilever beam with constant stiffness. The resulting deflection is obtained by superposing the deflection of the cantilever and the moment induced by the spring. Rahgozar et al. (2010) apply a similar method to 45-story and 55-story buildings composed of framed tube, shear core, belt truss, and an outrigger where the belt truss, outrigger, and shear core are considered as a bending spring with constant rotational stiffness acting as a concentrated moment where the belt truss and outrigger are located.

Stafford Smith and Coull (1991) created compatibility equations for each outrigger level to equate the rotation of the core to the rotation of the outrigger. The rotation of the core is expressed in terms of its bending deformation and that of the outrigger in terms of the axial deformations of the columns and the bending of the outrigger. The top drift of the structure may then be determined from the resulting bending moment diagram for the core by using the moment-area method. Furthermore, this same method of analysis can be applied to structures with more than two outriggers by expressing them as restraining moments in the equation of horizontal deflection for a cantilever beam. These multiple restraining moments can be expressed in matrix form for simultaneous solution of multiple equations. This method of compatibility was published earlier by Smith and Salim (1981) which was then improved upon by Stafford Smith and Coull (1991).

Wu and Li (2003) take this compatibility approach as well for multi-outrigger-braced tall buildings with an additional application to their dynamic characteristics. Rutenberg (1987) made a parametric study for this method investigating the effect of outrigger location, ratio of perimeter column to core stiffness, and stiffness variation along the height on the horizontal displacement at roof level.

2.5 **Discrete Substructuring Methods**

Lin et al. (1994) presented an approximate approach called the finite story method (FSM) to analyze the displacement and natural frequencies of tall framed tube buildings. The method reduces the system stiffness matrix to involve horizontal displacements and rotations about the vertical axis. It is based on the displacements of two-story substructures to approximate shear, bending, and torsion components of global deformations. A 30-story framed tube building is used as an example.

 De Llera and Chopra (1995) developed a new simplified model for analysis and design of multistory buildings. The model is based on a single super-element per building story that is capable of representing the elastic and inelastic properties of the story. This is done by matching the stiffness matrices and ultimate yield surface of the story with that of the element. The analysis consists of multistory buildings with rigid diaphragms where the masses are lumped together and where lateral resistance is provided by resisting planes in both horizontal directions composed of elasto-plastic elements. A single fictitious structural super-element per story has three degrees of freedom, two horizontal translations and the rotation of the floor connected by

the element, where a reduced stiffness matrix is created. This method was applied to a small building with 4 stories.

3 SIMPLIFIED SKYSCRAPER ANALYSIS MODEL

The steps of the simplified skyscraper analysis model (SSAM) consist of: 1) determination of megacolumn areas, 2) construction of stiffness matrix, 3) calculation of lateral forces and displacements, and 4) calculation of stresses. The SSAM was implemented on a spreadsheet. The spreadsheet can be used for rapid trial-and-error optimization of the skyscraper. Such usage will be addressed at the end of this chapter.

3.1 **Determination of Megacolumn Areas**

The SSAM subdivides the skyscraper vertically into **intervals**. Outrigger and belt trusses are located at interval boundaries. It will be assumed that the cross-sectional areas of the core, megacolumns, and diagonals remain constant in each interval. It will also be assumed that the cross-sectional areas of composite steel/concrete cores and megacolumns are the cross-sectional areas of the transformed all-concrete sections where steel area has been multiplied by the ratio of steel elastic modulus to concrete elastic modulus. Define the following terms:

 n_i = number of stories in interval i (20 for generic skyscraper) h_i = vertical height of interval i (80m for generic skyscraper) A_i^{core} = cross-sectional area of the core in interval i A_i^{colj} = cross-sectional area of megacolumn j in interval i A_i^{diag} = cross-sectional area of diagonal j in interval i V_i^{diag} = volume of all diagonal members in interval i S_i^{diag} = sine of angle from horizontal for diagonals in interval i $L_i^{\text{diag}} =$ length of diagonals in interval i

 k_i^{diag} = vertical stiffness of all diagonals in interval i F_i^{core} = axial force in core at base of interval i excluding interval i self weight F_i^{colj} = axial force in megacolumn j at base of interval i excluding interval i self weight γ = concrete unit weight (core and megacolumns) ε_i = axial strain at bottom of interval i $E =$ concrete modulus of elasticity (core and megacolumns) E^s = steel modulus of elasticity (diagonals, outriggers, belts) A_T^{core} = core tributary area A_T^{colj} = tributary area for megacolumn j P_T^{colj} = tributary perimeter for megacolumn j L^{dead} = floor dead load per area L^{live} = floor live load per area $L^{clad} = cladding load per area$ T_i^{core} = outrigger truss weight in interval i supported by the core T_i^{colj} = outrigger-belt-diagonal truss weight in interval i supported by megacolumn j

Assume that intervals are numbered with i=1 being the top interval and increasing downward. Assume that $h_0 = A_0^{\text{core}} = A_0^{\text{colj}} = 0$ in the following formulas. Assume that the weight of any pinnacle or cap on top of the skyscraper is distributed appropriately among the core and megacolumns to get values for F_0^{core} and F_0^{coll} . The core and megacolumn axial forces excluding interval self weight are calculated from Equations 3-1 and 3-2:

$$
F_i^{\text{core}} = F_{i-1}^{\text{core}} + \gamma h_{i-1} A_{i-1}^{\text{core}} + n_i A_T^{\text{core}} (L^{\text{dead}} + L^{\text{live}}) + T_i^{\text{core}} \tag{3-1}
$$

$$
F_i^{colj} = F_{i-1}^{colj} + \gamma h_{i-1} A_{i-1}^{colj} + n_i A_T^{colj} (L^{dead} + L^{live}) + h_i P_T^{colj} L^{clad} + T_i^{colj}
$$
\n
$$
\tag{3-2}
$$

Given the cross-sectional area of the core, the cross-sectional areas of the megacolumns are determined from the principle that **the axial strain in the megacolumns must be the same as the axial strain in the core under gravity loads** in order to prevent unacceptably large differential vertical displacements from accumulating in the upper floors of the skyscraper. If there are no diagonals, then at the base of interval i, the axial strain in the core is equated to the axial strain in each megacolumn j in Equation 3-3,
$$
\varepsilon_{i} = \frac{F_{i}^{\text{core}} + \gamma h_{i} A_{i}^{\text{core}}}{EA_{i}^{\text{core}}} = \frac{F_{i}^{\text{colj}} + \gamma h_{i} A_{i}^{\text{colj}}}{EA_{i}^{\text{colj}}}
$$
(3-3)

This can be solved for the area of megacolumn j in interval i in Equation 3-4:

$$
A_i^{\text{colj}} = A_i^{\text{core}} \frac{F_i^{\text{colj}}}{F_i^{\text{core}}}
$$
 (3-4)

The above formula must be modified if diagonals are present because diagonals contribute to the support of gravity loads. The vertical stiffness of all diagonals in interval i is calculated in Equation 3-5:

$$
k_i^{\text{diag}} = \frac{E^s \left(\sum_j A_i^{\text{diag}}\right) \left(S_i^{\text{diag}}\right)^2}{L_i^{\text{diag}}} = \frac{E^s \left(\sum_j A_i^{\text{diag}}\right) \left(S_i^{\text{diag}}\right)^3}{h_i}
$$
(3-5)

The sum of diagonal areas in interval i can be calculated from the volume of diagonal members in interval i from Equation 3-6:

$$
\sum_{j} A_i^{\text{diag}} = V_i^{\text{diag}} \frac{S_i^{\text{diag}}}{h_i}
$$
 (3-6)

At the base of interval i, the axial strain in the core is equated to the axial strain in all the megacolumns and diagonals together by Equation 3-7:

$$
\varepsilon_{i} = \frac{F_{i}^{\text{core}} + \gamma h_{i} A_{i}^{\text{core}}}{EA_{i}^{\text{core}}} = \frac{\left(\sum_{j} F_{i}^{\text{colij}}\right) + \gamma h_{i} \left(\sum_{j} A_{i}^{\text{colj}}\right)}{E \left(\sum_{j} A_{i}^{\text{colj}}\right) + E^{s} \left(\sum_{j} A_{i}^{\text{diag}}\right) \left(S_{i}^{\text{diag}}\right)^{3}}
$$
(3-7)

This can be solved for the sum of megacolumn areas in interval i in Equation 3-8:

$$
\sum_{j} A_i^{\text{colj}} = A_i^{\text{core}} \frac{\sum_{j} F_i^{\text{colj}}}{F_i^{\text{core}}} - \left(\sum_{j} A_i^{\text{diag}}\right) \left(S_i^{\text{diag}}\right)^3 \frac{E^s}{E} \left(1 + \frac{\gamma h_i A_i^{\text{core}}}{F_i^{\text{core}}}\right)
$$
\n
$$
= A_i^{\text{core}} \frac{\sum_{j} F_i^{\text{colj}}}{F_i^{\text{core}}} - \frac{V_i^{\text{diag}}}{h_i} \left(S_i^{\text{diag}}\right)^4 \frac{E^s}{E} \left(1 + \frac{\gamma h_i A_i^{\text{core}}}{F_i^{\text{core}}}\right)
$$
\n(3-8)

The area of megacolumn *j* in interval *i* is solved for in Equation 3-9:

i

h

$$
A_i^{colj} = \frac{F_i^{colj}}{\sum_j F_i^{colj}} \sum_j A_i^{colj}
$$

=
$$
A_i^{core} \frac{F_i^{colj}}{F_i^{core}} - \frac{V_i^{diag}}{h} (S_i^{diag})^4 \frac{F_i^{colj}}{\sum_j F_i^{colj}} \frac{E^s}{F} \left(1 + \frac{\gamma h_i A_i^{core}}{F_i^{core}} \right)
$$
 (3-9)

 \setminus

 $\sum F_i^{\text{colj}} E\begin{bmatrix} 1 & 1 \end{bmatrix} F_i^{\text{core}}$

E

 $\bigg)$

The above formula is used in the spreadsheet. Note that if the area of the diagonals is big enough, the megacolumn areas may drop to zero resulting in a diagrid skyscraper.

colj i

F

j

 $\mathbf{F}_i^{\text{core}}$ \mathbf{h}_i \mathbf{v}_i \mathbf{v}_i $\mathbf{F}_i^{\text{colj}}$ \mathbf{E} \mathbf{F}_i

3.2 **Construction of the Stiffness Matrix**

core i

F

Lateral load analysis in the SSAM is performed by constructing a stiffness matrix in the spreadsheet for the skyscraper. The degrees of freedom (DOF's) consist of the horizontal displacement of the core at the top of each interval, the rotation of the core at the top of each interval, and the vertical displacements of each of the megacolumns at the top of each interval. Figure 3-1 below shows a laterally displaced core (thick line), a single megacolumn B (thin line), and outrigger trusses at the top of each interval (dotted lines). The dashed lines show the undisplaced position of the structure. The DOF's are identified in Figure 3-1 where subscripts correspond to story numbers. Symmetry is exploited if possible. The generic skyscraper is doubly symmetric so that only one quarter of the skyscraper is included in the model. The model consists of one-fourth of the core, one-half of megacolumns C and E, and a full portion of

megacolumns A, B, and D. Assume that the lateral load is perpendicular to the wall containing megacolumns A, B, and C. Since the vertical displacement in megacolumn E is zero under lateral loading, only the vertical displacements for megacolumns A, B, C, and D will be counted as DOF's. Thus, there are 6 DOF's at the top of each interval for a total of 30 DOF's.

Figure 3-1: Displaced core with location of DOF's

The moment of inertia of the core must be calculated for each interval. This is done by dividing the core into thin rectangles where it is assumed that all rectangles have the same thickness in Equation 3-10:

 I_i^{core} = moment of inertia of the core in interval i t_i = core wall thickness in interval i d_i^j = length of rectangle j in interval i y_i^j = distance from centroid of rectangle j to neutral axis in interval i α_i^j = angle from neutral axis to axis parallel to length of rectangle j in interval i $\sum_{i} \left(d_i^j (y_i^j)^2 + \frac{(d_i^j)^2 (\sin \alpha_i^j)^2}{12} \right)$ (3-10) J \backslash \mathbf{I} I \setminus $= t_i \sum \left(d_i^j (y_i^j)^2 + \frac{(d_i^j)^3 (\sin \alpha)}{4} \right)$ j j \mathcal{V} i $\left(\frac{1}{i}\right)^2 + \frac{(d_i)^3}{i}$ j i \angle | u_i core $i = i \sum_{i} \left| \frac{\mathbf{u}_{i}(y_i)}{y_i} \right|$ 12 $I_i^{\text{core}} = t_i \sum \left[d_i^j (y_i^j)^2 + \frac{(d_i^j)^j (\sin \theta_i)}{12} \right]$

The local moments of inertia of the megacolumns are much less than the core moment of inertia, and may be calculated from the megacolumn areas in Equation 3-11:

 I_i^{colj} = local moment of inertia of megacolumn j in interval i A_i^{colj} = cross-sectional area of megacolumn j in interval i η = 12 for solid square and 4π for solid circle (3-11) $=\frac{(A_i^{colj})}{\eta}$ 2 colj $I_i^{\text{colj}} = \frac{(A_i^{\text{c}})^2}{I_i^{\text{colj}}}$

For the generic skyscraper, the contribution of the core and megacolumns to the first 12 rows and columns of the stiffness matrix is shown in Table 3-1 with Equations 3-12 to 3-20:

$$
I_{i} = \frac{I_{i}^{\text{core}}}{4} + I_{i}^{\text{coll}} + I_{i}^{\text{coll}} + \frac{I_{i}^{\text{coll}}}{2} + I_{i}^{\text{coll}} + \frac{I_{i}^{\text{coll}}}{2}
$$
(3-12)

$$
k_i^{\text{cor1}} = \frac{12EI_i}{h_i^3} \quad k_i^{\text{cor2}} = \frac{6EI_i}{h_i^2} \qquad k_i^{\text{cor3}} = \frac{4EI_i}{h_i} \qquad k_i^{\text{cor4}} = \frac{2EI_i}{h_i} \qquad (3-13, 3-14, 3-15, 3-16)
$$

$$
k^{\text{colA}}_i = \frac{EA^{\text{colA}}_i}{h_i} \ k^{\text{colB}}_i = \frac{EA^{\text{colB}}_i}{h_i} \hspace{0.5cm} k^{\text{colC}}_i = \frac{EA^{\text{colC}}_i}{2h_i} \ \ k^{\text{colD}}_i = \frac{EA^{\text{colD}}_i}{h_i} \hspace{0.5cm} (3\text{-}17, 3\text{-}18, 3\text{-}19, 3\text{-}20)
$$

			A_{100}	B_{100}	C_{100}	D_{100}			A_{80}	B_{80}	C_{80}	D_{80}
Δ_{100}	$\frac{\Delta_{100}}{k_1^{\text{corl}}}$	$\frac{\theta_{100}}{-k_1^{\text{cor2}}}$					$\frac{\Delta_{80}}{-k_1^{\text{corl}}}$	$\frac{\theta_{80}}{-k_1^{\rm cor2}}$				
θ_{100}	$-k_1$ ^{cor2}	k_1^{cor3}					k_1^{cor2}	k_1^{cor4}				
A_{100}			k_1^{colA}						$-k_1^{\text{colA}}$			
B_{100}				k_1^{colB}						$-k_1^{\text{colB}}$		
C_{100}					k_1^{colC}						$-k_1^{\text{colC}}$	
D_{100}						k_1^{coll}						$-k_1$ ^{colD}
Δ_{80}	$-k_1$ ^{cor1}	k_1^{cor2}					k_1 corl	k_1^{cor2}				
							$+k_2$ ^{cor1}	$-k_2$ ^{cor2}				
θ_{80}	$-k_1$ ^{cor2}	k_1^{cor4}					k_1^{cor2} - k_2^{cor2}	k_1^{cor3} + k_2^{cor3}				
A_{80}			$-k_1^{\text{colA}}$						k_1^{colA}			
									$+k_2$ ^{colA}			
B_{80}				$-k_1^{\text{coll}}$						k_1^{colB}		
										$+k_2^{\text{colB}}$		
C_{80}					$-k_1$ ^{colC}						k_1^{colC} + k_2^{colC}	
D_{80}						$-k_1$ ^{colD}						k_1^{colD} + k_2^{colD}

Table 3-1: Stiffness matrix - contribution of the core and megacolumns

The shear stiffness of a typical outrigger truss as shown in [Figure 3-2](#page-40-0) is the reciprocal of the vertical tip displacement due to a unit load.

Figure 3-2: Typical outrigger truss subject to unit load

Assume that the cross-sectional area of each member of the outrigger truss is proportional to the magnitude of the axial force F indicated in the figure above as in Equation 3-21. Let C be the constant of proportionality:

$$
A = C|F|
$$
 (3-21)

The total volume of N outrigger trusses at the top of an interval is calculated in Equation 3-22:

$$
V = N \sum AL = NC \sum |F|L \tag{3-22}
$$

The stiffness of any outrigger truss is the reciprocal of the tip displacement as determined by the principle of virtual forces in Equation 3-23:

$$
kout = \frac{1}{\sum_{EA}^{F^2} L} = \frac{CE}{\sum |F| L} = \frac{EV}{N(\sum |F| L)^2}
$$
(3-23)

For the outrigger truss in [Figure 3-2](#page-40-0) its stiffness is calculated from Equations 3-24 and 3-25:

$$
\sum |F|L = \frac{w^2}{h} + \frac{2w^2}{h} + \frac{L_1^2}{h} + \frac{2L_2^2}{h} + \frac{h}{2} = \frac{6w^2 + 2h^2}{h}
$$
 (3-24)

$$
k^{out} = \frac{Eh^2V}{N(6w^2 + 2h^2)^2}
$$
 (3-25)

The shear stiffness of each of the 8 two-member outrigger trusses per interval in the generic skyscraper is shown in [Figure 3-3](#page-41-0) and calculated in Equation 3-26:

Figure 3-3: Two-member outrigger truss subject to unit load

 k_i^{out} = shear stiffness of an outrigger truss at top of interval i V_i^{out} = volume of all outrigger trusses at top of interval i S_i^{out} = sine of angle from horizontal of members of outrigger truss at top of interval i h_i^{out} = height of outrigger truss at top of interval i (16m for generic skyscraper) E^s = steel modulus of elasticity

$$
k_i^{out} = \frac{EV}{N\left(\sum |F|L\right)^2} = \frac{EV}{8\left(2\left(\frac{1}{2S}\right)\left(\frac{h}{2S}\right)\right)^2} = \frac{E^s \left(S_i^{out}\right)^4 V_i^{out}}{2\left(h_i^{out}\right)^2}
$$
(3-26)

For the generic skyscraper, the contribution of the outriggers to the first 12 rows and columns of the stiffness matrix is shown in Table 3-2. Since there are no outriggers at story 100 in the generic skyscraper, $k_1^{\text{out}} = 0$, but it is retained in the table to illustrate the pattern.

	Δ_{100}	Θ_{100}	A_{100}	B_{100}	C_{100}	D_{100}	Δ_{80}	Θ_{80}	A_{80}	B_{80}	C_{80}	D_{80}
Δ_{100}												
Θ_{100}		$\frac{12.5^2 k_1^{out}}{1.25^2 k_1^{out}}$		$-25k_1^{\text{out}}$		$-12.5k_1^{\text{out}}$						
A_{100}												
\mathbf{B}_{100}		$-25k_1^{\text{out}}$		k_1 ^{out}								
C_{100}												
D_{100}		$-12.5k_1^{\text{out}}$				k_1 ^{out}						
Δ_{80}												
Θ_{80}								$12.5^{2}k_{2}^{out}$ +25 ² k_{2}^{out}		$-25k_2$ ^{out}		$-12.5k_2^{\text{out}}$
A_{80}												
B_{80}								$-25k_2$ ^{out}		k_2 ^{out}		
C_{80}												
D_{80}								$-12.5k_2^{\text{out}}$				k_2 ^{out}

Table 3-2: Stiffness matrix - contribution of outriggers

Note that there is coupling between the vertical displacements of megacolumns B and D and the rotation of the core. To understand this coupling, Figure 3-4 shows the left half of the core in solid black and a two-member outrigger truss extending from the core to megacolumn B. The top part of the figure shows a unit upward vertical displacement at megacolumn B and the bottom part of the figure shows a unit clockwise core rotation.

Figure 3-4: Unit upward vertical displacement (top) and unit clockwise core rotation (bottom)

The shear stiffness of each of the 16 eight-member belt trusses per interval in the generic skyscraper is shown in [Figure 3-5](#page-43-0) and calculated in Equation 3-27:

Figure 3-5: Eight-member belt truss subject to unit load

 k_i^{belt} = shear stiffness of a belt truss at top of interval i V_i^{belt} = volume of all belt trusses at top of interval i S_i^{belt} = sine of angle from horizontal of members of belt truss at top of interval i h_i^{belt} = height of belt truss at top of interval i (8m for generic skyscraper) E^s = steel modulus of elasticity

$$
k_i^{\text{belt}} = \frac{EV}{N(\sum |F|L)^2} = \frac{EV}{16\left(\frac{4w^2}{2h} + \frac{4L}{2S}\right)^2} = \frac{E^s (S_i^{\text{belt}})^4 V_i^{\text{belt}}}{64(h_i^{\text{belt}})^2 (2 - (S_i^{\text{belt}})^2)^2}
$$
(3-27)

If it is assumed that the horizontal members of the belt truss consist of infinitely stiff floor diaphragms, then the shear stiffness of each of the belt trusses in the generic skyscraper is increased as shown in [Figure 3-6](#page-44-0) and calculated in Equation 3-28:

Figure 3-6: Belt truss in generic skyscraper subject to unit load

$$
k_i^{\text{belt}} = \frac{EV}{N\left(\sum |F|L\right)^2} = \frac{EV}{16\left(4\left(\frac{1}{2S}\right)\left(\frac{h}{S}\right)\right)^2} = \frac{E^s \left(S_i^{\text{belt}}\right)^4 V_i^{\text{belt}}}{64\left(h_i^{\text{belt}}\right)^2}
$$
(3-28)

For the generic skyscraper, the contribution of the belts to the first 12 rows and columns of the stiffness matrix is shown in Table 3-3. Since there are no belts at story 100 in the generic skyscraper, $k_1^{belt} = 0$, but it is retained in the table to illustrate the pattern.

	Δ_{100}	θ_{100}	A_{100}	B_{100}	C_{100}	D_{100}	Δ_{80}	θ_{80}	A_{80}	B_{80}	C_{80}	D_{80}
Δ_{100}												
Θ_{100}		$\frac{2(12.5^2)}{k_1^{\text{belt}}}$	$-12.5k_1^{belt}$									
A_{100}		$-12.5k_1$ ^{belt}	$2k_1$ ^{belt}	$-k_1$ ^{belt}		$-k_1$ ^{belt}						
B_{100}			$-k_1$ ^{belt}	$2k_1$ ^{belt}	$-k_1$ ^{belt}							
				$-k_1$ ^{belt}	k_1 ^{belt}							
$\frac{C_{100}}{D_{100}}$			$-k_1$ ^{belt}			$2k_1$ ^{belt}						
Δ_{80}												
θ_{80}								$\frac{2(12.5^2)}{k_2^{belt}}$	$-12.5k_2$ ^{belt}			
A_{80}								$-12.5k_2$ ^{belt}	$\frac{2k_2^{belt}}{-k_2^{belt}}$	$-k_2$ ^{belt}		$-k_2$ ^{belt}
B_{80}										$2k_2$ ^{belt}	$-k_2$ ^{belt}	
C_{80}										$-k_2$ ^{belt}	k_2 ^{belt}	
D_{80}									$-k_2$ ^{belt}			$2k_2$ ^{belt}

Table 3-3: Stiffness matrix - contribution of the belt trusses

Note that there is coupling between the vertical displacement of megacolumn A and the rotation of the core. To understand this coupling, Figure 3-7 shows belt trusses spanning between megacolumn A on the left, megacolumn D in the middle, and megacolumn E on the right. The top part of the figure shows a unit vertical displacement at megacolumn A, the middle part of the figure shows a unit vertical displacement at megacolumn D, and the bottom part of the figure shows a unit core rotation. It is assumed that the rotation of all megacolumns is the same as the rotation of the core because the core and megacolumns are connected with axially rigid floor diaphragms at every story.

Figure 3-7: Unit displacement at megacolumns A (top) and D (middle), and a unit core rotation (bottom)

The vertical stiffness of each of the 32 diagonals per interval in the generic skyscraper is given in [Figure 3-8](#page-47-0) and calculated in Equation 3-29:

Figure 3-8: Diagonal in generic skyscraper subject to unit load

 k_i^{diag} = vertical stiffness of a diagonal member in interval i V_i^{diag} = volume of all diagonal members in interval i S_i^{diag} = sine of angle from horizontal for diagonals in interval i h_i^{diag} = height of diagonal between adjacent megacolumns (20m for generic skyscraper) E^s = steel modulus of elasticity

$$
k_i^{\text{diag}} = \frac{EV}{N\left(\sum |F|L\right)^2} = \frac{EV}{32\left(\left(\frac{1}{S}\right)\left(\frac{h}{S}\right)\right)^2} = \frac{E^s \left(S_i^{\text{diag}}\right)^4 V_i^{\text{diag}}}{32\left(h_i^{\text{diag}}\right)^2}
$$
(3-29)

For the generic skyscraper, the contribution of the diagonals to the first 12 rows and columns of the stiffness matrix is shown in Table 3-4.

		θ_{100}	A_{100}	B_{100}	C_{100}	$D_{1\underline{00}}$		θ_{80}	A_{80}	B_{80}	C_{80}	D_{80}
Δ_{100}	$\frac{\Delta_{100}}{4k_1^{\text{diag}}/6.4^2}$		$-k_1$ ^{diag} /6.4				$\frac{\Delta_{80}}{-4k_1^{\text{diag}}/6.4^2}$		$-k_1^{diag}/6.4$			
θ_{100}												
A_{100}	$-k_1$ ^{diag} /6.4		diag $2k_1$	diag $-k_1$		diag $-k_1$	k_1 ^{diag} /6.4					
B_{100}			$-k_1$ ^{diag}	diag $2k_1$	diag $-k_1$							
C_{100}				$-k_1$ ^{diag}	k_1 ^{diag}							
D_{100}			diag $-k_1$			diag $2k_1$						
Δ_{80}	$-4k_1^{diag}/6.4^2$		$k_1^{\text{diag}}/6.4$				$4k_1^{diag}/6.4^2$ +4 $k_2^{diag}/6.4^2$		$k_1^{diag}/6.4 - k_2^{diag}/6.4$			
θ_{80}												
A_{80}	$-k_1$ ^{diag} /6.4						$k_1^{diag}/6.4 - k_2^{diag}/6.4$		$2k_1$ ^{diag}	$-k_1$ ^{diag}		$-k_1$ ^{diag} - k_2 ^{diag}
									$\frac{+2k_2}{-k_1}$ diag	$-\underline{k_2}^{diag}$		
B_{80}										$2k_1$ ^{diag}	$-k_1^{\text{diag}}$ - k_2^{diag}	
									$-k_2^{\text{diag}}$	$+2k_2$ ^{diag}		
C_{80}										$-k_1$ ^{diag}	k_1 ^{diag}	
										$-\underline{k_2}$ ^{diag}	$+k_2$ ^{diag}	
D_{80}									$-k_1$ ^{diag} - k_2 ^{diag}			$\frac{2k_1^{diag}}{1+2k_2^{diag}}$

Table 3-4: Stiffness matrix - contribution of diagonals

Note that there is coupling between the vertical displacement of megacolumn A and the horizontal displacement of the core. To understand this coupling, Figure 3-9 shows diagonals and megacolumns A, D, and E in the top two intervals. The left part of the figure shows a unit vertical displacement at megacolumn A at the top of interval 2 (bottom of interval 1), the middle part of the figure shows a unit vertical displacement at megacolumn D at the top of interval 2, and the right part of the figure shows a unit horizontal displacement at the top of interval 2. It is assumed that the horizontal displacement of all megacolumns is the same as the horizontal displacement of the core because the core and megacolumns are connected with axially rigid floor diaphragms at every story.

Figure 3-9: Unit vertical displacements at megacolumns A (left), D (middle), and E (right)

3.3 **Calculation of Lateral Forces/Displacements**

The lateral force vectors have zero values for the DOF's corresponding to vertical displacements in the megacolumns at the top of each interval. To get the values for the DOF's corresponding to the horizontal displacements and rotations in the core at the top of each interval, the lateral forces for wind and seismic loading are determined at every story and then aggregated over the intervals. The spreadsheet includes a sheet with a row for each story in the building starting at the bottom and increasing upward (100 stories for the generic skyscraper).

For the lateral wind pressure, a formula such as Equation (**[3-30](#page-49-0)** taken from ASCE 7-05 could be used:

 $P_k^{\text{wind}} =$ wind pressure at story k in psf $v =$ design wind speed in miles per hour (123mph for the generic skyscraper) H_k = height of story k above the ground H_g = reference height parameter reflecting exposure (274m for the generic skyscraper) α = another parameter reflecting the exposure (9.5 for the generic skyscraper) (3-30) 2 $2/$ g $P_{\rm k}^{\rm wind} = 0.00256 \left| 2.01 \left(\frac{\rm H_{k}}{\rm H_{g}} \right) \right| \quad \text{v}$ $\overline{}$ J \setminus $\overline{}$ I \setminus ſ $\overline{}$ $\overline{}$ $\bigg)$ \setminus I I \setminus $= 0.00256 \left(2.01 \left(\frac{H_k}{\sigma^2} \right)^{2/\alpha} \right)$

After getting the wind pressure at each story and converting it to the appropriate units, the wind force at each story is obtained from Equation 3-31:

 $F_k^{\text{wind}} =$ lateral wind force at story k s_k = story height for story k (4m for the generic skyscraper) w_k = building width at story k (50m for the generic skyscraper) (3-31) k ^{vv} k wind k $F_k^{\text{wind}} = P_k^{\text{wind}} s_k w$

For lateral seismic forces, the dead weight of each story must be obtained from Equation 3-32:

 W_k = weight of story k (excluding live load) A_k = floor area of story k P_k = building perimeter at story k s_k = story height for story k (4m for the generic skyscraper) $L^{dead} =$ floor dead load per area $L^{clad} = cladding load per area$ γ = concrete unit weight $A_k^{\text{core-col}}$ = cross-sectional area of core and all megacolumns at story k γ^s = steel unit weight $V_k^{\text{out-belt-diag}}$ = volume of all outriggers, belts, and diagonals at story k

$$
W_k = A_k L^{\text{dead}} + s_k P_k L^{\text{clad}} + \gamma s_k A_k^{\text{core-col}} + \gamma^s V_k^{\text{out-belt-diag}}
$$
\n(3-32)

The seismic force at each story is obtained with a formula such as Equation 3-33 taken from

ASCE 7-05:

 $F_k^{\text{seismic}} =$ lateral seismic force at story k H_k = height of story k above the ground S_a = spectral acceleration in g (0.2 for generic skyscraper) $R =$ ductility factor (3 for generic skyscraper) β = seismic exponent (2 for generic skyscraper)

$$
F_k^{\text{seismic}} = \frac{W_k \left(H_k\right)^{\beta}}{\sum_{k} \left(W_k \left(H_k\right)^{\beta}\right) R} \sum_{k} W_k \tag{3-33}
$$

The wind and seismic forces at each story must be aggregated over intervals to get the forces and moments at the DOF's corresponding to the horizontal displacements and rotations in the core at the top of each interval. Figure 3-10 shows a particular interval of height h_i and a wind or seismic lateral force F_k at a particular story k. In the generic skyscraper there are 20 stories in each interval. Formulas for the fixed end force and moment support reactions at the top and bottom of the interval are given in the figure. In the spreadsheet, these formulas are evaluated for every lateral force in every interval. The negative of these support reactions are the equivalent forces and moments applied at the DOF's. The rightward force at a particular DOF corresponding to a core horizontal displacement is equal to the sum of F_k^{bot} for all lateral forces in the interval above the DOF plus the sum of F_k^{top} for all lateral forces in the interval below the DOF. The clockwise moment at a particular DOF corresponding to a core rotation is equal to the sum of M_k^{bot} for all lateral forces in the interval above the DOF minus the sum of M_k^{top} for all lateral forces in the interval below the DOF.

Figure 3-10: Interval with a wind/seismic force at a particular story k

The stiffness matrix is inverted and multiplied by the lateral force vector for wind loading to get the core horizontal displacements, the core rotations, and the megacolumn vertical displacements at the top of each interval. The inverted stiffness matrix is multiplied by the lateral force vector for seismic loading to get these same displacements for seismic loading. The principle of superposition is used to get the lateral displacement at a particular story within an interval. Superposition begins with a cubic polynomial for the displacement due to displacements and rotations at the top and bottom of the interval, and then adds the

displacements of the fixed-fixed beam in Figure 3-11 due to all of the point loads F_k in the

interval and calculated in Equation 3-34:

 Δ_k = lateral displacement at story k h_i = height of interval i a_k = height from bottom of interval i to story k Δ_i = core lateral displacement at top of interval i Δ_{i+1} = core lateral displacement at bottom of interval i θ_i = core rotation at top of interval i θ_{i+1} = core rotation at bottom of interval i F_m^{bot} = fixed end force at bottom of interval due to point force m F_m^{top} = fixed end force at top of interval due to point force m M_m^{bot} = fixed end moment at bottom of interval due to point force m M_m ^{bot} = fixed end moment at top of interval due to point force m $E =$ concrete modulus of elasticity (core and megacolumns) I_i = moment of inertia of core and local moment of inertia of megacolumns

$$
\Delta_{k} = \left(\frac{2(\Delta_{i+1} - \Delta_{i})}{h_{i}^{3}} + \frac{\theta_{i} + \theta_{i+1}}{h_{i}^{2}}\right)a_{k}^{3} + \left(\frac{3(\Delta_{i} - \Delta_{i+1})}{h_{i}^{2}} - \frac{\theta_{i} + 2\theta_{i+1}}{h_{i}}\right)a_{k}^{2} + \theta_{i+1}a_{k} + \Delta_{i+1}
$$
(3-34)

$$
-\left(\frac{a_{k}^{3} \sum_{m>k} F_{m}^{bot}}{6} - \frac{a_{k}^{2} \sum_{m>k} M_{m}^{bot}}{2} + \frac{(h_{i} - a_{k})^{3} \sum_{m>k} F_{m}^{top}}{6} - \frac{(h_{i} - a_{k})^{2} \sum_{m>k} M_{m}^{top}}{2}\right)\left(\frac{1}{EI_{i}}\right)
$$

Interstory drifts can be calculated and compared to allowable values (e.g. 1/360 for wind and

1/50 for seismic) in Equation 3-35:

 D_k = interstory drift at story k Δ_k = lateral displacement at story k s_k = story height for story k (4m for the generic skyscraper)

$$
D_k = \frac{|\Delta_k - \Delta_{k-1}|}{s_k} \tag{3-35}
$$

As the skyscraper displaces laterally under wind and seismic loads, the weight of the structure creates an additional overturning moment equal to the weight times the lateral

displacement. This moment, called the P∆ effect, increases the lateral displacement, and thus, nonlinear iteration is necessary to converge to the final equilibrium position when the P∆ moments no longer change:

 W_k = weight of story k (including live load) $F_k = F_{k+1} + W_k$ = total axial force at story k Δ_k = lateral displacement at story k $M_k = F_k(\Delta_k - \Delta_{k-1})$ moment at story k due to P Δ effect

The moments at each story must be aggregated over intervals to get the forces and moments at the DOF's corresponding to the horizontal displacements and rotations in the core at the top of each interval. Figure 3-11 shows a particular interval of height hi and a P∆ moment M_k at a particular story k. Formulas for the fixed end force and moment support reactions at the top and bottom of the interval are given in the figure. In the spreadsheet, these formulas are evaluated for every P∆ moment in every interval. The negative of these support reactions are the equivalent forces and moments applied at the DOF's. The rightward force at a particular DOF corresponding to a core horizontal displacement is equal to the sum of F_k^{bot} for all lateral forces in the interval above the DOF plus the sum of F_k^{top} for all lateral forces in the interval below the DOF. The clockwise moment at a particular DOF corresponding to a core rotation is equal to the sum of M_k^{bot} for all lateral forces in the interval above the DOF minus the sum of M_k^{top} for all lateral forces in the interval below the DOF.

Figure 3-11: Interval and a P-delta moment at a particular story k

Nonlinear iteration is accomplished in the spreadsheet by creating two columns for the P∆ lateral force vector -- a starting column and an ending column. The starting column is initialized to zero and is added to the wind lateral force vector. The ending column calculates the new P∆ lateral force vector by the procedure described above. The values from the ending column are repeatedly pasted into the starting column until the two columns are the same. Starting and ending columns for the P∆ lateral force vector are likewise created for seismic loading.

3.4 **Calculation of Stresses**

Gravity load stresses are greatest at the bottom of each interval for the core, megacolumns, and diagonals. The gravity load stress is the same for the core and the megacolumns since megacolumn areas were determined earlier by equating their gravity load strains to that of the core (see Equations 3-36 and 3-37). The gravity load stress in diagonals is also determined by equating the respective gravity load strain to that of the core in Equation 3- 38. The gravity load stress in interior diagonal members is decreased by a fraction of the relative increment in axial force for the interval in Equation 3-39:

 $\sigma_i^{\text{core_grav}} =$ gravity load stress in core at bottom of interval i $\sigma_i^{\text{colj_grav}} =$ gravity load stress in megacolumn j at bottom of interval i $\sigma_i^{\text{outB_grav}} =$ gravity load stress in outrigger B at top of interval i $\sigma_i^{\text{outD_grav}} =$ gravity load stress in outrigger D at top of interval i $\sigma_i^{\text{diagAB_grav}} =$ gravity load stress in bottom diagonal AB in interval i $\sigma_i^{\text{diagAD_grav}} =$ gravity load stress in bottom diagonal AD in interval i $\sigma_i^{\text{diagBC_grav}} =$ gravity load stress in bottom diagonal BC in interval i $\sigma_i^{\text{diagDE_grav}} =$ gravity load stress in bottom diagonal DE in interval i h_i = vertical height of interval i (80m for generic skyscraper) A_i^{core} = cross-sectional area of the core in interval i F_i^{core} = axial force in core at base of interval i excluding interval i self weight γ = concrete unit weight (core and megacolumns) $E =$ concrete modulus of elasticity E^s = steel modulus of elasticity S_i^{out} = sine of angle from horizontal of members of outrigger truss at top of interval i S_i^{diag} = sine of angle from horizontal for diagonals in interval i

$$
\sigma_i^{\text{core_grav}} = \frac{F_i^{\text{core}}}{A_i^{\text{core}}} + \gamma h_i
$$
\n(3-36)

$$
\sigma_i^{\text{colj_grav}} = \sigma_i^{\text{core_grav}} \tag{3-37}
$$

$$
\sigma_i^{\text{diagAB_grav}} = \sigma_i^{\text{diagAD_grav}} = \frac{E^s (S_i^{\text{diag}})^2 \sigma_i^{\text{core_grav}}}{E}
$$
(3-38)

$$
\sigma_i^{\text{diagBC}} - \text{grav} = \sigma_i^{\text{diagDE}} - \text{grav} = \frac{E^s (S_i^{\text{diag}})^2 \sigma_i^{\text{core}} - \text{grav}}{E} \left(1 - .25 \frac{F_i^{\text{core}} - F_{i-1}^{\text{core}}}{F_i^{\text{core}}} \right)
$$
(3-39)

The lateral load stress in the core and megacolumns at the bottom of each interval is equal to the modulus of elasticity times axial strain plus the modulus of elasticity times flexural curvature times distance from local neutral axis to outermost fiber in Equations 3-40 and 3-41. The flexural curvature is the same for core and megacolumns and is obtained by differentiating

the lateral displacement formulas twice and evaluating at $a_k = 0$ (bottom of the interval). Under lateral loading, the axial strain is zero in the core. The megacolumn axial strain is equal to the difference between vertical displacements in the megacolumn at the top and bottom of the interval divided by the interval height:

 $\sigma_i^{\text{core}_\text{lat}}$ = lateral load stress in core at bottom of interval i $\sigma_i^{\text{colj_lat}}$ = lateral load stress in megacolumn j at bottom of interval i h_i = height of interval i $E =$ concrete modulus of elasticity (core and megacolumns) I_i = moment of inertia of core and local moment of inertia of megacolumns c_i^{core} = distance to outermost fiber in core in interval i (12.5m for generic skyscraper) c_i^{colj} = distance to outermost fiber in megacolumn j in interval i A_i^{colj} = cross-sectional area of megacolumn j in interval i μ = 4 for solid square and π for solid circle Δ_i = core lateral displacement at top of interval i Δ_{i+1} = core lateral displacement at bottom of interval i θ_i = core rotation at top of interval i θ_{i+1} = core rotation at bottom of interval i Δ_i^{colj} = vertical displacement in megacolumn j at top of interval i Δ_{i+1}^{colj} = vertical displacement in megacolumn j at bottom of interval i M_m^{bot} = moment at bottom of interval due to lateral force at story m within interval i

$$
\sigma_i^{\text{core}_\text{lat}} = \text{Ec}_i^{\text{core}} \left(\frac{6(\Delta_i - \Delta_{i+1})}{h_i^2} - \frac{2\theta_i + 4\theta_{i+1}}{h_i} \right) + \frac{c_i^{\text{core}} \sum_{m} M_m^{\text{bot}}}{I_i}
$$
(3-40)

$$
\sigma_i^{\text{colj}_- \text{lat}} = \frac{E(\Delta_i^{\text{colj}} - \Delta_{i+1}^{\text{colj}})}{h_i} + \sigma_i^{\text{core}_- \text{lat}} \frac{c_i^{\text{colj}}}{c_i^{\text{core}}} \qquad \qquad c_i^{\text{colj}} = \sqrt{\frac{A_i^{\text{colj}}}{\mu}}
$$
(3-41)

For the typical outrigger truss in [Figure 3-12,](#page-57-0) recall the formulas developed earlier when the stiffness of this truss was considered:

Figure 3-12: Typical outrigger member subject to unit load

To get the lateral load stress for the members of this outrigger truss, the axial forces due to a unit load must be multiplied by the stiffness k^{out} times the shear displacement Δ^{out} . These axial forces must then be divided by the cross-sectional area to get stress as in Equation 3-42:

$$
\sigma^{\text{out}_lat} = \frac{|F|}{A} k^{\text{out}} \Delta^{\text{out}} = \frac{E}{\sum |F|} \Delta^{\text{out}} = \frac{Eh}{6w^2 + 2h^2} \Delta^{\text{out}}
$$
(3-42)

The lateral load stress in the members of each of the 8 two-member outrigger trusses per interval in the generic skyscraper is shown in [Figure 3-13](#page-57-1) and calculated in Equation 3-43:

Figure 3-13: Two-member outrigger truss subject to unit load

 $\sigma_i^{\text{out}_lat}$ = lateral load stress in outrigger at top of interval i Δ_i^{out} = shear displacement in outrigger at top of interval i S_i^{out} = sine of angle from horizontal of members of outrigger truss at top of interval i h_i^{out} = height of outrigger truss at top of interval i (16m for generic skyscraper) E^s = steel modulus of elasticity

$$
\sigma_i^{\text{out_lat}} = \frac{E}{\sum |F|L} \Delta^{\text{out}} = \frac{E}{2\left(\frac{1}{2S}\right)\left(\frac{h}{2S}\right)} \Delta^{\text{out}} = \frac{2E^s \left(S_i^{\text{out}}\right)^2}{h_i^{\text{out}}} \Delta_i^{\text{out}}
$$
(3-43)

The shear displacement in each outrigger is the difference between megacolumn vertical displacement and the product of core rotation and distance from core centerline to megacolumn as calculated in Equations 3-44 and 3-45. The shear displacement is greater for the upper member of the outrigger than for the lower member. The core rotation at the top of the upper member must be appropriately interpolated from the core rotation at the top of the interval and the core rotation at the top interval above:

 Δ_i^{outB} = shear displacement in outrigger B at top of interval i Δ_i^{outD} = shear displacement in outrigger D at top of interval i θ_i = core rotation at top of interval i θ_{i-1} = core rotation at top of interval i-1 Δ_i^{coll} = vertical displacement in megacolumn B at top of interval i Δ_i^{coll} = vertical displacement in megacolumn D at top of interval i (3-44) $\left(\theta_{_{i}}\right)-\Delta_{_{i}}^{colB}$ $\Delta_i^{outB} = |25m(\theta_i) - \Delta$

$$
\Delta_i^{\text{outD}} = |12.5m(\theta_i) - \Delta_i^{\text{colD}}| \tag{3-45}
$$

The lateral load stress in the members of each of the 16 eight-member belt trusses per interval in the generic skyscraper is shown in [Figure 3-14](#page-59-0) and calculated in Equation 3-46:

Figure 3-14: Eight-member belt truss subject to unit load

 σ_i^{belt} = lateral load stress in belt truss at top of interval i Δ_i^{belt} = shear displacement in belt truss at top of interval i S_i^{belt} = sine of angle from horizontal of members of belt truss at top of interval i h_i^{belt} = height of belt truss at top of interval i (8m for generic skyscraper) E^s = steel modulus of elasticity

$$
\sigma_i^{\text{belt}}{}^{-\text{lat}} = \frac{E}{\sum |F|L} \Delta^{\text{belt}} = \frac{E}{\frac{4w^2}{2h} + \frac{4L}{2S}} \Delta^{\text{belt}} = \frac{E^s (S_i^{\text{belt}})^2}{2h_i^{\text{belt}} (2 - (S_i^{\text{belt}})^2)} \Delta_i^{\text{belt}} \tag{3-46}
$$

If it is assumed that the horizontal members of the belt truss consist of infinitely stiff floor diaphragms, then the lateral load stress in the members of each of the belt trusses in the generic skyscraper is increased in [Figure 3-15](#page-59-1) and calculated in Equation 3-47:

Figure 3-15: Belt truss in generic skyscraper subject to unit load

$$
\sigma_i^{\text{belt}_lat} = \frac{E}{\sum |F|L} \Delta^{\text{belt}} = \frac{E}{4\left(\frac{1}{2S}\right)\left(\frac{h}{S}\right)} \Delta^{\text{belt}} = \frac{E^s \left(S_i^{\text{belt}}\right)^2}{2h_i^{\text{belt}}} \Delta_i^{\text{belt}} \tag{3-47}
$$

The shear displacement in belts AB and BC is the difference between the two ends of the belt of the megacolumn vertical displacements as calculated in Equations 3-48 and 3-49. The shear displacement in belt DE is the difference between megacolumn D vertical displacement and the product of core rotation and distance from core centerline to megacolumn D as calculated in Equation 3-50. The shear displacement in belt AD is the difference between the two ends of the belt of the difference between megacolumn vertical displacement and the product of core rotation and distance from core centerline to megacolumn as calculated in Equation 3-51:

 Δ_i^{beltAB} = shear displacement in belt AB at top of interval i Δ_i^{beltBC} = shear displacement in belt BC at top of interval i Δ_i^{beltAD} = shear displacement in belt AD at top of interval i Δ_i^{beltDE} = shear displacement in belt DE at top of interval i Δ_i^{coll} = vertical displacement in megacolumn A at top of interval i Δ_i^{coll} = vertical displacement in megacolumn B at top of interval i Δ_i^{colC} = vertical displacement in megacolumn C at top of interval i Δ_i^{coll} = vertical displacement in megacolumn D at top of interval i θ_i = core rotation at top of interval i

$$
\Delta_i^{\text{beltAB}} = \left| \Delta_i^{\text{colA}} - \Delta_i^{\text{colB}} \right| \qquad \qquad \Delta_i^{\text{beltBC}} = \left| \Delta_i^{\text{colB}} - \Delta_i^{\text{colC}} \right| \qquad (3-48, 3-49)
$$

$$
\Delta_i^{\text{beltAD}} = \left| 25\text{m}(\theta_i) - \Delta_i^{\text{colA}} - 12.5\text{m}(\theta_i) + \Delta_i^{\text{colD}} \right| \quad \Delta_i^{\text{beltDE}} = \left| 12.5\text{m}(\theta_i) - \Delta_i^{\text{colD}} \right| \tag{3-50, 3-51}
$$

The lateral load stress in each of the 32 diagonals per interval in the generic skyscraper is shown in [Figure 3-16](#page-61-0) and calculated in Equation 3-52:

Figure 3-16: Diagonal in generic skyscraper subject to unit load

 $\sigma_i^{\text{diag_lat}}$ = lateral load stress in a diagonal member in interval i Δ_i^{diag} = vertical displacement in diagonal members in interval i S_i^{diag} = sine of angle from horizontal for diagonals in interval i h_i^{diag} = height of diagonal between adjacent megacolumns (20m for generic skyscraper) E^s = steel modulus of elasticity

$$
\sigma_i^{\text{diag}_ \text{lat}} = \frac{E}{\sum |F| L} \Delta^{\text{diag}} = \frac{E}{\left(\frac{1}{S}\right) \left(\frac{h}{S}\right)} \Delta^{\text{diag}} = \frac{E^s \left(S_i^{\text{diag}}\right)^2}{h_i^{\text{diag}}} \Delta^{\text{diag}} \tag{3-52}
$$

The vertical displacement in diagonals AB and BC is the difference between the two ends of the diagonal of the megacolumn vertical displacements as calculated in Equations 3-53 and 3- 54. The vertical displacement in diagonal DE is the difference between megacolumn D vertical displacement and the product of lateral drift and distance from core centerline to megacolumn D as calculated in Equation 3-56. The vertical displacement in diagonal AD is the difference between the two ends of the diagonal of the difference between megacolumn vertical displacement and the product of lateral drift and distance from core centerline to megacolumn as calculated in Equation 3-55. In these formulas, megacolumn vertical displacements must be appropriately interpolated between the top and bottom of the interval to get values at the ends of the diagonal:

$$
\Delta_i^{\text{diagAB}} = \text{stress in bottom diagonal AB in interval i}
$$
\n
$$
\Delta_i^{\text{diagBC}} = \text{stress in bottom diagonal AD in interval i}
$$
\n
$$
\Delta_i^{\text{diagBC}} = \text{stress in bottom diagonal BC in interval i}
$$
\n
$$
\Delta_i^{\text{diagDE}} = \text{stress in bottom diagonal DE in interval i}
$$
\n
$$
\Delta_i^{\text{coll}} = \text{vertical displacement in megacolumn A at top of interval i}
$$
\n
$$
\Delta_i^{\text{coll}} = \text{vertical displacement in megacolumn B at top of interval i}
$$
\n
$$
\Delta_i^{\text{coll}} = \text{vertical displacement in megacolumn C at top of interval i}
$$
\n
$$
\Delta_i^{\text{coll}} = \text{vertical displacement in megacolumn D at top of interval i}
$$
\n
$$
\Delta_{i+1}^{\text{coll}} = \text{vertical displacement in megacolumn A at bottom of interval i}
$$
\n
$$
\Delta_{i+1}^{\text{coll}} = \text{vertical displacement in megacolumn A at bottom of interval i}
$$
\n
$$
\Delta_{i+1}^{\text{coll}} = \text{vertical displacement in megacolumn B at bottom of interval i}
$$
\n
$$
\Delta_{i+1}^{\text{coll}} = \text{vertical displacement in megacolumn C at bottom of interval i}
$$
\n
$$
\Delta_{i+1}^{\text{coll}} = \text{vertical displacement in megacolumn C at bottom of interval i}
$$
\n
$$
\Delta_{i+1}^{\text{diagAD}} = \text{lateral drift at the center of diagonal AD in interval i}
$$
\n
$$
D_i^{\text{diagAD}} = \text{lateral drift at the center of diagonal DE in interval i}
$$

$$
\Delta_i^{\text{diagAB}} = \left| \Delta_{i+1}^{\text{colA}} - .75 \Delta_{i+1}^{\text{colB}} - .25 \Delta_i^{\text{colB}} \right| \tag{3-53}
$$

$$
\Delta_i^{\text{diagBC}} = \left| .75\Delta_{i+1}^{\text{coll}} + .25\Delta_i^{\text{coll}} - .5\Delta_{i+1}^{\text{colC}} - .5\Delta_i^{\text{colC}} \right|
$$
\n(3-54)

$$
\Delta_i^{\text{diagAD}} = \left| D_i^{\text{diagAD}} (25m - 12.5m) - \Delta_{i+1}^{\text{colA}} + .75 \Delta_{i+1}^{\text{colD}} + .25 \Delta_i^{\text{colD}} \right|
$$
(3-55)

$$
\Delta_i^{\text{diagDE}} = \left| D_i^{\text{diagDE}} (12.5 \text{m}) - .75 \Delta_{i+1}^{\text{coll}} - .25 \Delta_i^{\text{coll}} \right| \tag{3-56}
$$

3.5 **Rapid Trial-and-Error Optimization**

Now that the description of the SSAM is complete, the spreadsheet can be used to optimize the skyscraper design. The design variables are the core thickness at each interval, the outrigger truss volume at each interval, the belt truss volume at each interval, and the diagonal volume at each interval. The objective is the minimization of structural cost which is the total volume of concrete in the core and megacolumns multiplied by the specified concrete cost per unit volume plus the total volume of steel in the outrigger trusses, belt trusses, and diagonals

multiplied by the specified steel cost per unit volume. The constraints to be satisfied include lateral drift in every story under wind loading, lateral drift in every story under seismic loading, stress in every member under combined gravity and wind loading, and stress in every member under combined gravity and seismic loading. For each of these types of constraints, the spreadsheet calculates a constraint ratio of actual value to allowable value. For example, the constraint ratio for wind lateral drift is equal to the maximum drift over the 100 stories divided by the specified allowable such as 1/360 or 1/400. The constraint ratio for wind+gravity belt stress is equal to the maximum wind+gravity stress over all belt truss members in all intervals divided by the allowable stress for steel. Design constraints are satisfied when the constraint ratios are less than or equal to one. The design variables, design objective, and design constraints are located together on the spreadsheet to facilitate rapid trial-and-error optimization. This process was carried out for all six configurations of the generic skyscraper.

4 SPACE FRAME MODEL

A 3D, skeletal, linear, static, small-displacement, space frame model was developed to compare the accuracy of the SSAM. The space frame model was executed on a program written by Balling (1991) as well as on the commercial program, ADINA. Both programs gave the same results for linear analysis. The ADINA program was also executed to get nonlinear (largedisplacement) results for one configuration of the space frame model. The space frame model will be described in five sections: nodes, members, supports, loads, and output.

4.1 **Nodes**

There were a total of 1877 nodes in the space frame model. The y-axis was taken as the vertical axis of the building located in the center of the core. There were 101 "core-center" nodes with x=z=0 equally spaced every 4m in the y-direction corresponding to the 100 stories of the generic skyscraper. Likewise, there were 101 "megacolumn" nodes for each of the 16 megacolumns. For a particular megacolumn, the x and z-coordinates were constant and depended on the location of the megacolumn in the plan, and the y-coordinates were equally spaced every 4m. Four "core-corner" nodes were located at each of stories 18, 22, 38, 42, 58, 62, 78, and 82 with horizontal coordinates $x=\pm 12.5$ m and $z=\pm 12.5$ m. Outrigger members connected core-corner nodes with megacolumn nodes. Sixteen "belt" nodes were located midway between megacolumn nodes at each of levels 19, 21, 39, 41, 59, 61, 79, and 81. Belt truss members connected belt nodes to megacolumn nodes.

4.2 **Members**

There were a total of 5668 members in the space frame model (see [Figure 4-1\)](#page-67-0), including 100 core members (yellow), 1600 megacolumn members (red), 64 outrigger members (green), 256 belt truss members (light blue), 160 diagonal members (black), 32 rigid link members (dark blue), and 3456 floor members (not shown in [Figure 4-1,](#page-67-0) but shown in [Figure 4-2\)](#page-68-0). Shear deformation was neglected in all members, and the Poisson's ratio was assumed to be 0.25.

Core members connect core-center nodes, and megacolumn members connect megacolumn nodes. Core and megacolumn members possess axial, flexural, and torsional stiffness. The modulus of elasticity and cross-sectional areas were set equal to the values used in the SSAM. Both the strong and weak core moments of inertia were set equal to the values used in the SSAM. The torsion constant was arbitrarily set to $1000m⁴$, and it was verified that this did not impact the results because of the symmetry of the structure and loading, and the axial rigidity of the floor diaphragms. Both ends of core and megacolumn members were connected rigidly.

Outrigger, belt truss, and diagonal members were modeled as truss members that only possess axial stiffness. The outrigger members connect between core-corner nodes and adjacent megacolumn nodes. The belt truss members connect between megacolumn nodes and belt nodes. The diagonal members connect between megacolumn nodes. Since these members possess axial stiffness only, their moments of inertia and torsion constants were set to zero, and both ends were hinge-connected. The modulus of elasticity was set equal to the value used in the SSAM. The cross-sectional areas were calculated by dividing the volumes used in the SSAM by the number of members and member length.

Rigid link members connect core-center nodes located at the intersection of intervals to core-corner nodes. They model the finite size of the core. Rigid link members possess infinite axial, flexural, and torsional stiffness. Infinite stiffness was obtained by setting the modulus of elasticity to 10^{12} KPa. The moments of inertia and torsion constant were arbitrarily set to 1000m⁴. Both ends of the rigid link members were connected rigidly.

Floor members extend radially from core-center nodes to megacolumn and belt nodes in the same horizontal plane. Additional floor members connect circumferentially between megacolumn and belt nodes in the same horizontal plane (see [Figure 4-2\)](#page-68-0). These members model the axially rigid floor diaphragms. They were modeled as truss members where their moments of inertia and torsion constants were set to zero, and both ends were hinge-connected. Axial rigidity was obtained by setting the modulus of elasticity to 10^{12}KPa . The cross-sectional areas were arbitrarily set to $1000m^2$. Choi et al. (2012) mentioned that if a belt truss is used, a stiff floor diaphragm is required at the top and bottom chord of each belt truss in order to transfer the core bending moment, in the form of floor shear and axial forces, to the belt wall and eventually to the columns. Also, improperly modeled diaphragms will result in misleading behaviors and load paths, and incorrect member design forces.

Figure 4-1: Space frame model – all members without floors

Figure 4-2: Space frame model – single floor configurations between intervals and at intervals

4.3 **Supports**

Supports restrained some of the DOF's. Each of the 1877 nodes in the space frame model had six displacement DOF's: three translations (Δ_x , Δ_y , and Δ_z) and three rotations (θ_x , θ_y , and θ _z). A total of 486 restraints were needed in this model. The core-center node and the sixteen megacolumn nodes at the base of the structure were fixed-supported to create 6x17=102 restraints. The rotational DOF's of the 128 belt nodes had to be supported for stability since the belt members were hinge-connected. This created 3x128=384 restraints. The number of unrestrained DOF's in the space frame model was $6 \times 1877 - 486 = 10,776$. Note that this is far greater than the 30 DOF's of the SSAM.

4.4 **Loads**

Both point loads and distributed loads were included in this model. A downward point load was applied at each of the core-center and megacolumn nodes representing the external dead, live, and cladding loads (1700 point loads). Horizontal point loads in the positive x direction were applied to each core-center node representing the lateral loads (100 point loads). Downward distributed loads were applied to core, megacolumn, outrigger, belt truss, and diagonal members representing member self-weight (2180 distributed loads). The magnitudes for all of these loads were obtained from the SSAM.

4.5 **Output**

Output from the space frame program consisted of nodal displacements and member end forces. These output files were imported into a macro-enabled Excel spreadsheet. The macro in the spreadsheet extracted appropriate data and calculated the following for comparison with the results from the SSAM:

core lateral translations core rotations core stresses megacolumn stresses outrigger stresses belt truss stresses diagonal stresses

5 RESULTS

Results from the SSAM and the space frame model (Sframe) are compared in the following tables for the six configurations of the generic skyscraper. For each configuration, the first table gives values of the design variables and calculated megacolumn areas for each interval. In the remaining tables for each configuration, the term "ratio" is the ratio of the SSAM value over the Sframe value. The "max error" given as a percentage below each table is equal to 100 times the maximum absolute value of the ratio minus one. The values in all tables are for linear analysis only with the exception of Table 5-2 and [Table 5-3](#page-72-0) (Configuration #1) where values are given for both linear and nonlinear analysis. All tables give results for combined gravity and lateral loading with the exception of tables for outrigger and belt stresses where the results are for lateral loading only.

It was observed in the space frame model, for configurations involving belt trusses, that the stress in the megacolumn located inside belt trusses was much greater than the stress in the megacolumn located outside belt trusses. It was assumed that the megacolumn cross-sectional area for an interval refers to the megacolumn outside belt trusses. The Sframe megacolumn stress reported in the following tables is the value for the member just above the belt truss at the bottom of the interval.

The lateral displacement and interstory drift are also plotted after the comparison tables for each configuration. Recall that interstory drift is defined as the difference in lateral displacement between the top and bottom of the story divided by the story height. Since rotation is the derivative of lateral displacement, interstory drift is effectively a finite difference approximation of rotation. The interstory drift that is plotted in the figures that follow has been normalized by the allowable value so that when the normalized value is less than one, the drift constraint is satisfied. Points of contraflexure are also indicated on the plots. They are located at points where the drift is vertical because that is the point where the rotation changes from increasing to decreasing with height. Points of contraflexure also correspond to points where curvature changes in the plot of lateral displacement. However, the curvature changes are too subtle to observe in the lateral displacement plots for the six configurations. A seventh configuration was added with outriggers located only at interval 2. Here the points of contraflexure are observable in both the plot of drift and the plot of lateral displacement.

5.1 **Configuration #1 – core+megacolumns**

						Core t Outrig V Belt V Diag V Megacolumn A Megacolumns B/D Megacolumns C/E	
Interval	\mathbf{m}	(m^3)	m	m	Area (m^2)	Area (m^2)	Area $(m2)$
	0.5				1.7318	3.1207	3.1207
\mathcal{D}	0.9				3.1172	5.6172	5.6172
3	1.4				4.8490	8.7379	8.7379
$\overline{4}$	1.8	0			6.2344	11.2344	11.2344
	23				7.9662	14.3551	14.3551

Table 5-1: Configuration #1 - design variables and calculated megacolumn areas
Top of	Linear	Linear		Linear Nonlinear Nonlinear Nonlinear	
Interval	SSAM	Sframe	Ratio SSAM Sframe		Ratio
$\mathbf{1}$	$\vert 0.693991 \vert 0.693624 \vert 1.0005 \vert 0.749785 \vert 0.748866 \vert 1.0012$				
2	$\vert 0.491343 \vert 0.49108 \vert 1.0005 \vert 0.530263 \vert 0.529674 \vert 1.0011$				
$\overline{3}$	$\vert 0.302933 \vert 0.302771 \vert 1.0005 \vert 0.326322 \vert 0.326006 \vert 1.0010$				
$\overline{4}$	$\vert 0.146485 \vert 0.146407 \vert 1.0005 \vert 0.157324 \vert 0.157196 \vert 1.0008$				
5	$\vert 0.039743 \vert 0.039722 \vert 1.0005 \vert 0.042491 \vert 0.042464 \vert 1.0006$				

Table 5-2: Configuration #1 - lateral core translation (m)

max linear error = 0.05 max nonlinear error = 0.12

Top of	Linear	Linear			Linear Nonlinear Nonlinear Nonlinear	
Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
1		$\left[0.002554\right]0.002553\left[1.0004\right]0.002767\left[0.002763\right]$				1.0015
2		$\left[0.002473\right]0.002472\left[1.0004\right]0.002678\left[0.002675\right]$				1.0013
3		$[0.002175] 0.002174 [1.0006] 0.002353 [0.002350]$				1.0011
$\overline{4}$		$\vert 0.001672 \vert 0.001671 \vert 1.0005 \vert 0.001803 \vert 0.001801 \vert$				1.0008
5		$[0.000930]$ 0.000929 $[1.0007]$ 0.000997 $[0.000996]$				1.0005

Table 5-3: Configuration #1 - core rotation (rad)

max linear error = 0.07% max nonlinear error = 0.15%

	Megacolumn A			Megacolumn B		
					Top of SSAM Sframe Ratio SSAM Sframe Ratio	
					$[0.0000 \ 0.0000 \ 1.000] 0.0000 \ 0.0000 \ 1.000]$	
2					$[0.0000 \ 0.0000 \ 1.000] 0.0000 \ 0.0000 \ 1.000]$	
$\overline{3}$					$[0.0000 \ 0.0000 \ 1.000] 0.0000 \ 0.0000 \ 1.000$	
$\overline{4}$					$\big 0.0000\ 0.0000\ 1.000\big 0.0000\ 0.0000\ 1.000$	
5					0.0000 0.0000 1.000 0.0000 0.0000 1.000	

Table 5-4: Configuration #1 - vertical megacolumn translation minus vertical core translation

max error $= 0.00\%$

Table 5-5: Configuration #1 - core stress (KPa)

Bottom of Interval	SSAM	Sframe	Ratio
	7128.8693	7127.8425 1.0001	
2		10325.5788 10321.9861 1.0003	
3		12330.3395 12324.8866 1.0004	
		15100.3036 15091.9960 1.0006	
$\overline{\mathcal{L}}$		16965.2776 16961.2986 1.0002	

max error $= 0.06\%$

		Megacolumn A		Megacolumn B		
Bottom of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
1		5622.3807 5642.2829 0.9965 5654.9521 5680.3098 0.9955				
2		7184.8934 7229.1492 0.9939 7278.0048 7337.1414 0.9919				
$\overline{3}$		8010.7539 8062.0372 0.9936 8173.9692 8242.4494 0.9917				
$\overline{4}$		9375.9937 9452.1382 0.9919 9624.9249 9726.8335 0.9895				
5		10301.7301 10301.6533 1.0000 10634.8049 10634.4231 1.0000				

Table 5-6: Configuration #1 - megacolumn stress (KPa)

		Megacolumn C		Megacolumn D		
Bottom of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
		5654.9521 5681.6678 0.9953 5654.9521 5681.6678 0.9953				
2		7278.0048 7337.4124 0.9919 7278.0048 7337.4124 0.9919				
3		8173.9692 8242.8105 0.9916 8173.9692 8242.8105 0.9916				
$\overline{4}$		9624.9249 9727.1394 0.9895 9624.9249 9727.1394 0.9895				
5		10634.8049 10634.7010 1.0000 10634.8049 10634.7010 1.0000				

max error $= 1.05\%$

Figure 5-1: Configuration #1 - lateral displacement and interstory drift

5.2 **Configuration #2 – core+megacolumns+outriggers**

Interval						Core t Outrig V Belt V Diag V Megaolumn A Megaolumns B/D Megaolumns C/E	
	(m)	m^3	(m^3)	m^{3}	Area (m^2)	Area (m^2)	Area (m^2)
	0.2			0	0.6927	1.2483	1.2483
$\overline{2}$	0.3	39			1.0353	1.8792	1.8656
3	0.5	65			1.7208	3.1406	3.1008
$\overline{4}$	0.7	78			2.4045	4.4051	4.3329
		58			3.4332	6.2962	6.1866

Table 5-7: Configuration #2 - design variables and calculated megacolumn areas

Table 5-8: Configuration #2 - lateral core translation (m)

Top of Interval	SSAM	Sframe	Ratio
		0.693383 0.692891 1.0007	
2		0.491356 0.491007 1.0007	
3		$0.306254 \mid 0.306038 \mid 1.0007$	
$\overline{4}$		0.152420 0.152315 1.0007	
ς		$0.043712 \mid 0.043683 \mid 1.0007$	

max error $= 0.07\%$

Table 5-9: Configuration #2 - core rotation (rad)

Top of	SSAM	Sframe	Ratio
Interval			
		0.002577 0.002576 1.0005	
2		$0.002375 \mid 0.002373 \mid 1.0007$	
3		0.002066 0.002065 1.0006	
$\overline{4}$		0.001599 0.001598 1.0009	
ς		$0.000945 \mid 0.000944 \mid 1.0011$	

max error $= 0.11\%$

	Megaolumn A			Megaolumn B		
					Top of SSAM Sframe Ratio SSAM Sframe Ratio	
1					0.0000 0.0000 1.0000 0.0532 0.0531 1.0007	
2					$[0.0000 \ 0.0000 \ 1.0000] 0.0532 \ 0.0531 \ 1.0007]$	
3					0.0000 0.0000 1.0000 0.0454 0.0453 1.0007	
$\overline{4}$					0.0000 0.0000 1.0000 0.0328 0.0327 1.0007	
5					0.0000 0.0000 1.0000 0.0160 0.0160 1.0007	

Table 5-10: Configuration #2 - vertical megacolumn translation minus vertical core translation

max error $= 0.07\%$

Table 5-11: Configuration #2 - core stress (KPa)

Bottom of Interval	SSAM	Sframe	Ratio
		15222.8996 15222.3633 1.0000	
$\mathcal{D}_{\mathcal{L}}$		21864.9112 21865.3745 1.0000	
3		21975.7891 21977.1556 0.9999	
4		23249.1280 23247.5511 1.0001	
5		23745.7850 23742.1704 1.0002	

max error = 0.02%

max error = 0.65%

Table 5-13: Configuration #2 - outrigger stress under lateral load only (KPa)

		R				
Top of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
$\mathcal{D}_{\mathcal{L}}$					44984.3482 44953.9263 1.0007 22492.1741 22477.7412 1.0006	
3					45745.6419 45710.9210 1.0008 22872.8209 22855.8147 1.0007	
4					52494.2377 52457.3896 1.0007 26247.1189 26229.1351 1.0007	
5					55408.6325 55373.9057 1.0006 27704.3162 27687.3060 1.0006	

max error $= 0.08\%$

Figure 5-2: Configuration #2 - lateral displacement and interstory drift

5.3 **Configuration #3 – core+megacolumns+belts**

Top of Interval	SSAM	Sframe	Ratio
		0.704044 0.699316 1.0068	
2		0.517826 0.514667	1.0061
\mathcal{R}	0.341883	0.34002	1.0055
4	0.182970	0.182244	1.0040
$\overline{\mathcal{L}}$		0.056885 0.056722	1.0029

Table 5-15: Configuration #3 - lateral core translation (m)

max error $= 0.68\%$

Table 5-16: Configuration #3 - core rotation (rad)

Top of Interval	SSAM	Sframe	Ratio
		0.002380 0.002360 1.0084	
$\overline{2}$		0.002177 0.002171 1.0028	
3		0.002035 0.002032 1.0014	
4		$0.001713 \mid 0.001713 \mid 0.9998$	
$\overline{\mathcal{L}}$		0.001237 0.001235 1.0019	

max error $= 0.84\%$

	Megacolumn A		Megacolumn B	
			Top of SSAM Sframe Ratio SSAM Sframe Ratio	
$\mathbf{1}$			0.0411 0.0413 0.9960 0.0367 0.0369 0.9948	
2			$\left 0.0411 \right 0.0411 \left 1.0006 \right 0.0367 \left 0.0367 \right 1.0003$	
3			0.0360 0.0360 1.0015 0.0313 0.0313 1.0020	
$\overline{4}$			0.0260 0.0259 1.0034 0.0212 0.0211 1.0045	
5			0.0124 0.0124 1.0015 0.0094 0.0094 1.0002	

Table 5-17: Configuration #3 - vertical megacolumn translation minus vertical core translation

max error = 0.56%

Table 5-18: Configuration #3 - core stress (KPa)

Bottom of	SSAM	Sframe	Ratio
Interval			
		15222.8996 14755.1687 1.0317	
2		20687.4577 20126.3594 1.0279	
3		25164.8733 24542.8792 1.0253	
4		24475.7970 23895.0744 1.0243	
5		29080.7494 29051.5824 1.0010	

max error $= 3.17\%$

		Megacolumn A		Megacolumn B		
Bottom of	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
Interval						
		11364.7174 11192.4457 1.0154 11416.2780 10839.4043 1.0532				
2		18530.1441 18352.4852 1.0097 18786.8899 18355.1234 1.0235				
3		23964.7985 23781.4997 1.0077 24128.3034 23770.5900 1.0150				
$\overline{4}$		24842.0815 24586.8684 1.0104 24041.3592 23755.9853 1.0120				
		24518.0750 24515.2250 1.0001 23192.4124 23200.8980 0.9959				

Table 5-19: Configuration #3 - megacolumn stress (KPa)

		Megacolumn C		Megacolumn D		
Bottom of	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
Interval						
					11416.2780 10842.9054 1.0529 11416.2780 10842.9045 1.0529	
$\overline{2}$					18825.0708 18396.9926 1.0233 17297.8410 16867.5663 1.0255	
$\overline{3}$					24076.7192 23722.7410 1.0149 21464.9875 21106.5570 1.0170	
$\overline{4}$					23649.9418 23357.7009 1.0125 21225.5716 20940.8840 1.0136	
5					22796.1558 22801.6575 0.9998 21000.2127 21008.4266 0.9996	

max error $= 5.32\%$

Table 5-20: Configuration #3 - belt truss stress under lateral load only (KPa)

		AB		BC			
Top of	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio	
Interval							
2		34091.8555 34100.2843 0.9998 11462.0951 11464.4492 0.9998					
3		36617.7339 36862.7669 0.9934 12008.4000 12039.1857 0.9974					
4		37160.7101 37498.0444 0.9910 11270.3162 11456.9165 0.9837					
5		23372.9232 24320.5346 0.9610 5669.7787 6002.3570 0.9446					

		AD.		DE		
Top of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
2		46071.0865 46434.0904 0.9922 57218.1212 57581.8362 0.9937				
3		51061.3895 52528.7085 0.9721 64111.4385 65809.9134 0.9742				
4		57366.3489 60005.8780 0.9560 73373.8281 76281.9196 0.9619				
		65316.2096 67916.3240 0.9617 78480.1129 80588.9503 0.9738				

max error $= 5.54\%$

Figure 5-3: Configuration #3 - lateral displacement and interstory drift

5.4 **Configuration #4 – core+megacolumns+diagonals**

						Core t Outrig Belt V Diag V Megacolumn A Megacolumns B/D Megacolumns C/E	
Interval m		'n	m^3	(m^3)	Area $(m2)$	Area (m^2)	Area $(m2)$
	0.1			43	0.3021	0.5369	0.5369
$\overline{2}$	0.2			214	0.4718	0.8184	0.8184
3	0.4			255	1.1710	2.0082	2.0082
4	0.5			301	1.5033	2.5575	2.5575
	0.7			35	2.5503	4.3708	4.3708

Table 5-21: Configuration #4 – design variables and calculated megacolumn areas

Top of Interval	SSAM	Sframe	Ratio
		0.700961 0.701863 0.9987	
2	0.504953	0.506065 0.9978	
3	0.326486	0.32738	0.9973
$\overline{4}$		0.172002 0.172012	0.9999
ς		0.054124 0.053793	1.0061

Table 5-22: Configuration #4 - lateral core translation (m)

Table 5-23: Configuration #4 - core rotation (rad)

max error $= 0.96\%$

Table 5-24: Configuration #4 - vertical megacolumn translation minus core vertical translation

	Megacolumn A		Megacolumn B	
			Top of SSAM Sframe Ratio SSAM Sframe Ratio	
			0.0524 0.0513 1.0224 0.0497 0.0479 1.0380	
2			0.0498 0.0489 1.0194 0.0475 0.0457 1.0390	
3			0.0420 0.0419 1.0041 0.0389 0.0376 1.0357	
$\overline{4}$			0.0316 0.0318 0.9958 0.0283 0.0276 1.0249	
5			0.0166 0.0179 0.9265 0.0126 0.0123 1.0212	

	Megacolumn C	Megacolumn D		
			Top of SSAM Sframe Ratio SSAM Sframe Ratio	
			0.0488 0.0463 1.0535 0.0257 0.0251 1.0234	
2			0.0467 0.0440 1.0622 0.0246 0.0239 1.0260	
$\overline{3}$			0.0379 0.0354 1.0713 0.0205 0.0200 1.0247	
$\overline{4}$			0.0272 0.0255 1.0634 0.0152 0.0150 1.0125	
5			0.0115 0.0109 1.0588 0.0072 0.0068 1.0634	

max error $= 7.35\%$

Table 5-25: Configuration #4 - core stress (KPa)

Bottom of Interval	SSAM	Sframe	Ratio
		24491.3087 24076.1019 1.0172	
2		24652.5844 23783.7907 1.0365	
3		20901.6996 20278.8252 1.0307	
		24710.9186 24565.4534 1.0059	
		30260.4110 30190.1385 1.0023	

max error $= 3.65\%$

max error $= 17\%$

		AB		BC		
Bottom of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
$\mathbf{1}$	81313.2121			97191.2950 0.8366 53515.7579 53745.4289 0.9957		
2	78286.8973			64893.0101 1.2064 70972.4314 66846.3767 1.0617		
$\overline{3}$	62204.8291			57484.1797 1.0821 63507.8966 58387.9340 1.0877		
$\overline{4}$	64801.9911			36811.8336 1.7604 79792.3507 72844.7126 1.0954		
5	83113.2553			80962.9631 1.0266 75733.4648 68248.1244		1.1097

Table 5-27: Configuration #4 - diagonal stress (KPa)

max error $= 76\%$

Figure 5-4: Configuration #4 - lateral displacement and interstory drift

5.5 **Configuration #5 – core+megacolumns+outriggers+belts**

Top of Interval	SSAM	Sframe	Ratio
		0.637650 0.637058 1.0009	
2		$0.465645 \mid 0.465354 \mid 1.0006 \mid$	
3		0.303810 0.303700 1.0004	
$\overline{4}$		$0.159402 \mid 0.159369 \mid 1.0002 \mid$	
5		0.049382 0.049371 1.0002	

Table 5-29 Configuration #5: - lateral core translation (m)

Table 5-30: Configuration #5 - core rotation (rad)

Top of Interval	SSAM	Sframe	Ratio
		$0.002202 \mid 0.002198 \mid 1.0019$	
$\mathcal{D}_{\mathcal{L}}$		0.001999 0.001999 1.0002	
\mathcal{E}		0.001860 0.001860 0.9999	
4		0.001525 0.001526 0.9994	
ς		0.001023 0.001024 0.9993	

max error $= 0.19\%$

max error $= 0.09\%$

	Megacolumn A			Megacolumn B		
Top of SSAM Sframe Ratio SSAM Sframe Ratio						
					0.0434 0.0435 0.9970 0.0438 0.0437 1.0019	
2					0.0434 0.0433 1.0022 0.0438 0.0438 0.9989	
3					$\vert 0.0371 \vert 0.0369 \vert 1.0035 \vert 0.0393 \vert 0.0394 \vert 0.9984 \vert$	
$\overline{4}$					0.0254 0.0253 1.0046 0.0301 0.0302 0.9983	
5					$\vert 0.0131 \vert 0.0130 \vert 1.0051 \vert 0.0170 \vert 0.0170 \vert 0.9985 \vert$	

Table 5-31: Configuration #5 - vertical megacolumn translation minus core vertical translation

Max error $= 0.79\%$

Table 5-32: Configuration #5 - core stress (KPa)

Bottom of	SSAM	Sframe	Ratio
Interval			
		15222.8996 14754.8100 1.0317	
\mathcal{D}_{\cdot}		20722.3915 20143.2498 1.0288	
3		25345.5702 24983.7534 1.0145	
		24767.1003 24608.8396 1.0064	
$\overline{\mathcal{L}}$		30466.8330 30469.8923 0.9999	

max error $= 3.17\%$

max error $= 5.04\%$

Table 5-34: Configuration #5 - outrigger stress under lateral load only (KPa)

Top of	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
Interval						
2	45035.2256 44577.5789 1.0103 18919.8601 18665.0165 1.0137					
3		51945.4870 51564.8600 1.0074 23095.2281 22900.8217 1.0085				
4		58063.3030 57824.4431 1.0041 27352.3210 27226.2807 1.0046				
		62190.0087 62060.0618 1.0021 30264.2007 30193.9614 1.0023				

max error $= 1.37\%$

	AB			BC		
Top of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
$\mathcal{D}_{\mathcal{L}}$					3232.7632 3017.2696 1.0714 33405.4233 34238.7440 0.9757	
3					17629.0634 17844.8855 0.9879 51982.8703 52978.4759 0.9812	
4					136793.7220 36402.7207 1.0107 67828.6849 67465.0595 1.0054	
5					30804.0766 31010.3883 0.9933 49485.4582 50678.8492 0.9765	

Table 5-35: Configuration #5 - belt truss stress under lateral load only (KPa)

	AD			DE		
Top of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
$\mathcal{D}_{\mathcal{L}}$					31137.7201 33000.5671 0.9436 20216.3696 22017.0424 0.9182	
3					48456.3261 51825.2521 0.9350 24677.8604 27699.4054 0.8909	
$\overline{4}$					69609.2164 73130.1273 0.9519 29226.6765 33110.0471 0.8827	
					64917.6447 67511.1317 0.9616 32338.0968 36489.2712 0.8862	

max error $= 11.7\%$

Figure 5-5: Configuration #5 - lateral displacement and interstory drift

5.6 **Configuration #6 – core+megacolumns+outriggers+belts+diagonals**

						Core t Outrig V Belt V Diag V Megacolumn A Megacolumns B/D Megacolumns C/E	
Interval	(m)	m ²	m	m^2	Area (m^2)	Area (m^2)	Area (m^2)
	0.1	0		12	0.3341	0.5998	0.5998
$\overline{2}$	0.2	37	37	θ	0.7010	1.2625	1.2535
3	0.4	56	33	θ	1.4023	2.5350	2.5054
4	0.5	67			1.7479	3.1721	3.1249
	0.7	57		θ	2.4408	4.4394	4.3676

Table 5-36: Configuration #6 – design variables and calculated megacolumn areas

Table 5-37: Configuration #6 - lateral core translation (m)

Top of Interval	SSAM	Sframe	Ratio
		0.695754 0.695147 1.0009	
2		$0.500956 \mid 0.500729 \mid 1.0005$	
3		$0.322717 \mid 0.322649 \mid 1.0002$	
$\overline{4}$		$0.168275 \mid 0.168239 \mid 1.0002$	
5		0.050341 0.050327 1.0003	

max error $= 0.09\%$

Table 5-38: Configuration #6 - core rotation (rad)

Top of	SSAM	Sframe	Ratio	
Interval				
		0.002507 0.002501 1.0022		
2		0.002199 0.002199 0.9998		
3		0.001977 0.001979 0.9991		
4		0.001659 0.001659 0.9997		
ς		$0.001047 \mid 0.001047 \mid 1.0002$		

max error $= 0.22\%$

	Megacolumn A			Megacolumn B		
	Top of SSAM Sframe Ratio SSAM Sframe Ratio					
	$\left[0.0503\right]$ 0.0506 0.9946 0.0484 0.0483 1.0021					
2	$\left 0.0486\right 0.0485\left 1.0033\right 0.0486\left 0.0487\right 0.9974$					
$\overline{3}$	$\left[0.0394\right.00392\left.1.0050\right 0.0419\left.0.0420\right.0.9976\right]$					
$\overline{4}$					0.0273 0.0271 1.0050 0.0328 0.0329 0.9982	
5					0.0122 0.0122 1.0038 0.0173 0.0173 0.9992	

Table 5-39: Configuration #6 - vertical megacolumn translation minus vertical core translation

max error $= 1.07\%$

Table 5-40: Configuration #6 - core stress (KPa)

Bottom of	SSAM	Sframe	Ratio
Interval			
		27387.9184 26620.0518 1.0288	
\mathcal{D}_{\cdot}		29424.0492 28598.3007 1.0289	
3		24363.6381 24021.8767 1.0142	
		28732.2483 28628.6999 1.0036	
5		29877.1437 29878.9769 0.9999	

max error $= 2.89\%$

max error $= 4.97\%$

Table 5-42: Configuration #6 - outrigger stress under lateral load only (KPa)

Top of	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
Interval						
2		46261.5351 45510.2512 1.0165 19093.0546 18564.0411 1.0285				
3		54787.1379 54326.4558 1.0085 24328.4516 24070.2618 1.0107				
4		62792.5224 62541.1241 1.0040 29685.5489 29536.8798 1.0050				
		64374.0247 64284.4537 1.0014 31554.6433 31492.5186 1.0020				

max error $= 2.85\%$

Table 5-43: Configuration #6 - belt truss stress under lateral load only (KPa)

	AB			BC		
Top of	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
Interval						
2		242.9812 2937.2585 0.0827 30852.7526 34012.3290 0.9071				
3		19429.7002 20427.1005 0.9512 56116.9603 58352.3398 0.9617				
$\overline{4}$	43192.0741 42899.3472 1.0068 75696.5409 75563.9430 1.0018					
5		39531.7217 39606.8331 0.9981 56116.1896 57445.9654 0.9769				

max error $= 91.7\%$

Table 5-44: Configuration #6 - diagonal stress (KPa)

	ΑB			ВC		
Bottom of Interval	SSAM	Sframe	Ratio	SSAM	Sframe	Ratio
	69067.7863 55893.0411 1.2357 74604.5230 59454.8293 1.2548					

max error $= 25.5\%$

Figure 5-6: Configuration #6 - lateral displacement and interstory drift

5.7 **Configuration #7 – core+megacolumns+outirgger at one level only**

Top of Interval	SSAM	Sframe	Ratio
		0.940770 0.939826 1.0010	
2		0.737032 0.736291	1.0010
3		$0.505269 \mid 0.504765 \mid 1.0010$	
4		0.256719 0.256467	1.0010
$\overline{\mathcal{L}}$		0.071406 0.071338	1.0010

Table 5-46: Configuration #7 - lateral core translation (m)

max error $= 0.10\%$

Table 5-47: Configuration #7 - core rotation (rad)

Top of Interval	SSAM	Sframe	Ratio
		0.002599 0.002596 1.0011	
$\overline{2}$		0.002396 0.002394 1.0008	
3		0.003211 0.003208 1.0011	
4		0.002822 0.002819 1.0011	
5		0.001637 0.001636 1.0009	

max error $= 0.11\%$

	Megacolumn A			Megacolumn B		
Top of SSAM Sframe Ratio SSAM Sframe Ratio						
					0.0000 0.0000 1.0000 0.0529 0.0528 1.0010	
2					0.0000 0.0000 1.0000 0.0529 0.0528 1.0010	
$\overline{\mathbf{3}}$					0.0000 0.0000 1.0000 0.0302 0.0302 1.0010	
$\overline{4}$					0.0000 0.0000 1.0000 0.0166 0.0166 1.0010	
$5\overline{)}$					0.0000 0.0000 1.0000 0.0068 0.0068 1.0011	

Table 5-48: Configuration #7 - vertical megacolumn translation minus vertical core translation

 $\overline{}$

max error $= 0.11\%$

Figure 5-7: Configuration #7 - lateral displacement and interstory drift

6 CONCLUSIONS

The SSAM was developed, implemented, and tested. The SSAM was able to predict the existence of points of contraflexure in the deflected shape of configurations involving outriggers, belts, and diagonals, as verified by the space frame model. Such points of contraflexure cannot be predicted with continuum models.

The accuracy of the SSAM was compared against the space frame model. For all configurations that exclude diagonals, the maximum error was 1% for linear and nonlinear lateral translations, 1% for linear and nonlinear rotations, and 1% for vertical translations. Furthermore, the maximum error in stress was 3% for the core, 3% for the megacolumns, 1% for outriggers, and 12% for belts. For configurations that included diagonals, the maximum error was 1% for linear lateral translations, 1% for linear rotations, and 7% for vertical translations. Additionally, the maximum error in stress was 4% for the core, 17% for the megacolumns, 3% for the outriggers, 92% for the belts, and 76% for the diagonals. Thus, the accuracy of the SSAM is very good for translations and rotations, and reasonably good for stress in configurations that exclude diagonals. Stress formulas for configurations that include diagonals need further development.

The speed of execution, data preparation, data extraction, and optimization is much faster with the SSAM than with general space frame programs, both that of Balling (1991) and ADINA. Execution of the SSAM is instantaneous since it only involves 30 DOF's for the generic skyscraper. Execution of the space frame model of the generic skyscraper with 10,776

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DOF's on the space frame program from Balling (1991) required about 25 minutes on a computer. Preparation of data for the SSAM spreadsheet on a new skyscraper will take some time. But preparation/extraction of data for general space frame and finite element programs for a skyscraper involving 5668 members and 1877 nodes will take more time. Rapid trial-and-error optimization is possible with the SSAM spreadsheet, but not possible with general space frame and finite element programs. The SSAM appears to be ideal for preliminary skyscraper design and educational purposes for students learning about the behavior and design of modern skyscrapers.

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APPENDIX A. SSAM EXCEL SPREADSHEET (CONFIGURATION #6)

The SSAM was executed on an Excel spreadsheet. A typical spreadsheet has five sheets:

1) Properties sheet, 2) Design sheet, 3) Matrices sheet, 4) Lateral sheet, and 6) Stress sheet. An

example will follow with Configuration #6.

Properties Sheet

Stress Sheet

