



Brigham Young University  
BYU ScholarsArchive

---

Theses and Dissertations

---

1984-12-01

## Application of Combined Jointed Media and Discrete Slip Plane Characteristics to Subsidence Predictions

David W. Basinger  
*Brigham Young University - Provo*

Follow this and additional works at: <https://scholarsarchive.byu.edu/etd>



Part of the Civil and Environmental Engineering Commons

---

### BYU ScholarsArchive Citation

Basinger, David W., "Application of Combined Jointed Media and Discrete Slip Plane Characteristics to Subsidence Predictions" (1984). *Theses and Dissertations*. 3450.

<https://scholarsarchive.byu.edu/etd/3450>

This Thesis is brought to you for free and open access by BYU ScholarsArchive. It has been accepted for inclusion in Theses and Dissertations by an authorized administrator of BYU ScholarsArchive. For more information, please contact [scholarsarchive@byu.edu](mailto:scholarsarchive@byu.edu), [ellen\\_amatangelo@byu.edu](mailto:ellen_amatangelo@byu.edu).

APPLICATION OF COMBINED JOINTED MEDIA  
AND DISCRETE SLIP PLANE CHARACTERISTICS  
TO SUBSIDENCE PREDICTIONS

DAVID W. BASINGER

APPLICATION OF COMBINED JOINTED MEDIA  
AND DISCRETE SLIP PLANE CHARACTERISTICS  
TO SUBSIDENCE PREDICTIONS

A Thesis  
Presented to the  
Department of Civil Engineering  
Brigham Young University

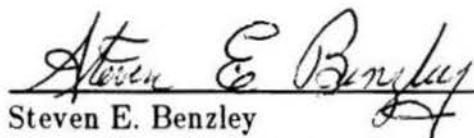
In Partial Fulfillment  
of the Requirements for the Degree  
Master of Science

by

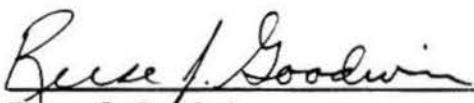
David W. Basinger

December 1984

This Thesis, by David W. Basinger, is accepted in its present form  
by the Department of Civil Engineering of Brigham Young University as  
satisfying the thesis requirement for the degree of Master of Science.



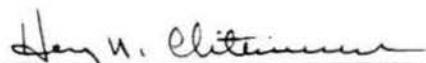
Steven E. Benzley  
Committee Chairman



Reese J. Goodwin  
Committee Member

4 SEPTEMBER 84

Date



Henry N. Christiansen  
Department Chairman

## **TABLE OF CONTENTS**

Acknowledgements .....	iv
List of Figures .....	v
Chapter	
1. INTRODUCTION .....	1
2. SUBSIDENCE PREDICTION .....	3
Background Information .....	3
Methods of Prediction .....	3
Current Research .....	6
3. LOW SHEAR AND JOINTED MEDIA THEORY .....	8
Low Shear Theory .....	9
Jointed Media Theory .....	11
4. MODEL VERIFICATION .....	21
Centrifuge Model .....	21
Finite Element Models .....	27
Comparisons .....	33
5. CONCLUSIONS AND RECOMMENDATIONS .....	42
BIBLIOGRAPHY .....	47
APPENDIX	
A. SCRUBS.BYU - Subroutine map and descriptions .....	51
B. SCRUBS.BYU - User's Manual .....	59

C. SCRUBS.BYU - Code Listing .....	74
D. Additional Subsidence Results. ....	199
E. Selected Files. ....	203

## **ACKNOWLEDGEMENTS**

I wish to express my appreciation to Dr. Steven E. Benzley for his patient help in the preparation of this thesis, for providing this research opportunity, and for his expert advice. Appreciation goes also to Royd R. Nelson and Randy Nish, who helped me get started, and to the Brigham Young University Department of Civil Engineering for providing software, hardware, graphical aids, and moral support. Above all, love, appreciation and thanks go to the my wife, Janette, for her patience, understanding and overwhelming confidence through many long hours.

## **CHAPTER ONE**

### **INTRODUCTION**

Ground settlement, also called subsidence, has increased in significance as the use of longwall mining and underground coal gasification have become more prominent. Many methods have been used to predict the amount of subsidence that may occur. These include empirical methods, physical models, and numerical models. This thesis investigates the use of finite element material modeling to incorporate slippage planes in the analysis of subsidence problems.

Chapter two of this thesis reviews current research in finite-element numerical simulations of subsidence predictions. The area emphasized is the ability to incorporate fractures and joints in rock mechanics problems.

In chapter three, the theory behind two methods of modeling fractures in finite element technique is presented. Low shear theory is presented as the first method. Among the items discussed in low shear theory are: (1) the incorporation of low shear slip planes into the model, (2) the formulation of the low shear, and (3) the installation of a low shear element row into the model. The second method used to modeling fractures is to model the material as a jointed media continuum. In this section, the topics are: (1) the approximation of the media as a continuum, (2) the formulation of a constitutive model, (3) the assumptions of model behavior,

and (4) the solution of the constitutive equations. Three basic assumptions are included in the jointed media formulation. These involve: (1) the behavior of intact material, (2) the neglection of joint dilatation, and (3) the behavior of joint shear.

In chapter four, various models used to predict subsidence in a coal mine problem are shown. First, a physical centrifuge model carried out at Sandia National Laboratories is described in detail. The results of this model are also given. Second, several numerical models set up and analyzed using the SCRUBS.BYU finite element program are described. Included in the descriptions are: (1) the equipment used, (2) the construction of the model, (3) the dimensions of the model, (4) the materials used, (5) the creation of the subsurface cavity, and (6) the results of selected runs. Finally, comparisons are made between the models.

In chapter five, conclusions are made and recommendations listed. The successes, the problems, and the proposed solution to these problems are presented.

In the attached appendices, a current listing of the program SCRUBS.BYU is provided. Also included are a subroutine map, a short description of each subroutine, additional results of simulation runs, and sample files used in the simulations.

## CHAPTER TWO

### SUBSIDENCE PREDICTION

#### **Background Information**

The collapse of the earth at the surface, called surface subsidence, can seriously effect ground water, surface hydrology, and surface structures. The mining of natural resources, especially of coal, can result in significant amounts of subsidence that in turn can cause significant damage.

Consequently, accurate subsidence prediction is of great interest to mining engineers. Recently, increased use of longwall mining techniques and increased research in underground coal gasification have heightened the concern in predicting the behavior of rocks and soils subject to mining stresses [17]. Longwall mining and in-situ (underground) coal gasification are often preferred as methods that maximize resource removal, as both of these methods have the result that all the coal in a seam is removed. The result is, of course, the total collapse of the area above the mined region and the resulting subsidence of all overlying strata. This is in contrast to the older mining method of room and pillar mining, where pillars of coal were left behind to support the mine roof.

#### **Methods of Prediction**

**Historical methods.** Empirical methods have historically been used to predict surface subsidence [3,14]. These methods are based mostly

on engineering judgement and require a large data base from which to derive the design formulas. In Europe, where empirical methods have long been used, many records exist that provide a long history from which to gather a sufficient data base. In the United States such a data base does not usually exist and alternative methods are sought. Methods that have been investigated include both physical and numerical models. It has been shown that mutual enhancement can occur when both physical and numerical models are applied to subsidence problems [19]. In this thesis, physical and numerical methods are applied to a subsidence problem in an effort to obtain the additional understanding that this mutual enhancement can afford.

**Physical methods.** A centrifuge can be used to physically simulate mining subsidence. Subsidence above a mine is caused primarily by the force of gravity. Gravity interacting with the mine geometry, the material properties of the rock and soil, and the natural ground movement of the area, creates a stress field in the overburden. For an accurate model, the stress field in the full-size structure must be duplicated in the reduced-scale model. To do that, the force of gravity can be increased in the same proportion that the model has been reduced in scale. A centrifuge can be used to apply these greater-than-gravity loads to the scaled model. For example, a coal mine at a depth of 100 m below ground level can be simulated by a scale model only 1 m high and constructed from representative site materials by loading the scaled model in a centrifuge to 100 times the acceleration of gravity (g's).

**Numerical methods.** Numerical models have increased in use with the onset of the computer, and the corresponding increase in computational power, speed, and accuracy. Many numerical approaches to subsidence prediction have been used [1,7,13,22,23]. One important numerical technique is called the finite element technique.

The finite element technique is a numerical method that has been adapted to modeling geologic materials. The nonhomogeneity of soil and rocks make their modeling intrinsically complicated and uncertain. Material properties are often vague. The presence of cracks and fissures increase the complexity and difficulty of predicting the behavior of geologic materials. As a result, numerical simulations of geologic materials have almost necessarily involved major idealizations and simplifications involving the material properties and the effect of fractures and joints on subsidence mechanics.

While accurately determining soil properties will always be a problem, determining the location of cracks and joints and incorporating their effects into a numerical model leads to better and more accurate predictions of soil and rock mechanics problems. Many finite element codes have incorporated joints and fractures into their analysis by adding sliding interfaces or slip planes, with the usual result that computation time has increased dramatically [16]. At Brigham Young University, several unique geologic modeling techniques have been included in a finite element program called SCRUBS.BYU.

## Current Research

**The computer code SCRUBS.BYU.** SCRUBS.BYU is a two-dimensional, elastic-plastic finite element computer program developed to analyze resource extraction problems resulting in significant surface subsidence [9]. SCRUBS.BYU can model the subsidence process associated with either longwall coal mining or in-situ coal gasification. Of special interest in SCRUBS.BYU'S subsidence formulations are the abilities to model failure and rubbleization, to mine elements, and to incorporate joints and cracks.

**Fracture modeling.** In 1983 Royd Nelson, a master's candidate at Brigham Young University, incorporated joints, cracks, and fractures into SCRUBS.BYU [16]. Two separate crack definitions were used. In the first, a discrete crack model was used, and in the other a continuum approach defining a new material with regularly spaced joints was used. These capabilities were demonstrated by several simplified examples.

**Recommendations for future study.** Further study in this area could be made. Nelson specifically recommended that areas of future work include [16, p.56]:

- 1) Studying the effects of faults on a variety of geomechanical problems using the slip plane addition to model the faults.
- 2) Evaluating the effect of joints and fractures on problems where the rubble model available in SCRUBS.BYU is utilized.
- 3) Investigating plastic yielding of the low shear slip plane material, particularly with utilization of the Drucker- Prager failure criteria.

- 4) Performing experimental studies to determine single-joint slip responses in order to more accurately estimate the material constants that define the slip response.
- 5) Performing of large-scale tests to verify analytical calculations.

To some extent this thesis presents further study in each of the recommended areas except number 3. The investigation of plastic yielding and the Drucker-Prager failure criteria was deemed to be beyond the scope of this study.

**The Scope of this thesis.** This thesis is a continuation of Nelson's work to incorporate fracture modeling into the finite element code SCRUBS.BYU. Verification of the discrete slip plane and jointed media formulations is sought by their application to a physical model. In addition, the effort to combine discrete slip planes and jointed media continua in models will increase the understanding of numerical geologic materials modeling.

## CHAPTER THREE

### LOW SHEAR AND JOINTED MEDIA THEORY

#### **Low Shear Theory**

**Modeling with low shear element slip planes.** The modeling of joints and fractures has been incorporated into many finite element codes by using sliding interfaces or slip planes. The implementation of these interfaces into the codes involves complex formulations and often increases the computing time of these programs considerably. A slip plane formulation is part of the finite element computer code SCRUBS.BYU. In this program a "low shear element" slip plane was formulated. The low shear element slip plane has the advantages of being easy to implement and has a limited effect on the run time of the program. In this method, a thin row of elements is added into the model wherever a slip plane is desired, as shown in Figure 1. This thin row of elements is then defined as a low shear material. This formulation simply imposes regions of minimal shear resistance along the slip plane element row.

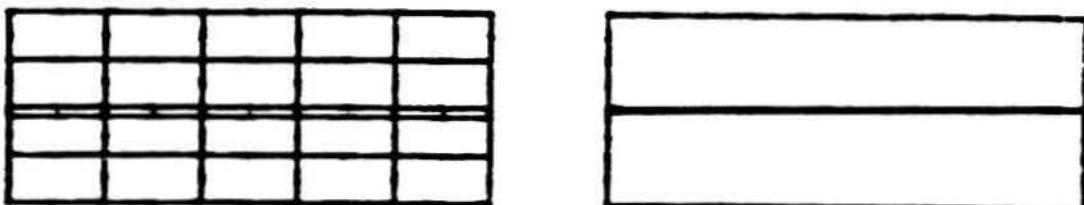


Figure 1. Low shear slip plane addition.

### The low shear formulation.

"In standard plane strain computer programs the relationship between stresses and strains is expressed as a generalized form of Hooke's law,

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} = \frac{E}{(1+\nu)(1-2\nu)} \begin{bmatrix} (1-\nu) & \nu & 0 \\ \nu & (1-\nu) & 0 \\ 0 & 0 & \frac{(1-2\nu)}{2} \end{bmatrix} \begin{Bmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \gamma_{xy} \end{Bmatrix}$$

Problems occur in this formulation. When Poisson's ratio becomes .5, division by zero occurs. Another disadvantage for a material that has little shear strength is that as the shear modulus G approaches zero, the modulus of Elasticity E also approaches zero and the equations for stress and strain break down.

In a manner similar to Clough and Woodward [4] we can circumvent the above problems by writing the stress strain relations in terms of the bulk modulus (K) and the shear modulus (G). Doing this,

$$\begin{Bmatrix} \sigma_{xx} \\ \sigma_{yy} \\ \sigma_{xy} \end{Bmatrix} = \begin{bmatrix} K + \frac{4}{3}G & K - \frac{2}{3}G & 0 \\ K - \frac{2}{3}G & K + \frac{4}{3}G & 0 \\ 0 & 0 & G \end{bmatrix} \begin{Bmatrix} \epsilon_{xx} \\ \epsilon_{yy} \\ \gamma_{xy} \end{Bmatrix}$$

where

$$K = \frac{E}{3(1-2\nu)}$$

$$G = \frac{E}{2(1+\nu)}$$

The above equation allows G to approach zero and still maintain a valid stress strain relationship." [2]

This formulation is incorporated in the SCRUBS.BYU program by entering the bulk modulus K as a negative number in place of Young's modulus, and by entering the shear modulus G in place of Poisson's ratio. The negative sign on the bulk modulus is a flag that causes the elasticity

matrix to be created using equation 3.2 rather than equation 3.1. To model a low shear material, the shear modulus is entered as a number low relative to the bulk modulus. As stated before, this formulation is not limited to use in low shear materials, but can be utilized any time the material is described by  $K$  and  $G$  rather than by  $E$  and  $\nu$ .

PRESCRUBS.BYU provides the capability to input low shear slip planes. A solution control parameter is required that indicates whether any slip planes exist. If so, the user is automatically prompted for the bulk and shear moduli for the slip plane material. Note that this formulation requires a separate boundary flag for each discrete slip plane.

**Addition of the slip plane element row.** The geometric modeling is done on an interactive mesh generator called QMESH.BYU. This program accepts the perimeter data for specified regions of the geometry, and automatically creates and numbers the finite element mesh. Boundary conditions are imposed by assigning flags to desired lines or line segments that can later (in PRESCRUBS.BYU) be coupled to specified displacement or force criteria. To define low shear element rows as described earlier, the user would have to enter perimeter data for each row. The SCRUBS.BYU program automatically creates this thin row of elements. Any line can be defined as a slip plane by simply assigning it a boundary flag in QMESH.BYU, thus saving considerable preprocessing time. (Readers not familiar with the use of QMESH.BYU should consult Reference 8.)

## Jointed Media Theory

**Modeling as jointed media.** A second method of modeling the effects of cracks and fractures in geologic materials is by using a material model for the jointed material based on continuum theory. In this method, joints in the materials are implemented by allowing for the effects of jointing on the material response rather than discrete models for each joint. This formulation is taken from work done by Thomas [21], but is modified neglecting joint dilatation response, and limited to only two dimensional or axisymmetric continua.

The model is composed of two parts: (1) a continuum approximation in which the joint displacements are averaged through the material, and (2) a continuum description based on linear behavior of the base material and nonlinear shear at the joints.

**The continuum approximation.** The continuum model used for this material is based on the published work of Moreland [10,11,12]. Consider a "representative elementary volume" containing regularly spaced parallel fractures as sketched in Figure 2. The orientation of this joint set is characterized by a unit normal vector  $\hat{n}$  with respect to fixed  $x_1$ ,  $x_2$ ,  $x_3$  coordinate axes. The spacing between fractures is denoted by  $\delta$ . Additional unit vectors  $\hat{s}$  and  $\hat{t}$  in the plane of the joints are introduced such that  $\hat{s}$ ,  $\hat{t}$ , and  $\hat{n}$  form a local Cartesian coordinate system.

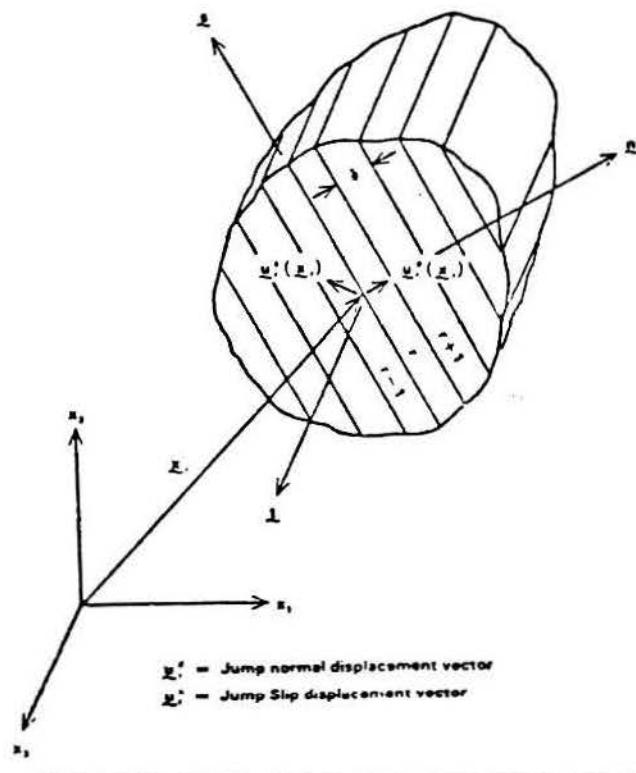


Figure 2. Representative elementary volume containing regularly spaced fractures.

It is assumed that the relative motion at the interface of the  $r$ th fracture at position  $x_r$  can be measured by a jump "dilatation" vector  $u_r^d(x_r)$  normal to the fracture plane, and a jump slip displacement vector  $u_r^s(x_r)$  parallel to the fracture plane. The net jump displacements for  $R$  fractures in the representative volume will then be

$$\begin{aligned} R\bar{\underline{u}}^d(\underline{x}) &= \sum_{r=1}^R \bar{u}_r^d(x_r) \\ R\bar{\underline{u}}^s(\underline{x}) &= \sum_{r=1}^R \bar{u}_r^s(x_r) \end{aligned} \quad (3.3)$$

where  $\bar{\underline{u}}^d$  and  $\bar{\underline{u}}^s$  are average displacements and  $\underline{x}$  is any position in the element. The continuous displacement fields  $\bar{\underline{u}}^d$  and  $\bar{\underline{u}}^s$  with respect to the  $x_1, x_2, x_3$  axes are introduced,

$$\begin{aligned} \bar{u}^d(\underline{x} + d\underline{n}) &= \bar{u}^d(\underline{x}) + \left( \frac{\bar{\underline{u}}^d}{\delta} \right) d\underline{n} \\ \bar{u}^s(\underline{x} + d\underline{n}) &= \bar{u}^s(\underline{x}) + \left( \frac{\bar{\underline{u}}^s}{\delta} \right) d\underline{n}, \end{aligned} \quad (3.4)$$

where

$$\begin{aligned} \bar{\underline{u}}^d &= |\bar{\underline{u}}^d| \underline{n} = \bar{u}^d \underline{n} \\ \bar{\underline{u}}^s &= |\bar{\underline{u}}^s| \underline{v} = \bar{u}^s \underline{v} \end{aligned} \quad (3.5)$$

In equation (3.5) the direction of slip displacement is in the direction of the unit vector  $\underline{s}$ . The total displacements can be written as

$$\bar{u}(\underline{x}) = \bar{u}^b(\underline{x}) + \bar{u}^d(\underline{x}) + \bar{u}^s(\underline{x}) \quad (3.6)$$

where  $\underline{u}^b$  is the displacement field of the intact material between fractures.

From equation (3.6), the strain decomposition is taken to be

$$\underline{\epsilon} \approx \underline{\epsilon}^b + \underline{\epsilon}^d + \underline{\epsilon}^s \quad (3.7)$$

The dilatation and slip strains are defined in terms of the continuous displacement,

$$2 \underline{\epsilon}^d = \underline{u}^d \nabla + (\underline{u}^d \nabla)^T$$

$$2 \underline{\epsilon}^s = \underline{u}^s \nabla + (\underline{u}^s \nabla)^T \quad (3.8)$$

where  $\nabla$  is the gradient operator with respect to the  $x_1, x_2, x_3$  axes.

Equation (3.8) can be reduced by decomposing  $\underline{u}^d$  and  $\underline{u}^s$  into components in the local coordinate system.

$$\underline{u}^d = |\underline{u}^d| \underline{n} = u^d \underline{n}$$

$$\underline{u}^s = |\underline{u}^s| \underline{v} = u_s^s \underline{s} \quad (3.9)$$

Since both  $\underline{u}^d$  and  $\underline{u}^s$  have nonzero gradients only in the  $\underline{n}$  direction, equation (3.8) becomes

$$\underline{\epsilon}^d \approx \frac{\partial u^d}{\partial n} (\underline{n} \times \underline{n})$$

$$\underline{\epsilon}^s \approx \frac{1}{2} \frac{\partial u_s^s}{\partial n} (\underline{s} \times \underline{n} + \underline{n} \times \underline{s}) \quad (3.10)$$

From equation (3.4)

$$\begin{aligned}\frac{\partial u^d}{\partial n} &= \frac{\bar{u}^d}{\delta} \\ \frac{\partial u^s}{\partial n} &= \frac{\bar{u}^s}{\delta}\end{aligned}\tag{3.11}$$

so the final form for the strains is

$$\begin{aligned}\approx e^d &= \frac{\bar{u}^d}{\delta} (n \times n) \\ \approx e^s &= \frac{\bar{u}^s}{2\delta} (s \times n + n \times s)\end{aligned}\tag{3.12}$$

**The constitutive model.** We will first introduce the components of a stress tensor  $\approx T$  and a total strain tensor  $\approx E$  which refer to the local  $s, t, n$  coordinate system. If  $\sigma$  and  $e$  are stress and strain tensors in the  $x_1, x_2, x_3$  coordinate system, the transformation equations are

$$\begin{aligned}T_{nn} &= \approx \sigma_n \cdot n \\ T_{ss} &= \approx \sigma_s \cdot s \\ T_{tt} &= \approx \sigma_t \cdot t \\ T_{ns} &= \approx \sigma_n \cdot s\end{aligned}\tag{3.13}$$

and

$$E_{nn} = \approx^e n \cdot n$$

$$E_{ss} = \approx^e s \cdot s$$

$$E_{tt} = \approx^e t \cdot t$$

$$E_{ns} = \approx^e n \cdot s \quad (3.14)$$

**The behavior of intact material.** In the present formulation, the intact material is assumed to behave as a linear elastic solid, having a strain rate

$$\dot{\epsilon}^b \approx = \frac{\dot{\sigma}}{2G} - \left( \frac{K - \frac{2}{3}G}{6KG} \right) (\text{tr } \dot{\sigma}) \approx \quad (3.15)$$

**Neglection of joint dilatation.** The main purpose of using this model is to predict the weakening effects of slip along fractures and joints in materials. For many problems the fracture opening is small relative to the fracture spacing. For these problems, the joint dilatation normal to the crack is also small for cracks in compression; therefore the dilatation response will be neglected; thus

$$\dot{\epsilon}^d \approx = 0 \quad (3.16)$$

The only condition imposed on the joint dilatation is that a joint cannot support a tensile load; therefore

$$T_{nn} = 0, \bar{u}^d \geq 0 \quad (3.17)$$

**The behavior assumption for joint shear.** The joint shear stress-displacement behavior is assumed to be elastic perfectly plastic. In the elastic range

$$\dot{\bar{u}}_s^s = \frac{\dot{T}_{ns}}{G_s} \quad (3.18)$$

where  $G_s$  is an elastic modulus of slip determined for a single joint. From equation (3.12) the slip strain rate is

$$\dot{\bar{e}}^s = \frac{\dot{T}_{ns}}{2\delta G_s} (\bar{s} \times \bar{n} + \bar{n} \times \bar{s}) \quad (3.19)$$

The onset of plastic behavior is assumed to be governed by a linear Mohr-Coulomb criterion, based on a scalar "slip function",  $F$ , defined as

$$F = |T_{ns}| + \mu T_{nn} - C_o \quad (3.20)$$

where  $\mu$  is the coefficient of friction and  $C_o$  is the cohesion. The joint behavior is elastic for  $F$  less than zero and plastic for  $F$  greater than zero. The stress-displacement behavior in shear is shown in Figure 3.

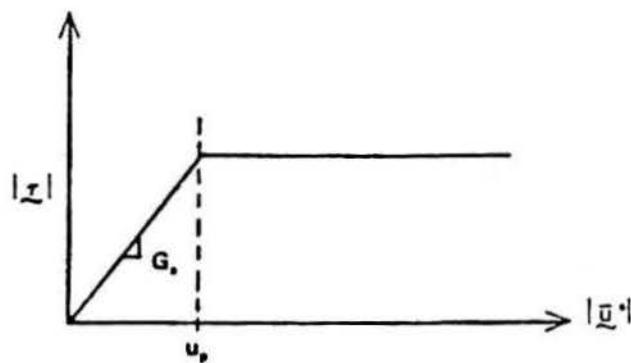


Figure 3. Assumed stress-displacement behavior in shear.

**The solution of the constitutive equations.** The SCRUBS.BYU finite element program uses an incremental method where the stresses and strains are known at the last stress increment, the current incremental strains are known, and only the current incremental stresses are needed.

From equation (3.7), the elastic strain rate can be defined as

$$\dot{\epsilon} \approx = \dot{\epsilon}^b \approx + \dot{\epsilon}^d \approx + \dot{\epsilon}^s \approx$$

Using the constitutive relations in equations (3.15), (3.16), and (3.19), the elastic strain rate [Eq 3.21] becomes

$$\dot{\epsilon} \approx = \frac{\dot{\sigma}}{2G} - \left( \frac{K - \frac{2}{3}G}{6KG} \right) (\text{tr} \dot{\epsilon} \approx) \approx + \frac{\dot{T}_{ns}}{2\delta G_s} (\underline{s} \times \underline{n} + \underline{n} \times \underline{s})$$

Transferring equation (3.22) to scalar equations in terms of the local stress components, and omitting the out-of-plane shears, we have

$$\begin{aligned}
 \dot{E}_{nn} &= \frac{\dot{T}_{nn}}{2G} - \left( K - \frac{2}{3}G \right) (\text{tr} \tilde{T}) \\
 \dot{E}_{ns} &= \left( \frac{1}{2G} + \frac{1}{2\delta G_s} \right) \dot{T}_{ns} \\
 \dot{E}_{ss} &= \frac{\dot{T}_{ss}}{2G} - \left( K - \frac{2}{3}G \right) (\text{tr} \tilde{T}) \\
 \dot{E}_{tt} &= \frac{\dot{T}_{tt}}{2G} - \left( K - \frac{2}{3}G \right) (\text{tr} \tilde{T})
 \end{aligned} \tag{3.23}$$

Solving for incremental stresses in terms of incremental strains produces

$$\begin{aligned}
 \dot{T}_{ns} &= \left( \frac{2G}{1 + \frac{G}{\delta G_s}} \right) \dot{E}_{ns} \\
 \dot{T}_{nn} &= 2GE_{nn} + \left( K - \frac{2}{3}G \right) \text{tr}(\tilde{E}) \\
 \dot{T}_{ss} &= 2GE_{ss} + \left( K - \frac{2}{3}G \right) \text{tr}(\tilde{E}) \\
 \dot{T}_{tt} &= 2GE_{tt} + \left( K - \frac{2}{3}G \right) \text{tr}(\tilde{E})
 \end{aligned} \tag{3.24}$$

Therefore for the elastic case, all components of incremental stress in the local coordinate system can be obtained directly from incremental strains. Next, it must be determined if plastic slip occurs. After the stress components have been obtained the slip function [Eq 3.20] must be tested.

If the slip function  $F$  was less than zero, the strain rate was entirely elastic and the stress rates determined in equation (3.24) are correct. However, if  $F$  was greater than zero, plastic slip has occurred.

For plastic slip, determination of the incremental stresses can easily be made by assuming elastic and perfectly plastic behavior such that

$$\dot{E}_{ns} = \dot{E}_{ns}^e + \dot{E}_{ns}^p \quad (3.25)$$

where  $\dot{E}_{ns}$  is the total strain increment, and  $\dot{E}_{ns}^e$  and  $\dot{E}_{ns}^p$  are the elastic and plastic components of incremental strain, and the shear stress increment is then defined as

$$\dot{T}_{ns} = \left( \frac{2G}{1 + \frac{G}{\delta G_s}} \right) E_{ns}^p \quad (3.26)$$

and the normal shear stresses are still defined as in equation (3.24) since they are not dependent on the incremental shear stress.

Using equations (3.25) and (3.26) and substituting into equation (3.20), the plastic strain,  $E_{ns}^p$  can be solved for directly by solving the slip function,  $F$ , equal to zero. After the plastic strain is determined the incremental shear stress can be determined by repeating equations (3.25) and (3.26).

In chapter four a physical centrifuge simulation performed previously at Sandia National Laboratories along with several simulations performed for this thesis are presented. The results of the numerical simulations are then compared with each other and with the results of the physical simulation.

## **CHAPTER FOUR**

### **MODEL VERIFICATION**

#### **Description of Problem**

This chapter summarizes the procedure and results of various mine subsidence simulations. First, a physical centrifuge experiment of a coal mine model done at Sandia National Laboratories and the results of that experiment are presented. Second, numerical simulations using SCRUBS.BYU are introduced, the variables of the numerical models are listed and the results shown. Finally, comparisons are made.

#### **Centrifuge Model**

The following description of the test was taken basically from the laboratory report of the test [20].

**The prototype.** This centrifuge experiment modeled the response of shale overburden to the mining of a long wall panel. The prototype mine was located 86.3 m below the surface. The primary material above this mine was Devonian shale with horizontal bedding planes. The shale was fractured along and across these bedding planes. Above the shale was a relatively thin layer of sandy soil. A cavity of increasing width beneath the shale was created and the resulting failures and rubble formation were recorded.

The Sandia 25-Foot Centrifuge was used to conduct this test. The scaled-down model described in this section was mounted on a "swing platform" connected to the centrifuge.

**Construction of the model.** To construct the model, several shale boulders were cut into 202 mm slabs using a large rock saw. Three of these slabs were chosen. Their lengths were trimmed to 1.167 m (or less) and their top and bottom surfaces were machined flat and parallel to their bedding planes. They were then placed in a holding fixture that duplicated the internal dimensions of the test fixture. After this initial processing, dental plaster was used to fill voids between the three slabs of shale and to fill voids around the ends of each slab.

The model was fractured to simulate a jointed shale overburden. The fracturing process involved machining grooves into the exposed surface of the model (along the bedding planes). The grooves were 6 mm wide by 13 mm deep and on 25 mm centers. A 1.167 m long knife blade was then pressed into each groove to crack the shale along the bedding planes (the plaster was also broken). Some vertical cracks were also generated in the model during handling, machining, and fracturing processes. A complete description of the crack system, as observed from the non-grooved face of the model, is given in Figure 4.

**Dimensions of the model.** After the model was fractured, a thin layer of silica sand was placed above the shale to represent the soil layer. The thickness of this layer was 63.5 mm. With the shale layers being 0.511 m high, the completed model was rectangular, 1.167 m long, 0.202 m deep and 0.575 m high (again, refer to Figure 4).

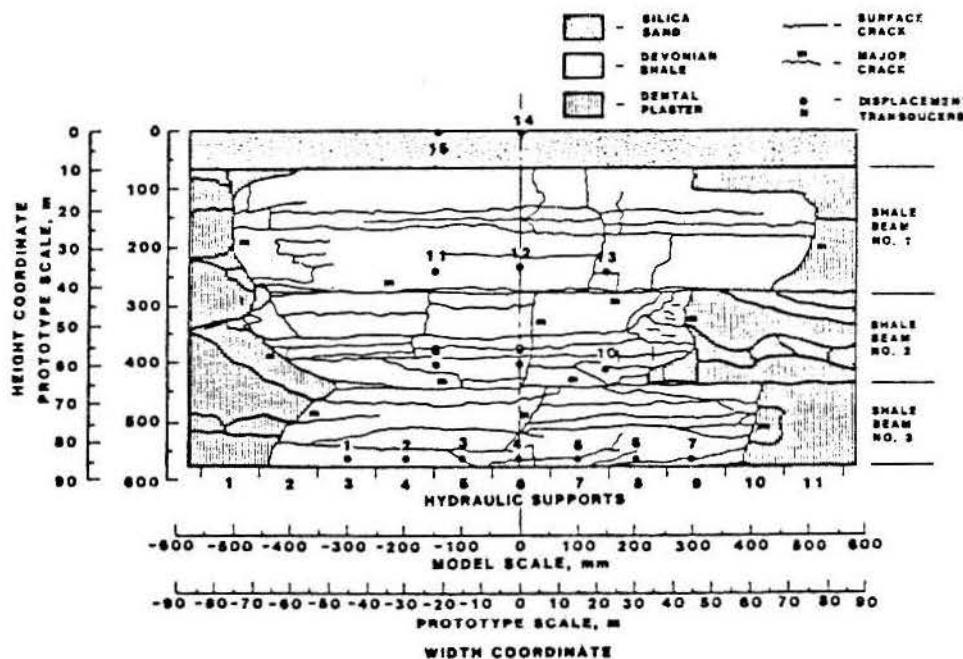


Figure 4. Schematic diagram of the centrifuge test [19].

**The materials.** As mentioned, three materials were used to construct the model mine structure. They were Devonian shale, silica sand, and dental plaster. The specific gravity of the Devonian shale was 2.64 Mg/m<sup>3</sup>. Its material properties varied between samples and with load range. For samples tested below 34.5 MPa, the average Modulus of Elasticity was 69.0 Gpa and Poisson's Ratio was 0.29. The unconfined compressive strength was 216 Mpa. The density of the dental plaster was

1.65 Mg/m<sup>3</sup>. The silica sand had a maximum particle size of 400 micrometers. When compacted at 150 g's, the density of this material was 1.25 Mg/m<sup>3</sup>.

**Modeling the cavity.** To create the subsurface cavity, the model was placed into the fixture with its bottom surface (length dimension) resting on a series of hydraulic supports. Each unit supported an area 102 mm wide by 203 mm deep. A total of 11 units were used to support the entire width (1.167 m) of the model. Using an electrically controlled hydraulic system, each support could be made to fall while under gravity loads. The cavity created by the fall of each support was 102 mm wide, 51 mm high, and 203 mm deep. Figure 4 includes a schematic diagram of this experimental configuration.

Between each segment of the simulation experiment (i.e., increase in width of the mine cavity), the centrifuge was stopped and additional records were made.

The experiment was conducted at an acceleration of 150 g's. Since linear dimensions scale in direct proportion with the acceleration, this model simulates a mine that is 86.3 m below the surface. The release of any single hydraulic support creates a prototype scale void that is 15.24 m wide and 7.62 high. All subsequent presentation of dimensions in this section will be specified in the prototype scale.

**The results.** Before the cavity was created in the experiment, the model was taken to 150 g's for approximately 5 minutes. This period was used to stabilize it. This was considered to be the first "time step."

As discussed earlier, a total of 11 hydraulic units supported the model. The mine cavity was created by lowering chosen supports in four additional time steps. For this simulation, the chosen sequence for lowering the supports was symmetric about the centerline of the model. First, the centerline unit was dropped. Subsequently, symmetric pairs about the centerline were dropped. Using the numbering sequence shown in Figure 4, support number 6 was dropped first (time step two), next supports 5 and 7 were dropped simultaneously (time step three), then supports 4 and 8 (time step four), and, finally, supports 3 and 9 (time step five).

Dropping support 6 produced a cavity of 15.24 m wide by 7.62 m high below the total strata depth of 84.3 m.

When the width of the drift was increased to 45.7 m by dropping jacks 5 and 7 (a total of three supports removed), a failure arch was formed. This arch extended to a depth of 49.1 m below the surface (a height of 35.2 m above the original roof of the cavity).

When the width was increased in the next step to 76.2 m (a total of 5 supports removed), the failure extended to the surface. Some new cracks were formed. The surface subsidence trough that was introduced into the model by these motions had a lateral extent of 94 m with a maximum subsidence of 5.33 m (see Figure 5).

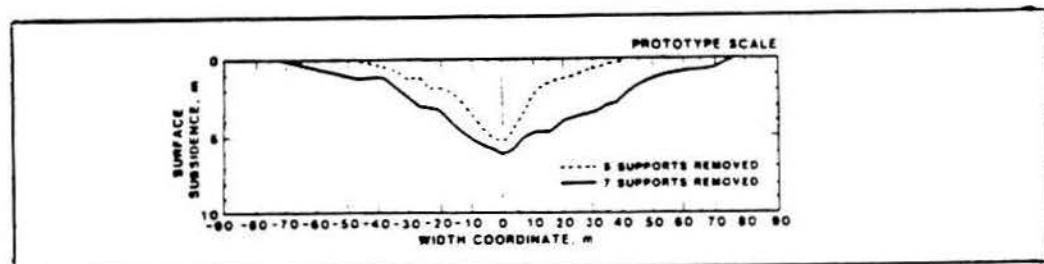


Figure 5. Centrifuge subsidence profiles [4].

With the final increase of the cavity width to 106.7 m (a total of 7 supports removed), many new cracks were formed and/or opened (see Figure 6). The subsidence trough extended to a width of 133 m with the maximum subsidence increasing slightly to 6.10 m (see Figure 5).

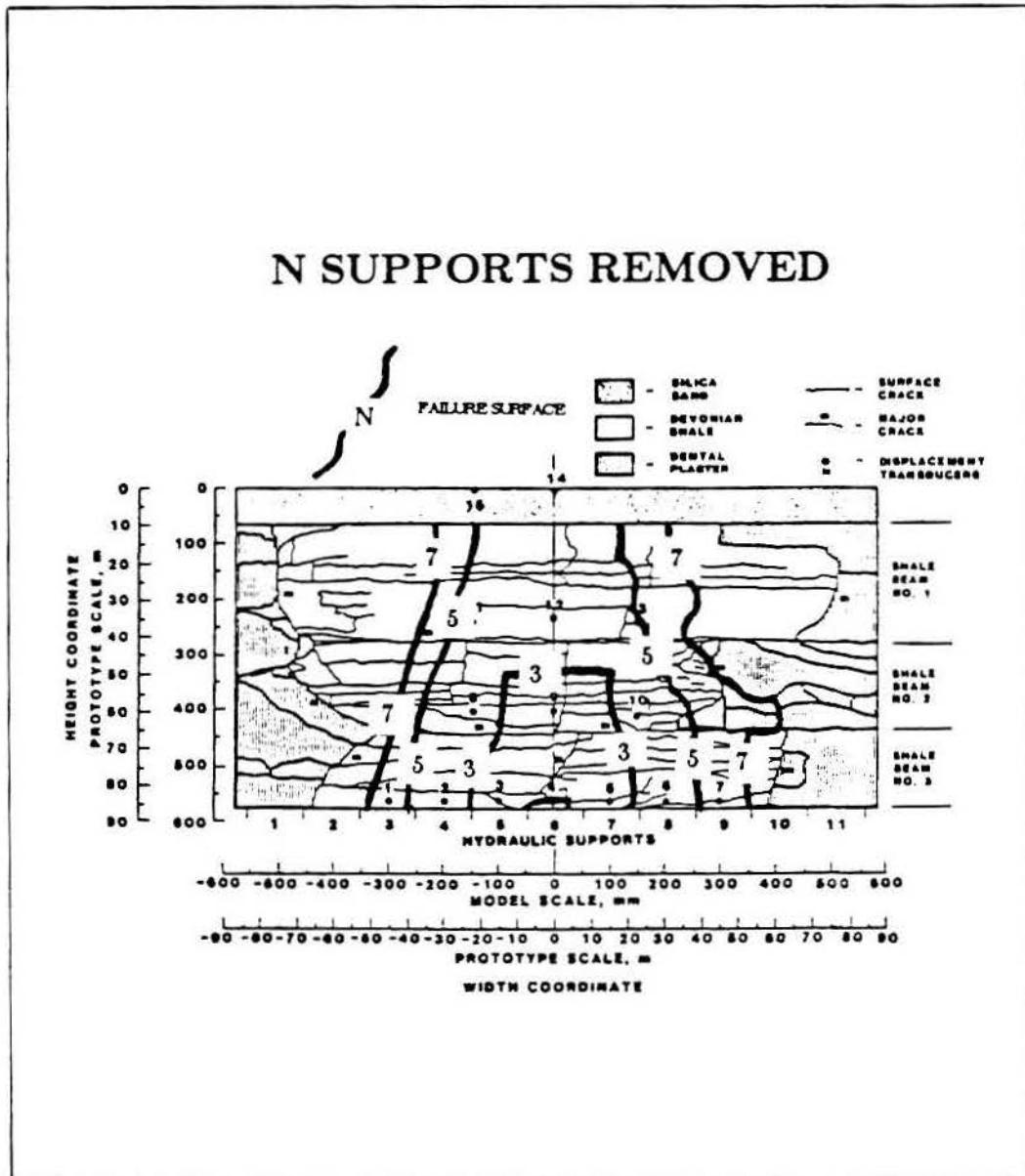


Figure 6. Failure progression of centrifuge model [4].

## Finite Element Models

**Equipment used.** The numerical simulation of the mine was performed using SCRUBS.BYU on a VAX 11750 computer. Computer programs used in addition to the finite element code included a mesh generator (QMESH.BYU), a pre-processor (PRESCRUBS.BYU), an interface for the output (INTERFACE), and the graphics package (MOVIE.BYU). A short description of each of these programs and their use is contained in this section (See also Figure 7).

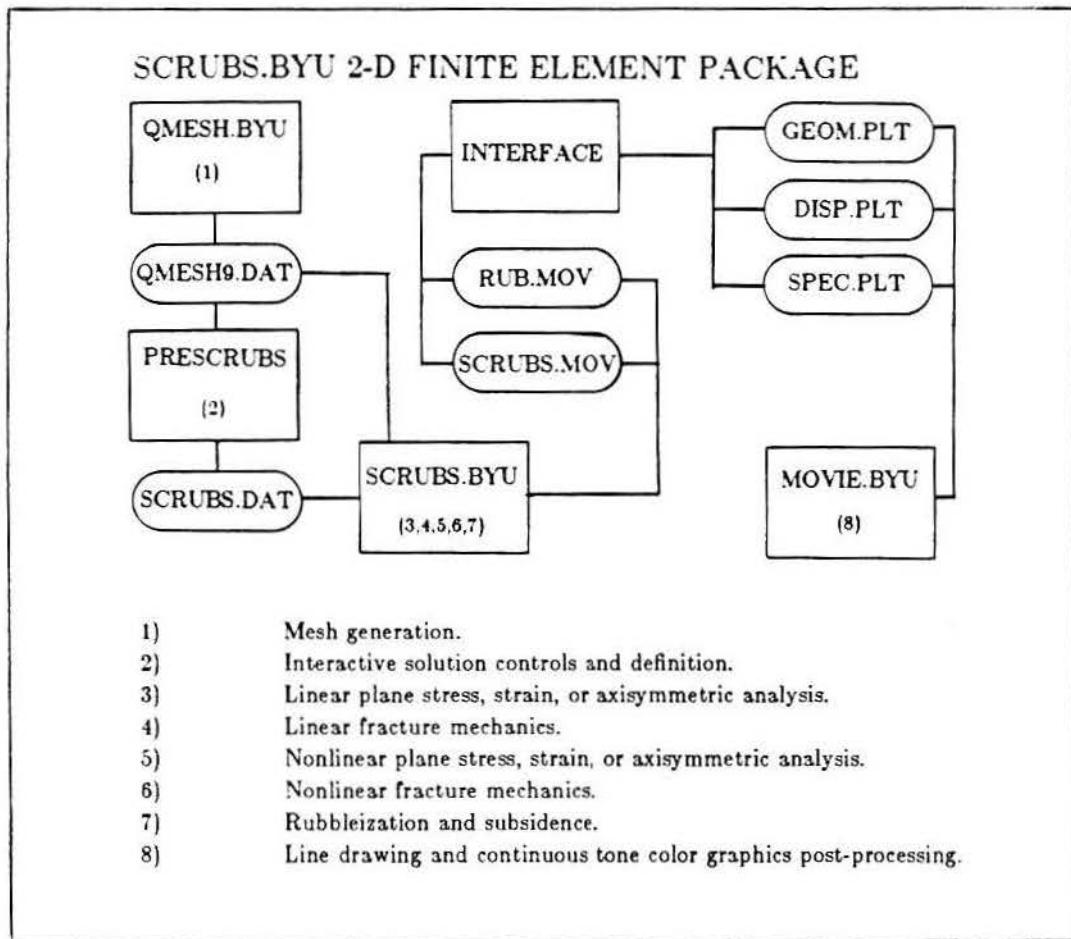


Figure 7. Program flow and capabilities [9].

**Description of the various models.** Six numerical models were used to simulate the response of the shale overburden; two different meshes were generated, and each mesh was used with three different combinations of jointed media continuum/discrete slip planes characteristics. The first mesh used the major vertical and horizontal fracture lines as determined in the Sandia test as region boundaries. This mesh approximated these major fracture lines as closely as possible (see figure 8). The horizontal joints were straight, but the vertical joints were not, which introduced some difficulties in constructing a uniform elements. As a result, this mesh was labeled the "skewed mesh." The second mesh approximated the major fracture lines with strictly vertical and horizontal boundaries. This resulted in a much more uniform mesh (see figure 9), and was labeled the "straight mesh."

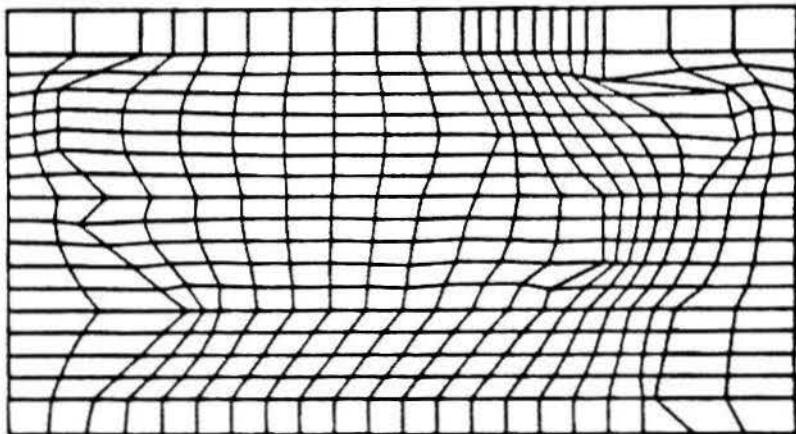


Figure 8. The skewed mesh.

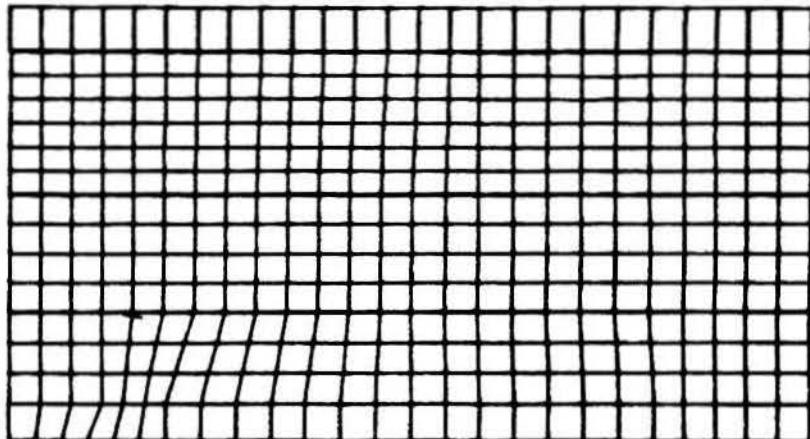


Figure 9. The straight mesh.

As stated, three different combinations of discrete slip plane/jointed media continuum were used with each mesh. The fracture combinations were:

- 1) Horizontal slip planes only (modeling of major slip planes).
- 2) Jointed media continuum only (modeling of minor fractures).
- 3) Combined jointed media and horizontal slip planes.

**Construction of the meshes.** Included in the mesh generation were the assignment of regions, material types, boundary conditions, application of smoothing algorithms to obtain even meshes, and renumbering of the mesh for more efficient use in the finite element code. The final meshes each contained 14 regions of four different materials (refer

to Figures 8 and 9). There were a total of 462 elements and 506 nodes in the skewed mesh, and 375 elements and 416 nodes in the straight mesh. The number of elements in the mesh was kept as low as it was judged possible and still maintain reasonable accuracy and reasonable computation time. Each potential slip plane required a unique flag to be set in QMESH.BYU. The mesh parameters, once processed by QMESH.BYU, were stored in a binary file named QMESH9.DAT to be used later by SCRUBS.BYU. Anyone not familiar with the operation of QMESH.BYU should consult Reference 8.

The problem parameters were all input using PRESCRUBS.BYU, the preprocessor for SCRUBS.BYU. These problem parameters included the material properties, the stress/strain field used, the yield condition, the element type, the number of gauss points to use in integration, the mining data, the convergence criteria, and the loading conditions. A state of plane strain was used throughout. Elasticity was assumed, the Von Mises failure criteria was chosen, gravity loads were applied, and linear isoparametric elements were integrated using four gaussian points per element. The rubbleization, slip plane, and jointed media characteristics were activated or deactivated by changing the corresponding flag in PRESCRUBS.BYU. The output from PRESCRUBS.BYU was stored in the file SCRUBS.DAT.

**Model dimensions.** The outside dimensions of both meshes were the same as those of the centrifuge model. The length was 112.2 cm, the height was 624.5 cm (from the bottom of the supports to the top of the sand), and the thickness was 20.2 cm. The steel elements had the same

depth, 51 cm, as the supports in the Sandia model. The 14 interior steel elements were defined to have exactly one half the width of the Sandia supports, 51 cm, so that two elements were equivalent to one Sandia support.

**Materials modeled.** Four materials were modeled in the numerical simulation. The four modeled materials were 1) silica sand, 2) Devonian shale, 3) dental plaster, and 4) steel. The silica sand, dental plaster, and Devonian shale were set up the same as in the centrifuge model. Steel was used for the material of the supports at the bottom of the model.

Material properties which were needed for the numerical simulation but not available from the Sandia centrifuge test information were determined from soil mechanics texts and judgement. A consistent system of units was used of centimeters, seconds, grams, and dynes for all measurements and quantities. For silica sand, a modulus of elasticity of 17 MPa ( $170(10^6)$ dynes/cm $^2$ ), a Poisson's Ratio of 0.3, and a density of 1.25 g/cm $^3$  were used. For both the shale and the plaster properties of 69 GPa ( $690(10^9)$ dynes/cm $^2$ ) for Young's modulus, 0.29 for Poisson's Ratio, and 2.64 g/cm $^3$  for the densities were used. For the steel, the modulus of elasticity was 200000 N/m $^2$  ( $20(10^{11})$ dynes/cm $^2$ ), Poisson's Ratio 0.3, and the density 7.8 g/cm $^2$ .

To use the rubbleization, slip plane, and jointed media capabilities of SCRUBS.BYU, additional material properties were required. Properties of the rubbleized material were set the same as for the shale. The

slip material was given a bulk modulus of  $3.45(10^{11})$ dynes/cm<sup>2</sup> and a shear modulus of  $3.45(10^{10})$ dynes/cm<sup>2</sup>. The jointed media was given a fracture spacing of 10 cm and a slip modulus of  $10^7$ dynes/cm<sup>2</sup>.

All materials were given a very high cohesion of  $10^{20}$ dynes/cm<sup>2</sup> and a hardening modulus of one. The cohesion was set arbitrarily high so that the materials failed while still in the elastic range. The hardening modulus was arbitrarily set at one as it is not used in this formulation.

**Failure condition.** The failure condition was chosen to be when either the horizontal or vertical stress exceeded the failure stress. This condition is a user-supplied option in the subroutine FTEST (see appendix E). The failure stress for each model is noted in each figure caption (see Figures 10-15). The bulking parameter for rubbleization was set at 0.98 for all materials. The failure stress and the bulking parameter were set in PRESCRUBS.BYU. These choices gave generally good results, and were chosen for that reason.

The finite element program SCRUBS.BYU was used to analyze the model. The model was initially subjected to a gravity load of 150 gravities ( $1471.5$  cm/s<sup>2</sup>). The subsidence of the material under a gravity load was then determined using basic finite element techniques. This stabilizing step was called the first time step. Supports were removed in four additional time steps, with the center one (two elements) removed in the second time step and two neighboring supports (four elements) removed in each successive step, until seven supports (fourteen elements) had been removed.

**The results.** Results of the simulation run were stored in three files: (1) SCRUBS.LIS contained the parameters and the progression of failure, (2) SCRUBS.MOV contained the geometry, displacements, and stresses of the final mesh, and (3) RUB.MOV contained the rubbleized incremental geometry. SCRUBS.LIS contained the results in a readable form, while SCRUBS.MOV and RUB.MOV were binary files. Using an interface to the graphics package MOVIE.BYU, final subsidence profiles and rubbleized incremental profiles could be obtained from correspondingly, SCRUBS.MOV and RUB.MOV.

### Comparisons

The failure progression of the physical centrifuge simulation can be seen in Figure 6. This progression was used as a standard from which the numerical simulations were adjusted and refined in an attempt to match, and to which the results were compared.

The different meshes seemed to have some effect on the results. There was a tendency for the failure in the skewed mesh to tilt in the direction of the skewed elements, and in the straight mesh the failure would often pipe to the surface long before the failure in the skewed mesh would reach the surface. This piping is evident in both the jointed media and the discrete slip plane straight mesh models, although in slightly different forms. The centrifuge model had more of a pyramid failure form. The tilting of the failure in the skewed meshes did not seem to alter the overall pattern of failure, which was also pyramid in form.

In the jointed media straight mesh model (see Figures 10 a-d), piping to the surface occurred at the second time step (first support removed). After this initial piping, the failure seemed to follow the same general pyramid pattern of the centrifugal failure (and the skewed meshes).

In the jointed media skewed mesh model (see Figures 11 a-d), failure occurred in pyramid form, with the time steps favorably comparable to the progression which had occurred in the centrifuge model, including the formation of a failure arch, failure to the surface occurring at the fourth time step (5 supports removed), and a wide subsidence trough at the end.

In the discrete slip plane straight mesh model (see Figures 12 a-d), no piping occurred until the third time step, but failure to the surface was then direct for all the remaining time steps. The resulting trough was comparable to the physical model, but there was no formation of a failure arch at any time.

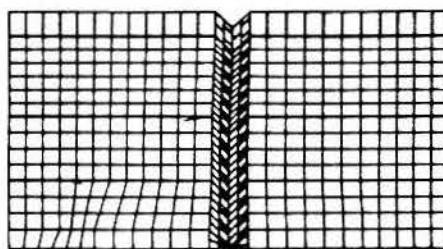
The discrete slip plane skewed mesh model was similar to the jointed media skewed mesh (Figures 13 a-d). The failure included a pyramid form, the formation of a failure arch at the third time step, failure to the surface at the fourth time step, and the final wide subsidence trough.

The combined straight mesh (Figures 14 a-d) resulted in a failure progression almost exactly like that of the jointed media straight mesh. A pipe failure to the surface occurred in the second time step, then a pyramid failure occurred from time step three to the final subsidence trough.

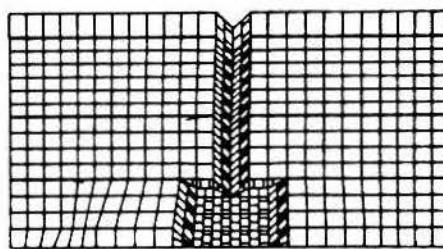
The combined skewed mesh (Figures 15 a-d) resulted in failure progression which was somewhat between that of the jointed media skewed

model, and interestingly, the jointed media straight model. Piping failure occurred, although not quite as drastically or sudden as in the straight meshes. The final subsidence trough was comparable to the others.

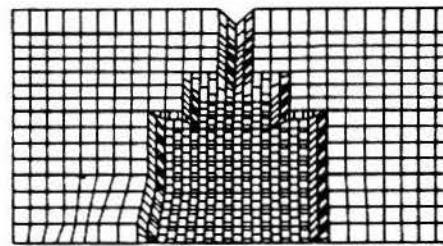
Some interesting variations of these numerical models are provided in appendix D.



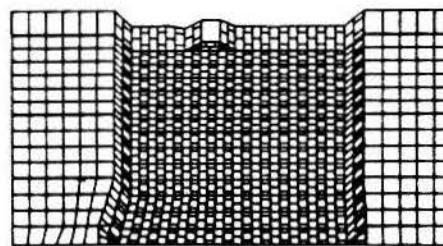
a. One support removed.



b. Three supports removed.

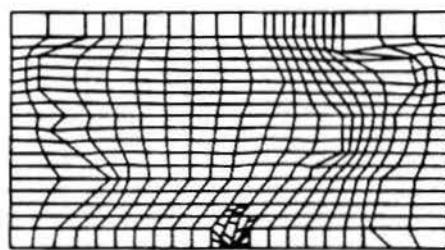


c. Five supports removed.

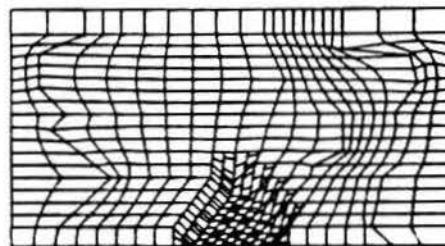


d. Seven supports removed.

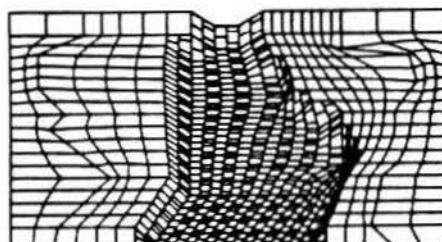
Figures 10 a-d. Jointed media straight mesh. Failure stress set to 0.1  
 $10^7$  dynes/cm<sup>2</sup> (tension).



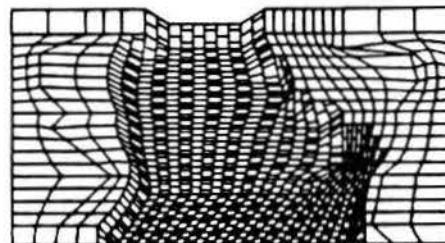
a. One support removed.



b. Three supports removed.

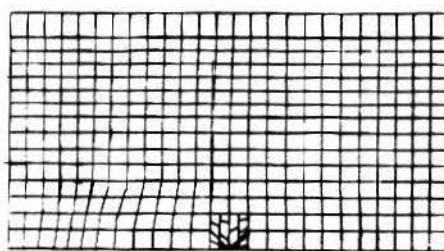


c. Five supports removed.

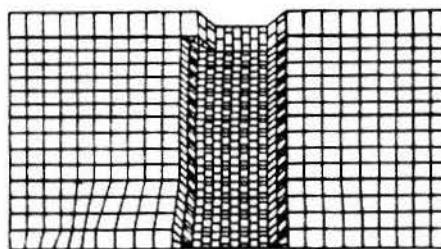


d. Seven supports removed.

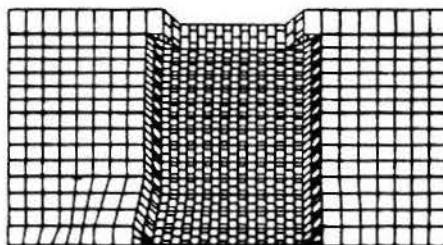
Figures 11 a-d. Jointed media skewed mesh. Failure stress set to zero.



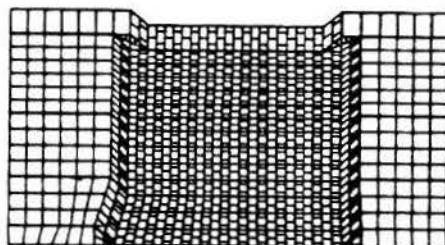
a. One support removed.



b. Three supports removed.

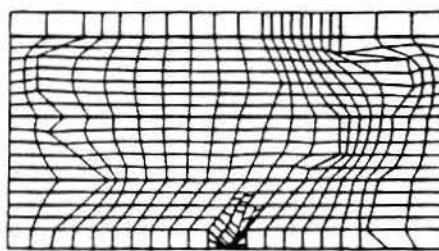


c. Five supports removed.

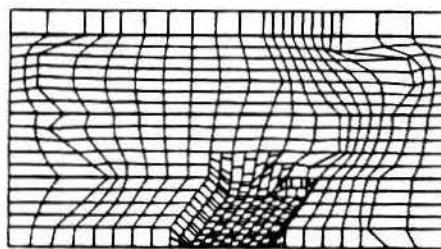


d. Seven supports removed.

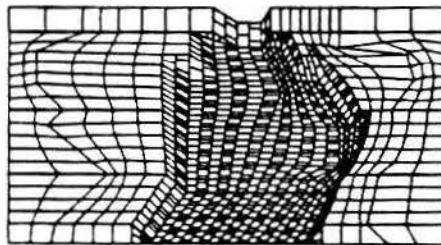
Figures 12 a-d. Discrete slip plane straight mesh. Failure stress set to 0.1  $10^5$  dynes/cm<sup>2</sup> (tension).



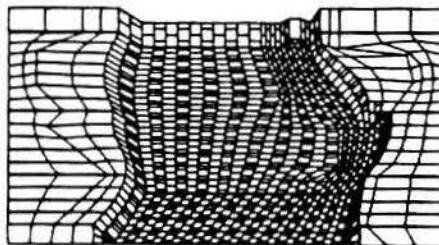
a. One support removed.



b. Three supports removed.

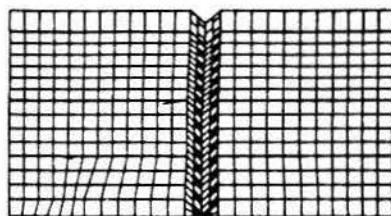


c. Five supports removed.

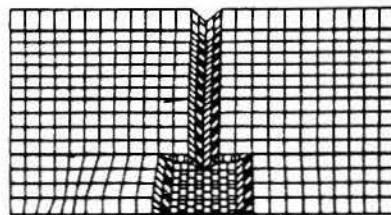


d. Seven supports removed.

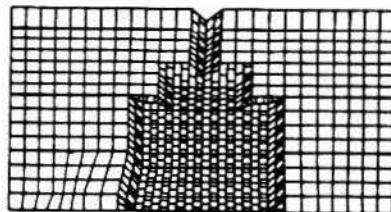
Figures 13 a-d. Discrete slip plane skewed mesh. Failure stress set to zero.



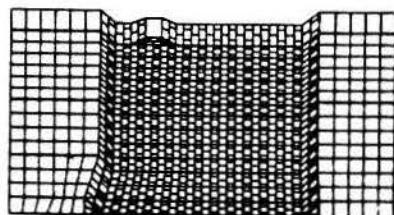
a. One support removed.



b. Three supports removed.

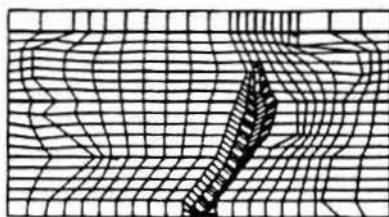


c. Five supports removed.

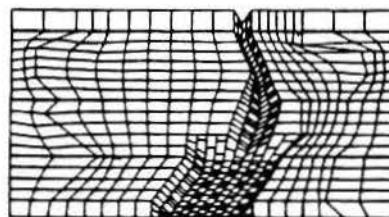


d. Seven supports removed.

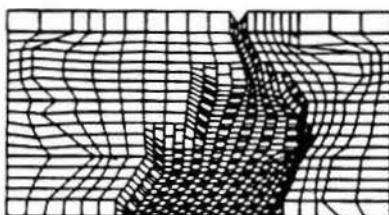
Figures 14 a-d. Combined straight mesh. Failure stress set to 0.1  
 $10^7$  dynes/cm<sup>2</sup> (tension).



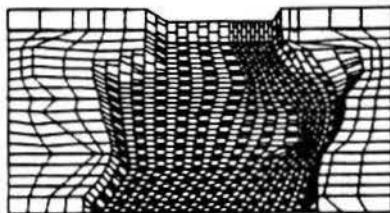
a. One support removed.



b. Three supports removed.



c. Five supports removed.



d. Seven supports removed.

Figures 15 a-d. Combined skewed mesh. Failure stress set to  $0.1 \times 10^7$  dynes/cm<sup>2</sup> (tension).

## **CHAPTER FIVE**

### **CONCLUSIONS AND RECOMMENDATIONS**

Knowledge of fracture and joint modeling in rock mechanics problems has been increased by the contribution of this thesis. Modeling fractures as either low shear element slip planes, jointed media continua, or as a combination of both are all valid approaches. Since many geologic materials contain both faults, which are better modeled by discrete slip planes, and rock mass with somewhat regular joint spacing, which is best modeled by continuum theory, it would make sense at times to combine them. In any case, it is possible for the stress analyst to be able to choose between the two models, or use the combination of both.

Two important characteristics of the simulations were closely considered: first, the failure sequence, and second, the final subsidence troughs. The general failure progression of all models in the mine subsidence problem were very similar. This would seem to indicate that all the models used were valid. To some extent, this success was dependent on an understanding of the properties and geometry of the problem. The second important characteristic considered, the subsidence troughs, were not always similar. The maximum displacements of the troughs were comparable, but the trough edges were not. As noted in chapter four, the physical centrifuge model resulted in gradually sloping trough edges, while the numerical simulations contained very steep trough edges. This is caused

by a weakness in the numerical stiffness formulation, which has difficulty in modeling the flow of the surface sand with solid finite elements. This difficulty is also indicated by the presence of isolated non-failed elements at the surface (refer to figures 10d, 13d, and 14d).

### Problems and Solutions

The two different mesh types, skewed and straight, resulted in two consistent variations in the failure. First, the direction of failure was influenced, though only slightly, by the mesh type. The skewed mesh showed a tendency to fail diagonally, along the skewed elements, rather than in a more regular, vertical pattern like the straight mesh. The tendency for the skewed mesh to fail slightly diagonally implies that the finite-element formulation has some difficulty with the uneven elements. The failure was still quite good, however, and the final results seemed to be as good as those of the physical simulation. Second, the general form of failure varied between mesh types. The skewed mesh resulted in a pyramid form of failure, while the straight mesh contained more of a piping form. The varying forms of failure seem more pronounced than the slight directional tendencies.

For this problem, the skewed mesh seemed to be slightly more accurate. This is most likely due to the presence of major not-quite vertical slip planes in the centrifuge model (refer to Figure 4). While we were not able to use vertical slip planes (there is a problem with combining both vertical and horizontal discrete slip planes in a single model in

SCRUBS.BYU), the skewed mesh introduced diagonal failure tendencies. The diagonal failure may have reduced the piping failure, as the piping usually occurred vertically.

We used the least number of elements we could and still get results that did not seem effected by the element sizes. The run time for this kind of formulation and the size of the problem seemed reasonable. In our formulation, linear elements were used, whereas quadratic elements may have given better results. If quadratic elements were needed, fewer elements would be used, but the increased computational requirements for the quadratic formulation would offset the lowered computational requirements for the fewer elements.

As previously mentioned (chapter four), the failure stress was set at zero for the jointed media and discrete slip skewed meshes, at  $0.1 \cdot 10^7$  dynes/cm<sup>2</sup> for the jointed media straight mesh model and the combined models, and at  $0.1 \cdot 10^5$  dynes/cm<sup>2</sup> for the discrete slip plane straight mesh model. This criteria seemed to give the best results. Other criteria attempted included the separate horizontal and vertical stresses by themselves and the maximum principal stress. More study of the failure stress possibilities would be useful.

Although at present the use of the low shear element capability is currently limited to elastic deformations along the plane of slip, the incorporation of a plastic failure model for the slip plane material is possible. The Drucker-Prager yield criteria [6] would be especially applicable for this purpose and would be recommended for any further study in this area.

It should be noted here that the jointed media formulation in SCRUBS.BYU at present is only valid for a plane strain or axisymmetric condition. In the mine model, a plane strain assumption was made because of this, even though a plane stress situation may have been more realistic.

As previously mentioned, the poor profile of the subsidence trough at the edges in our numerical simulations were most likely a result of an incorrect stiffness formulation for the sand.

### **Summary**

A summary of the recommendations made above are listed as follows:

- 1) Test the effectiveness of using quadratic elements in a model.
- 2) Study in detail the different failure criteria, and determine those which would be most accurate and in which situations.
- 3) Apply the Drucker-Prager yield conditions to a model in which the required parameters are available.
- 4) Do a plastic analysis of a subsidence problem, preferably using the Drucker-Prager yield condition.
- 5) Adjust the jointed media formulation for plane stress states.
- 6) Correct the stiffness formulation to allow for sandy materials.
- 7) Correct SCRUBS.BYU to allow combined horizontal and vertical discrete slip planes in a single model.

## BIBLIOGRAPHY

## SELECTED BIBLIOGRAPHY

1. Advani, S.H. and Lin, Y.T. "Subsidence and Roof Response Studies Related to Underground Coal Gasification," *Proceedings, Third Annual Underground Coal Conversion Symposium*. Fall Leaf Lake, CA, June 9 (1977).
2. Benzley, S.E. "SCRUBS.BYU, A Finite Element Computer Program for Subsidence Modeling," Engineering Research, College of Engineering Sciences and Technology. Brigham Young University, Provo, UT (1982).
3. Brauner, G. "Subsidence Due to Underground Mining, Part I," *I.C. 8571*, U.S. Bureau of Mines. Washington, D.C. (1973).
4. Clough, R. W. and Woodward, R.J. III "Analysis of Embankment Stresses and Deformations," *Journal of the Soil Mechanics and Foundations Division*, ACSE, Vol. 93, No. SM4. July (1967), pp.529-549.
5. Cook, Robert D *Concepts and Applications of Finite Element Analysis (Second Edition)*, John Wiley and Sons Inc. NY (1981).
6. Drucker, D.C. and Prager, W. "Soil Mechanics and Plastic Analysis or Limit Design," *Quarterly of Applied Mechanics*, 10. (1952), pp.157-165.
7. Heuze, F.G. "Stability Analysis for Rock Structures," *19th Symposium on Rock Mechanics*. Stateline, NE (1978).
8. Jones, R. K. "User's Manual for QMESH, a Self-Organizing Mesh Generation Program," *SLA-74-02139*, Sandia Laboratories. Albuquerque, NM, July (1974).
9. Long, Michael G. "SCRUBS.BYU: A Two-Dimensional Finite Element Package for Continuum Analysis Using Quadratic Isoparametric Elements," Unpublished Master's Thesis. Brigham Young University, Provo, UT (1983).

10. Moreland, L.W. "Elastic Response of Regularly Jointed Media," *Geophysical Journal*, Vol. 37. (1974), pp.435-446.
11. Moreland, L.W. "Continuum Model of Regularly Jointed Mediums," *Journal of Geophysical Research*, Vol. 79, No. 2. (1974), pp.357-362.
12. Moreland, L.W. "Plane Wave Propagation in Anisotropic Jointed Media," *Quarterly Journal of Mechanics and Applied Mathematics*, Vol. 30. (1977), pp.1-21.
13. Nair, K. "Analytical Methods for Predicting Subsidence," *Proceedings, Lawn Subsidence Symposium*. Tokyo, Sept (1969).
14. National Coal Board *Subsidence Engineer's Handbook*. Hobart House, Grosvenor Square, London (1975), 111 pp.
15. Nayak, G.C. and Zienkiewicz, O.C. "Elasto-Plastic Stress Analysis. A Generalization for Various Constitutive Relations Including Strain Softening," *International Journal for Numerical Methods in Engineering*, Vol. 5. (1972), pp 113-135.
16. Nelson, Royd R. "Two-Dimensional Computer Modeling of Joints and Fractures in Continua", Unpublished Master's Thesis. Brigham Young University, Provo, UT, December (1983).
17. Peng, S. S. *Coal Mine Ground Control*. Wiley, NY (1978).
18. Sutherland, H.J., Hommert, P.J., Taylor, L.M., and Benzley, S.E. "Subsidence Prediction for the Forthcoming Tono UCG Project", *Proceedings, Ninth? Annual Underground Coal Conversion Symposium*, ?? IL, ? (1983).
19. Sutherland, H.J., Schuler, K.W., and Benzley, S.E. "Numerical and Physical Simulations of Strata Movement Above Idealized Mine Structures," *SAND83-0701*. Sandia National Laboratories, Albuquerque, NM (1983).
20. Sutherland, H.J., Heckes, A.A., and Taylor, L.M. "Physical and Numerical Simulations of Subsidence above High Extraction Coal Mines," Sandia National Laboratories, Albuquerque, New Mexico (1983).

21. Thomas, Robert K. "A Continuum Description for Jointed Media," *SAND81-2615*. Sandia National Laboratories, Albuquerque, NM (1980), p 24.
22. Voight, B. and Dahl, H.D. "Numerical Continuum Approaches to Analysis of Nonlinear Rock Deformation," *Canadian Journal Earth Science*, Vol. 7(1970).
23. Witte, W., editor. *Numerical Methods in Geomechanics, Vol. 1, 2, and 3*, Proceedings of 3rd 1st Conference on Numerical Methods in Geomechanics. Balkema, Rotterdam (1979).

## **APPENDICES**

## APPENDIX A

### SCRUBS.BYU SUBROUTINE MAP AND DESCRIPTIONS

The following appendix provides subroutine descriptions and subroutine maps for the finite element code SCRUBS. The subroutine descriptions (the main is included) are listed alphabetically.

The subroutine descriptions:

- AUX: Creates coordinate jacobian 0 interpolate X; YOCOJ(I,J), XY(1),XY(2) are respectively the coordinate jacobian matrix, the X coordinate and the Y coordinate.
- BSUB: Conducts systematic back-substitution and solves for boundary displacements and reaction transformations.
- CONRUB: This subroutine checks for rubble/continuum interaction and computes the hydrostatic force in the rubble if a continuum element is in contact.
- CONVG: Determines the percent convergence.
- CORNN: This subroutine determines if node IX is a corner node.
- DATALST: Writes title, line numbers for files (presently not used).
- DROP: Checks for elements about to fail and adjusts geometry for failure.
- FLAGE: Makes impact node calculations and new node assignments.

- GAUSSP: Initializes gaussian constants.
- GDATA: Reads geometrical data, boundary conditions, and gaussian integration data.
- INVAR: Calculates invariants and sets the yield stress accordingly.
- JOINTM: Calculates incremental stresses and residuals.
- LDATA: Reads load control data.
- LINEAR: Helps to update stress and strain.
- MAKEEL: This subroutine adds a new element to the connectivity containing corner nodes I and K.
- MOD: Forms D matrix for different stress/strain cases.
- NEWNOD: This subroutine finds the new node number of node N.
- NFLOW: Calculates the amount of yield that results.
- NODEXY: Sets x,y values of new intermediate coordinates of quadratic or cubic elements.
- OUTPUT: Writes displacements, reactions, stresses and strains to SCRUBS.LIS
- PDISP: Initializes the displacement vector according to number of loading increments.
- READF: Reads the mining parameters: which elements, and when.
- REMLD: Removes gravity load from failed elements.
- RESIDUE: Determines element failure, rubbleization, and residual.
- RESOLV: Updates stiffness equation solution.
- ROSB: Adjusts stiffness matrix.
- ROTATE: This subroutine rotates 2D stress or strain vector by angle THETA.
- RUBDRAW: Writes the rubble file RUB.MOV.

- RZBASE: This subroutine finds the base R and Z dimensions for fall calculations.
- SCRUBS: Program designed to compute the failure, collapse, and resulting subsidence of geologic materials. Performs elastic/plastic analysis of plane stress/strain and axisymmetric problems for linear, parabolic, and cubic elements.
- SCRUBSV: This subroutine opens and closes the files used by the main program, SCRUBS.
- SET: Sets element spacing and determines bandwidth and resulting stiffness storage required.
- SFR: Sets shape functions according to element type.
- SLIPP: This subroutine reads the slip plane data, adjusts the geometry and elements accordingly, and then records the adjusted information.
- SOLVE: Solves stiffness equations, modifies loads.
- STIFM: Forms and updates stiffness matrix, and calculates body forces.
- SWITCH: Switches coordinates.
- TFORM: Makes adjustments for inclined boundary situations.
- ZONE: This subroutine reads meshing cards as done in the CHILES2 program. It is provided here only as an interim capability. This subroutine is called by the main program.

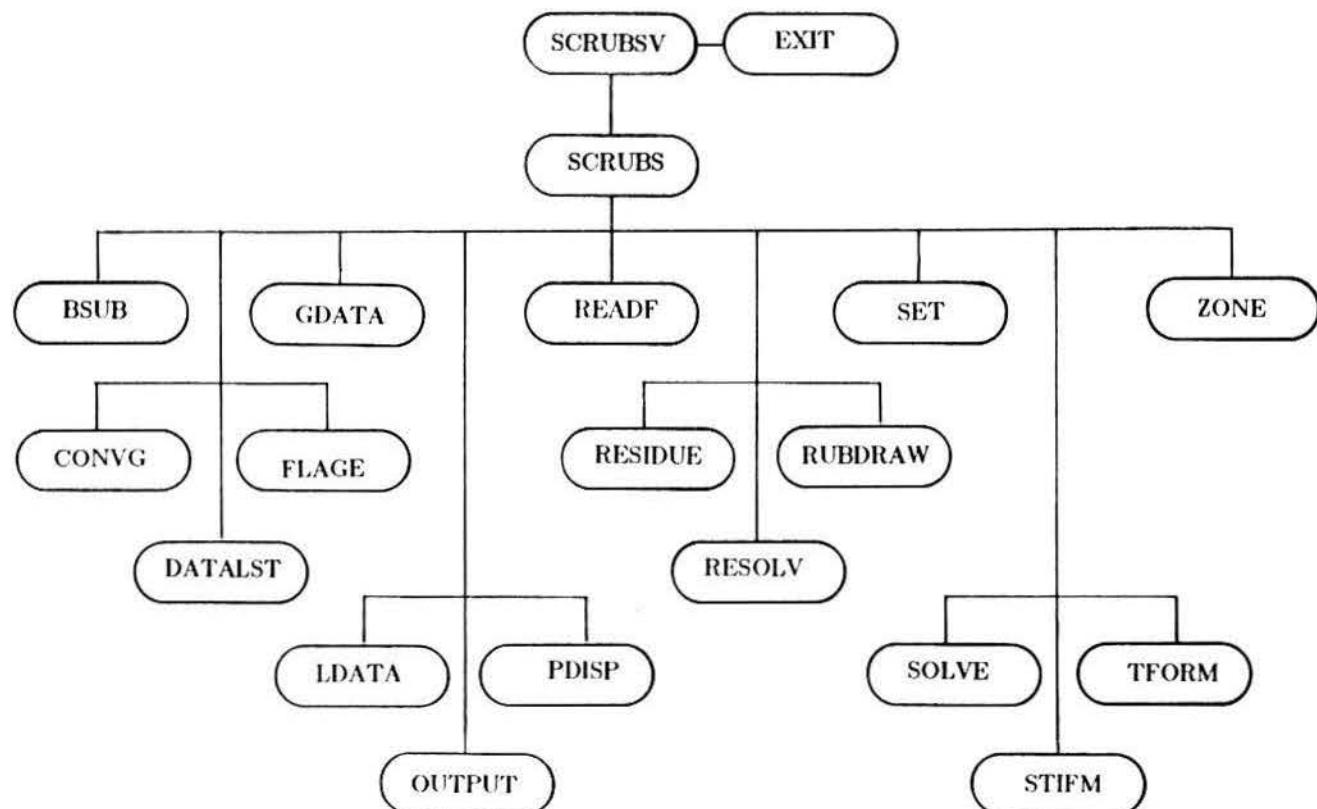


Figure 16 a. Subroutine map -- main.

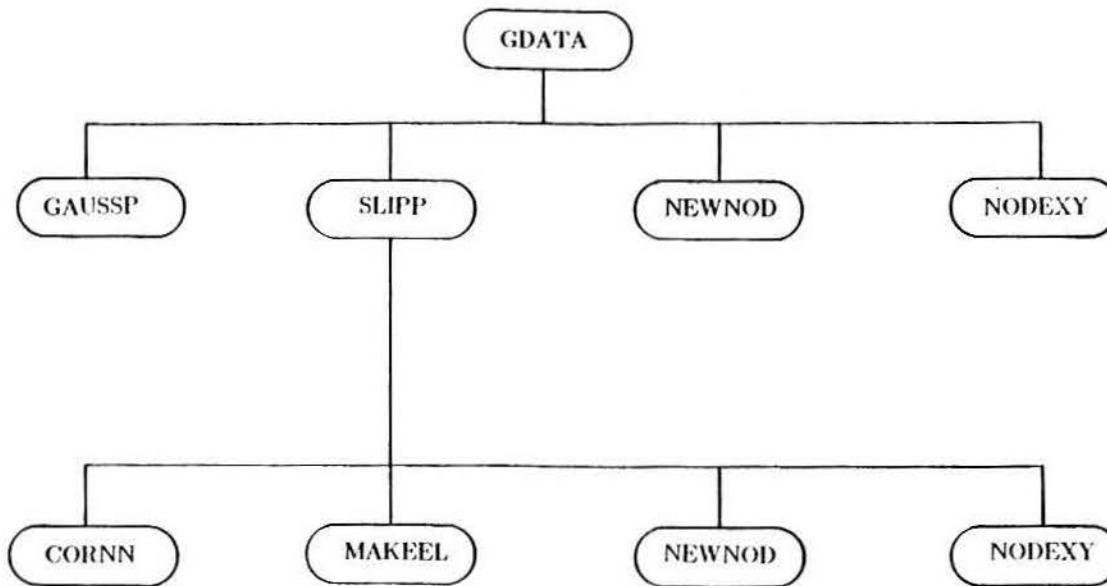


Figure 16 b. Subroutine map -- GDATA.

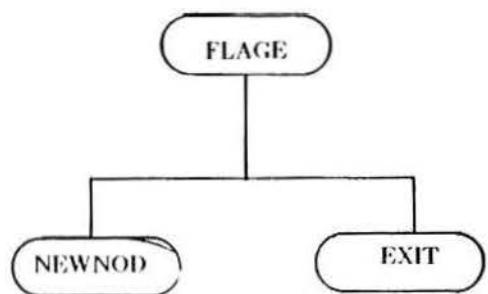


Figure 16 c. Subroutine map -- FLAGE.

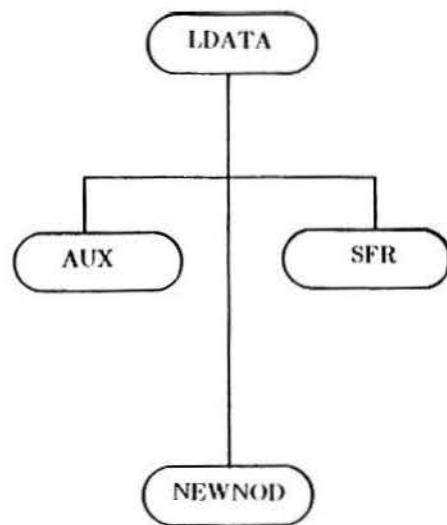


Figure 16 d. Subroutine map -- LDATA.

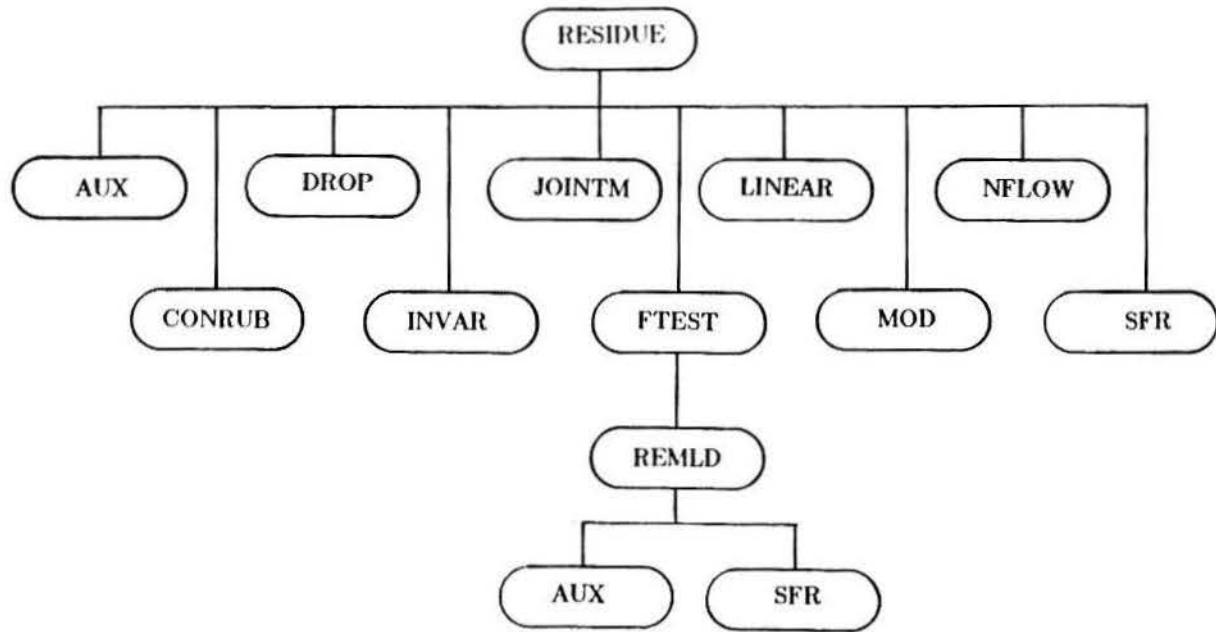


Figure 16 e. Subroutine map -- RESIDUE.

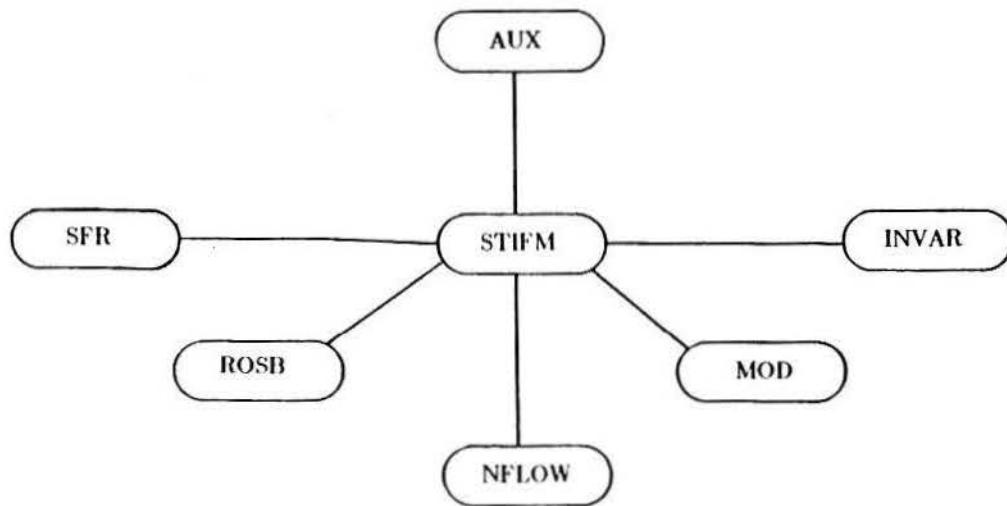


Figure 16 f. Subroutine map -- STIFM.

## **APPENDIX B**

### **SCRUBS.BYU USER'S MANUAL**

The following appendix provides: first, a short description of the program SCRUBS and its capabilities; second, detailed descriptions of the three files which are read by SCRUBS and the four files that are created by SCRUBS.

## SCRUBS.DOC

SCRUBS is a FORTRAN computer program designed to compute the failure, collapse, and resulting subsidence of geologic materials. The uniqueness of this program is it's ability to model rubble formation and collapse in a continuum, as opposed to a discrete, sense. Both pre and post failure aspects of particular problems are treated. SCRUBS is a nonlinear finite element program which is capable of determining the deformation and state of stress in plane and axi-symmetric bodies. Pre and post failed material properties may be elastic-perfectly plastic, or elastic work hardening. Linear, quadratic or cubic isoparametric elements are used to represent the region and its boundary. Four different yield conditions can be imposed on the materials: von Mises, Tresca, Drucker-Prager, or Beltrami. Three different algorithms for solving the nonlinear discretized equations are available. They are: 1) a constant stiffness initial stress method, 2) a two step process where the stiffness matrix is updated on the second iteration of an otherwise initial stress process and 3) a regular tangent stiffness method. A check on force residuals is used to evaluate convergence for any load increment.

Three specific files are read and four other specific files are created by SCRUBS. The three files that are read have the following names and functions.

QMESH9.DAT = Mesh information as created by QMESH.BYU  
SCRUBS.DAT = SCRUBS input data  
SCRUBS.RST = Restart file

The four files that are created have the following names and functions.

SCRUBS.MOV = Displacement, stress and strain data at each load step  
RUBBLE.MOV = Element rubbleization plot file  
SCRUBS.RST = Restart file  
SCRUBS.LIS = List of failure sequence

The contents of these six files are now explained in detail.

**QMESH9.DAT**

This is the standard QMESH.BYU renumbered file that contains the two dimensional finite element meshing information. It consists of five records written in blocked binary form. The content of these records is as follows.

Record 1. (8 words) A comment, packed 4 characters per word.  
This comment is from the COMLEN card in the QMESH input.

Record 2. (4 words)  
KKK, the number of elements in the mesh  
NNN, the number of nodes in the mesh  
NFF, the number of words in the boundary flag table  
MAXDIF, the maximum difference of node numbers for any element in the renumbered mesh

Record 3. (2 x NNN words) the lists of nodes, in renumbered order; that is  
(X(N),Y(N),N=1,NNN),  
or  
(R(N),Z(N),N=1,NNN)

Record 4. (5 x KKK words) The list of elements:  
(N1(K),N2(K),N3(K),N4(K),MAT(K),K=1,KKK)  
where N1(K) to N4(K) are the node numbers for the K-th element in counterclockwise order, and MAT(K) is the material number of the K-th element.

Record 5. (NFF words) the list of boundary flags and nodes,  
(IFLAG(I),I=1,NFF). Flags will be negated to distinguish them from nodes, and the corresponding node or list of nodes will follow each flag.  
If NFF=0, this record will not be written.

End-of-File mark.

## SCRUBS.DAT

This file contains the data necessary to define the problem to be analyzed. The groups of lines of this file and the specified format of each line follows.

\*\*\*\*\*

## GROUP 1 INTERNAL MESH GENERATION OR RESTART SPECIFICATION

Line 1. (4I5) Geometry parameters  
 1 - 5 Number of elements (NEL) \*\*  
 6 - 10 Number of nodes (NODES)  
 11 - 15 Number of load cards (NUMPC)

\*\* NOTE if NEL = 0, omit remaining lines of the group and  
 read total mesh from the input file QMESH9.DAT. If NEL = -1,  
 the problem is to be restarted and the remaining lines of this  
 group are omitted.

Line 2. (6I5) N,IX array  
 1 - 5 Element number (N)  
 6 - 10 Ith nodal point (IX array)  
 10 - 15 Jth nodal point (IX array)  
 16 - 20 Kth nodal point (IX array)  
 21 - 25 Lth nodal point (IX array)  
 26 - 30 Material number (MAT, IX array)

In general every element must be defined; but with the semi-automatic mesh generation feature, a minimum of one element per row need be input. For example, if element 10 is read with values I=12, J=13, k=24, L=23, and MAT=1, and the next element is read is element 15 with values I=23, J=24, K=35, L=34, and MAT=1, then element 11 would be assigned values 13, 14, 25, 24, and 1.

Line 3. (I5,F5.0,4F10.0)  
 1 - 5 Nodal point number (N)  
 6 - 10 Boundary condition code (CODE)  
 11 - 20 Radial coordinate (R)  
 21 - 30 Axial coordinate (Z)

In general, every nodal point must be defined, but since the program has a semi-automatic mesh generation feature, a minimum of two nodal points per row need be input and the intervening points will be assigned coordinates based on a linear interpolation procedure. For example, if nodal point 1 is the first point in a row with coordinates (2.5, 5.4), and nodal point 11 is the next point defined with coordinates (12.5, 10.4), then nodal point 2 will be located at (3.5, 5.9), etc.

\*\*\*\*\*

\*\*\*\*\*  
GROUP 2 SOLUTION CONTROLS

Line 1. Problem identification  
 1 - 5 Total number of problems to be solved in one run (NPROB)

Line 2. Title (20A4)  
 1 - 72 Title of problem.

Line 3. Control data (16I5)  
 1 - 5 Total number of nodes, NP (not more than 1000)  
 6 - 10 Total number of elements, NE (not more than 1000)  
 11 - 15 Total number of restrained boundary points, NB  
 16 - 20 Total number of load cases/problem, NLD  
 21 - 25 Number of d.o.f. per node, NDF  
 26 - 30 Number of different materials, NMAT (not more than 10)  
 31 - 35 Element type 1=linear, 2=parabolic, 3=cubic, NSFR  
 36 - 40 Number of gauss points for stiffness calc. NGAUS  
 41 - 45 Solution algorithm, NALGO  
     0 = elasticity only  
     1 = constant stiffness  
     2 = two step process  
     3 = tangent stiffness  
 46 - 50 Stress/strain type NFP  
     0 = Plane strain  
     1 = Plane stress  
     2 = Axisymmetric problem  
 51 - 55 Yield condition parameter, NYIELD  
     1 = Mises  
     2 = Tresca  
     3 = Drucker-Prager  
     4 = Beltrami  
 56 - 60 Input stiffness control, NT  
     0 = Number of elastically coupled nodes  
     1 = input stiffness coefficients  
 61 - 65 Flag for Rubble calculation, NL  
     0 = No rubble  
     1 = rubble  
 66 - 70 Bandwidth (leave blank unless NT = 1)  
 71 - 75 Number of coordinates per node NCORD (default 2)  
 76 - 80 Number of gauss points for nodal force residual  
 calculation and stress storage (MGAUS) result even for  
 elastic solution MGAUS defaults for NGAUS.

\*\*\*\*\*

\*\*\*\*\*

GROUP 3 - MATERIAL PROPERTIES

Line 1. Material data (I10, 7F10.2) NMAT Lines, limited to NMAT= 10  
 (Note, if NL = 1, card NMAT of this section must give  
 unconsolidated rubble constants)  
 1 - 10 Material property number N  
 11 - 20 Young's modulus ORT(N,1)\*  
 21 - 30 Poisson's ratio ORT(N,2)\*\*  
 31 - 40 Yield stress ORT(N,3)  
 41 - 50 Hardening modulus ORT(N,4)  
 51 - 60 Conical yield surface angle ORT(N,5)  
 61 - 70 Thickness (leave as zero if NPP = 1) ORT(N,6)

\* A negative value in this position activates the low shear material description. In this case, the bulk modulus, K, is the absolute value of ORT(N,1), and the shear modulus, G, is the value of ORT(N,2)

\*\* A negative value in this position activates the jointed media material description. For this case, one more line is read, for that material only, defined as follows: (2G12.5)

1-12 Fracture spacing ORT(N,9)

Line 2. Tabulated plastic stress-strain data  
 (Only for materials with ORT(N,4) negative) (I10,F10.3)  
 1 - 10 Number of tabulated strain points, NTAB  
 11 - 20 Strain increment in percent strain, TABSTN(N)  
 If ORT(N,4)> 0 these values default to 2 and 100 respectively.

Line 3. String of stress values, NTAB in number, one line required for each material (15F8.0)  
 1 - 8 Stress value for point 1  
 9 - 16 Stress value for point 2  
 17 - 24 Stress value for point 3  
 25 - 32 Stress value for point 4  
 .  
 .  
 .  
 etc.

Line 4. String of strain values, NTAB in number, one line required for each material (15F8.0)  
 1 - 8 Strain value for point 1  
 9 - 16 Strain value for point 2  
 17 - 24 Strain value for point 3  
 .  
 .  
 .  
 etc.

\*\*\*\*\*

\*\*\*\*\*

GROUP 4 RUBBLEIZATION DATA (Omit this group if NL=0)

Line 1. Rubble material data, one line required for each material  
 (I10,2F10.3)  
 1 - 10 Material number, N  
 11 - 20 Bulking parameter, ORT(N,7)  
 21 - 30 Failure stress ORT(N,8}

Line 2. Minimum boundary coordinate (E10.3)  
 1 - 10 Value of minimum Z coordinate for which element nodal points cannot pass through

Line 3. Material failure flag (IS)  
 1 - 10 Failure flag, NRFF  
 If this flag is non zero, a subroutine, READF is called. This subroutine defines a list of elements that can be removed (i.e.mined) on a particular increment. NRFF is the total number of increments allowed (10 max).

Line 4. Element mining data, omit if NRFF=0. (16I5)  
 1 - 5 Number of elements to be mined on increment 1, NME(1)  
 6 - 10 Number of elements to be mined on increment 2, NME(2)  
 11 - 15 Number of elements to be mined on increment 3, NME(3)  
 16 - 20 Number of elements to be mined on increment 4, NME(4)  
 .  
 .  
 .  
 etc.

Note: Currently 16 is the maximum number of elements that can be mined on any given increment.

Line 5. Specified elements to be mined, one line required for each increment, NRFF total, omit if NRFF=0. (16I5)  
 1 - 5 Element to be mined on this increment, MINES(INC,1)  
 6 - 10 Element to be mined on this increment, MINES(INC,2)  
 11 - 15 Element to be mined on this increment, MINES(INC,3)  
 16 - 20 Element to be mined on this increment, MINES(INC,4)  
 .  
 .  
 .  
 etc.

\*\*\*\*\*  
 \*\*\*  
 \*\*\*\*\*  
 \*\*\*

## GROUP 5 BOUNDARY CONDITIONS

Line 1. Ancillary control data (16I5)  
 1 - 5 Number of slip planes NNP  
 6 - 10 Number of singular points NSING  
 11 - 15 Number of boundary points NNBB  
 16 - 20 Number of reactions to be summed MPR  
 21 - 80 Indexing vector, automatic generation of NOPE array IB(I), I=1,12

Line 2. Boundary conditions (2I5,4F10.3) NNBE cards in ascending order of boundary nodes.  
 1 - 5 Boundary node number NBC(I)  
 9 u condition, 0=free, 1=fixed  
 10 v condition, 0=free, 1=fixed  
 11 - 20 Prescribed u displacement US(I,1)

21 - 30 Prescribed v displacement US(I,2)  
 31 - 40 Boundary angle (if inclined) ANG(I)  
 in degrees of X' axes from X.  
 Positive when counterclockwise.

Lines 3 and 4 are repeated in NSP blocks, each block representing a new slip plane. If NSP = 0, omit lines 3 and 4.

Line 3. Slip plane control data (2I5,G10.3)

1 - 5	Number of nodes on slip plane boundary	NSLP(N)
6 - 10	Angle flag of slip plane	IANG(N)
11 - 20	Thickness of slip plane	STHIK(N)

Line 4. Slip plane node list (16I5) NSLP(N)/16 cards

1 - 5	Node number	
6 - 10	Node number	ISLP(I,1), I = 1,NSLP(N)
11 - 15	Node number	

.  
 .  
 .  
 etc.

Line 6. Summed reaction nodes (16I5) (If MPR>0, otherwise omit)

1 - 5	Node number	
6 - 10	Node number	NOPR(I), I = 1,MPR
11 - 15	Node number	

.  
 .  
 .  
 etc.

\* \* \* \* \*

\*\*\*\*\*  
 \* NOTE!!! THE FOLLOWING LINES OF  
 \* GROUP 6 ARE REPEATED IN NLD BLOCKS \*  
 \* EACH BLOCK REPRESENTING A NEW LOAD \*  
 \* CASE  
 \*\*\*\*\*

## GROUP 6 LOADING DEFINITION

## Line 1. Ancillary load control data (2I15)

1 - 5 Initial stress counter ISTS (not used)  
 6 - 10 Increment control (Note LDTYPE applies to both prescribed loads and displacements.)  
 0 ... equal increments  
 1 ... increments in proportion to total according to the fac array  
 $\{X\} = FAC \{X\}$   
 inc inc total  
 2 ... independent set of loads for each increment

## Line 2. Loading title (20A4)

## Line 3. Loading control (8I5)

1 - 5 NSTRS (Not used)  
 6 - 10 Number of nodes where point loads are applied, NRE  
 11 - 15 Gravity load flag, if nonzero read lines 5 and 6.  
 16 - 20 Pressure load flag, if nonzero read lines 7, 8 and 9.  
 21 - 25 Temperature load flag, currently not available.  
 26 - 30 Centrifugal force flag, if nonzero read lines 5 and 6.

## Line 4. External Point load data (I10,3F10.3) NRE lines

1 - 10 Node number  
 11 - 20 Force in the X direction  
 21 - 30 Force in the Y direction

## Line 5. Gravity and centrifugal force data (3F10.3) two or three lines if NRC + NRG &gt; 0. Otherwise go to line 7.

1 - 10 Angle of Y or Z axes from gravity axes, clockwise positive. THEDA  
 11 - 20 Number of g's applied for this system (Only when NRC = 1) GRAV  
 21 - 30 Angular velocity in radians/unit time (only when NRC = 1) ANGVEL

## Line 6. Density (8F10.3)

1 - 10 Density for material 1 DENS{1}  
 11 - 20 Density for material 2 DENS{2}

  :  
  :  
  :

## Line 7. Pressure element control, if no pressure loads (i.e. NRPRS=0) leave out and go to line 10. (8I5)

1 - 5 Number of line elements on which pressures are applied LNE

Note each line 8 and 9 should be in sequence i.e., 8,1

9,1  
8,2  
9,2  
etc.

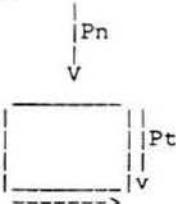
Line 8. Element nodes with applied pressure, one line/element (4I5)  
 1 - 5 Node 1                    0-----0  
 6 - 10 Node 2                0-----0-----0  
 11 - 15 Node 3              0---0---0---0  
 16 - 20 Node 4              NOPL(I), I=1, NSFR+1

Node numbers on element pressure surfaces numbered in  
 counterclockwise direction.

Line 9. Pressure data (8F10.3)  
 (a) same loads on each node of line element  
 1 - 10 Normal pressure (Pn)

11 - 20 Tangential pressure (Pt)

21 - 30 Zero



(b) Different loads at each node of line element Pn

1 - 10 Pn | Node 1

11 - 20 Pt |

21 - 30 |

31 - 40 | Node 2

etc.

Return to 8 for next line element.

Note (a) does not apply for linear elements

Line 10. Load increment data (I5)  
 1 - 5 Number of load increments NINC

Line 11. Load factor data (16F5.3)  
 1 - 5 Multiplier for increment 1 FAC{1}  
 6 - 10 Multiplier for increment 2 FAC{2}  
 .  
 .  
 .  
 etc.

Line 12. Output control data (16I5) NOUT(I), I=1,NIC  
 1 - 5 s 0 t    s = 1st iteration write out indicator  
                  t = final iteration write out indicator  
                  all printout is given up to and including s or t  
                  s or t = 0    no output  
                        = 1    displacements at nodal points  
                        = 2    reactions at constrained nodes as well  
                        = 3    stresses at gauss points as well  
                        = 4    residual forces at nodes as well  
 6 - 10 NOUT(2)  
 11 - 15 NOUT(3)  
 .  
 .  
 .  
 etc.

Line 13. Iteration and convergence data (I10,F10.3)  
 1 - 10 Maximum number of iterations NIT  
 11 - 20 Convergence factor in percent CONFAC  
       checks on  $100 \times (\text{Sum of } |\text{force residuals}|)$   
       divided by  $(\text{Sum of } |\text{applied forces}|)$

\*\*\*\*\*

#### GROUP 7 REDUCED PRINTOUT CONTROLS

Line 1. Print control (2I5)  
 1 - 5 Number of elements to be printed. If negative,  
       all elements printed.  
 6 - 10 Nodal point output control, if zero, no nodes  
       printed, if 1, all nodes printed.

Line 2. List of elements to be printed (16I5) (only if NELP > 0)  
 1 - 5 element number to be output  
 6 - 10 element number to be output  
 11 - 15 element number to be output  
 .  
 .  
 .  
 etc.

\*\*\*\*\*

## SCRUBS.MOV

This file is written in blocked binary form as follows:

Record 1. (22 words) the first twenty words are the title of the problem and the last two words are NE, the total number of elements, NP, the total number of nodal points, that is,

TITLE,NE,NP

Record 2. (2xNP+5xNE words) the first two lists are the nodal point coordinates, the next is the element connectivity, and the last is the element type.

(CORD(I,1),I=1,NP), (CORD(I,2),I=1,NP),  
{(NOP{4\*(K-1)+M},K=1,NE),M=1,4},  
{IMAT(I),I=1,NE}

The following records are repeated for each load increment.

Record 1'. (1 word) Increment number, TINC.

Record 2'. (3x2xNP words) Nodal point displacements, repeated 3 times.

{TDIS{1,I},TDIS{2,I},I=1,NP},  
{TDIS{1,I},TDIS{2,I},I=1,NP},  
{TDIS{1,I},TDIS{2,I},I=1,NP}

Record 3'. (4xNE words) Average element stresses

((SPLT(I,J),J=1,NE),I=1,4)

Record 4'. (4xNE words) Average element strains

((SPLT(I,J),J=1,NE),I=1,4)

## RUB.MOV

The records of this file are written to draw rubbleized groups of subelements to effectively display a failed region.

Record 1. (2 words, E15.5, I5) Increment number, TT, and total number of parts, ICNT.

Record 2. (4 words, 4I5) Number of "parts", NONE; number of nodal points, NUMNP; number of unfailed elements, NP2; number of entries in connectivity array, NCON.

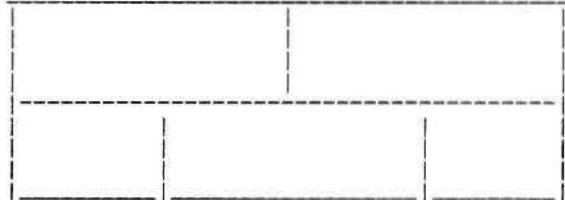
Record 3. (2 words, 2I5) Beginning element number, NP1; Ending element number, NP2.

Record 4. (3xNUMNP words, 6e12.5) Nodal point coordinates (CORD(I,1), CORD(I,2), 0.0), I=1, NUMNP)

Record 5. (4XNUMEL WORDS, 16I5) connectivity array (IXAR(I), I=1, NCON)

The above records provide geometry data for the original mesh. The following records are written, for each and every failed or rubble element, to describe the rubbleization as a "rubble" region.

Record 1'. (4 words, 4I5) The variables NONE, NJ, NPT AND NCON. These standard descriptors for the group of rubble subelements as used to describe a rubble region (see below). NONE is the number of "parts" for this group (i.e. 1), NJ is the number nodes (i.e. 12), NPT is the number of elements, (i.e. 5), and NCON is the number of entries in the connectivity (i.e. 20).



Record 2'. (2 words, 2I5) The variables NP1 and NP2 which are the smallest and largest element numbers associated with the subelement group.

Record 3'. (36 words, 6E12.5) the coordinates of the subelement group. (RN(J), ZN(J), 0.0), J=1, 12)

**SCRUBS.RST**

This file is the restart file that is used to both restart from and write subsequent restart files. A file is automatically written after each converged increment. To restart a run, the following lines of SCRUBS.DAT, along with the proper SCRUBS.RST file, are all that are required.

1. Group 1, line 1.
2. Group 3, all lines
3. Group 6, lines 10,11,12, and 13.

Note: Group 6, line 10 (NINC) must be changed to the number of remaining load increments:\*\*\*\*\*

## SCRUBS.LIS

This file contains input and output data formatted into a readable form. The input data is first written in its entirety, and includes a nodal mapping for the node numbers changed due to the slip plane addition.

After the input data is written, convergence information is output for each iteration. This information includes run times at various points in the program, and information on current loads, residuals, displacements, and plastic work. Convergence is reached when the normal of the residual sum ratio reaches the convergence percentage specified by the user. The flag NCHECK will be zero when convergence is attained.

The last portion of this file contains the output information. Output includes displacements and reactions for all boundary nodes, nodal displacements for all nodes if specified, and all stresses at each gauss point of any elements specified.

SCRUBS also has several checks for errors or incomplete solution which halt execution before the solution is obtained. For each of these an error message is output to the SCRUBS.LIS file. The following is a list of each of these stops, including a description and possible cause of the error.

## NO CONVERGENCE ON INCREMENT I

Solution could not be reached in the number of iterations specified. This is usually due to too much plastic flow and can often be corrected by reducing the loads.

NEGATIVE DET STOPPED AT ELEMENT NO = I

X1,Y1= x , y

X2,Y2= x , y

X3,Y3= x , y

X4,Y4= x , y

This indicates a element is improperly deformed as shown



Usually caused by too large of deformations.

PROGRAM HALTED IN SET STIFFNESS SPACE EXCEEDED

Bandwidth is too high and stiffness dimensioning is exceeded, bandwidth must be decreased.

PROGRAM HALTED IN SOLVE

NEGATIVE OR ZERO DIAGONAL STIFFNESS

Stiffness matrix is not positive definite, error in material parameters or problem has rigid body modes.

ERROR-- FRACTURE SCPACING (DELTA) MUST BE POSITIVE & NONZERO

Fracture spacing has been input improperly

ERROR-- HALTED IN SLIPP, ERROR IN CONNECTIVITY

When slip plane is being added, improper slip node numbering leads to this error. Caused by improper mesh generation or adding of a slip plane along a free edge.

ERROR-- NODE I NOT FOUND IN CONNECTIVITY ARRAY

Program cannot find new node number of a node in the nodal mapping. Caused by error in mesh generation.

\*\*\*\*\*  
\*\*\*\*\*

## **APPENDIX C**

### **SCRUBS CODE LISTING**

The following appendix contains the program listing of the computer code SCRUBS. This listing is included since SCRUBS was greatly updated in both logic and programming as this thesis was conducted. The subroutines will be found in alphabetical order. A summary of these subroutines with their descriptions can be found in appendix A.

---



---



---

- Subroutine BSUB:
- Conducts systematic back-substitution and solves for boundary displacements and reaction transformations.

---

- Written:
- Last modified: JUL 24 1984

---



---

- Called by: SCRUBS

---

#### SUBROUTINE BSUB

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

DIMENSION DIS(2,500)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NFP,ICS,  
 1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,  
 2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,  
 3 TPWORK

COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)

COMMON/BOUN/NBC(400),NFIX(400),U(800),ANG(400),TRC(800),

1 US(400,2)

COMMON/LDS/R1(2000),RL(2000),RT(2000)

COMMON/SCR/SK(20000),R

EQUIVALENCE (SK(1),DIS(1,1))

REWIND 3

BACKSPACE 4

ND=ND-1

KJ=NDF\*NP

DIS(NDF,NP)=R1(KJ)

R1(KJ)=0.

I=NDF

L=NP

NBUF=NBUF-2

IF(NNP EQ 1) BACKSPACE 4

GO TO 40

• Start systematic back substitution.

```

10      L=L-1
20      I=I-1
        NNP=SK(NBUF)
        IF(NNP.EQ.1) BACKSPACE 4
        NBUF=NBUF-1
        NSZ=SK(NBUF)
        IA=NBUF-NSZ
        NBUF=IA-3
        KJ=NDF*(L-1)+I
        GASH=R1(KJ)
        R1(KJ)=0.
        DO 30 J=1,NSZ
          LJ=L+(J+I-1)/NDF
          K=I+J-(LJ-L)*NDF
          GASH=GASH-SK(IA)*DIS(K,LJ)
30      IA=IA+1
        DIS(I,L)=GASH
40      IF(SK(NBUF+2).GT.0) GO TO 50
        R1(KJ)=DIS(I,L)
        DIS(I,L)=U(ND )
        ND=ND-1
50      CONTINUE
        IF(I+L-2) 60,90,60
60      IF(NNP.NE.1) GO TO 70
        READ(4) NBUF,(SK(II),II=NSK,NBUF)
        BACKSPACE 4
70      IF(I.NE.1) GO TO 20
80      I=NDF+1
        GO TO 10
90      CONTINUE

```

• Boundary displacements and reaction transformation.

```

NOSH=0
DO 110 M=1,NB

```

```
MOSH=NOSH+1
NOSH=MOSH+1
N=NBC(M)
NASH=2•N
MASH=NASH-1
RX=R1(MASH)
RY=R1(NASH)
IF(ANG(M) EQ 0.) GOTO 100
GASH=ANG(M)* 017453292
CS=COS(GASH)
TN=TAN(GASH)
DXC=DIS(1,N)*CS
DYC=DIS(2,N)*CS
DIS(1,N)=DXC-DYC•TN
DIS(2,N)=DYC+DXC•TN
RXC=RX•CS
RYC=RY•CS
RX=RXC-RYC•TN
RY=RYC+RXC•TN
100 TRC(MOSH)=TRC(MOSH)+RX
      TRC(NOSH)=TRC(NOSH)+RY
      RT(MASH)=RT(MASH)+RX
      RT(NASH)=RT(NASH)+RY
110 CONTINUE

      RETURN
      END
```

Subroutine CONRUB:

This subroutine checks for rubble/continuum interaction and computes the hydrostatic force in the rubble if a continuum element is in contact.

Written:

Last modified JUL 19 1984

Called by: RESIDUE

#### SUBROUTINE CONRUB(SIGRES,M)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,IPS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK,KNE
COMMON/FG/ FLAG(1000),BULK(1000,2),MINE(10,50),NME(10),GAMMA
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
```

SIGRES=0001

Computes area of rubble element.

K1=(M-1)\*4\*NSFR+1

K2=K1+NSFR

K3=K2+NSFR

K4=K3+NSFR

J1=NOP(K1)

J2=NOP(K2)

```

J3=NOP(K3)
J4=NOP(K4)
COE1=CORD(J2,1)-CORD(J4,1)
COE2=CORD(J3,2)-CORD(J1,2)
COE3=CORD(J3,1)-CORD(J1,1)
COE4=CORD(J4,2)-CORD(J2,2)
AREA=.5*(COE1*COE2+COE3*COE4)
IF(AREA.GE.BULK(M,2)) RETURN

```

---



---

- Computes hydrostatic compaction force since contact is established.
  - 
  -
- 
- 

```

BSTN=(AREA-BULK(M,2))/BULK(M,2)
SIGRES=BSTN*ABS(ORT(NMAT,1))
WRITE(6,10) M,AREA,BULK(M,2),SIGRES
10 FORMAT(' M,AREA,BULK(M,2),SIGRES !!!!!!!',I5,3E13.3)

```

RETURN

END

- 
- 
- Subroutine CONVG:
  - Determines the percent convergence.
  -

- Written:
- Last modified: JUL 19 1984
- 

---



---

- Called by: SCRUBS
- 

---



---

SUBROUTINE CONVG(NCHECK)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)  
 DIMENSION RAB(2)

```

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,MALGO,PWORK,
3 TPWORK
COMMON/LDS/R1(2000),RL(2000),RT(2000)
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2),
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
2 ,STRS(4),STRN(4),R(3),RMAX(2),RTOT(3)
COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),GAMMA

C      MASH=NCHECK=0
      MASH=0.0
      NCHECK=0.0
C      R(1)=R(2)=RMAX(1)=RMAX(2)=RTOT(1)=RTOT(2)=SUMD=SUMTD=0.
      R(1)=0.0
      R(2)=0.0
      RMAX(1)=0.0
      RMAX(2)=0.0
      RTOT(1)=0.0
      RTOT(2)=0.0
      SUMD=0.0
      SUMTD=0.0
      DO 20 I=1,NP
         DO 20 K=1,2
            MASH=MASH+1
            GISH=RT(MASH)
            GOSH=DIS(K,I)
            GESH=DISN(K,I)
            GASH=GISH-R1(MASH)
C      IF (I.GE.1.AND.I.LE.7) WRITE (6,10) I,K,RT(MASH),
C      1      R1(MASH),GASH
C      IF (I.GE.12.AND.I.LE.18) WRITE (6,10) I,K,RT(MASH),
C      1      R1(MASH),GASH
10     FORMAT(' *** I,K,RT(MASH),R1(MASH),GASH.'* 2I5,3E15.5)
            R1(MASH)=GASH
            R(K)=R(K)+GASH*GASH
            RTOT(K)=RTOT(K)+GISH*GISH
            SUMD=SUMD+GOSH*GOSH
            SUMTD=SUMTD+GESH*GESH
            GASH=ABS(GASH)
            IF(GASH.GT RMAX(K))RMAX(K)=GASH
20     CONTINUE
            R(3)=R(1)+R(2)
            RTOT(3)=RTOT(1)+RTOT(2)
            DO 30 K=1,3

```

```

R(K)=SQRT(R(K))
RTOT(K)=SQRT(RTOT(K))
IF(RTOT(K).LT. 1E-10) RTOT(K)=1.
30   R(K)=100.*R(K)/RTOT(K)
      SUMD=SQRT(SUMD)
      SUMTD=SQRT(SUMTD)
      IF(SUMTD.LT. 1E-20) SUMTD=1.
      IF(SUMD.LT. 1E-20) SUMD=1.
      SUM=100.*SUMD/SUMTD
      IF(SUM.GT.CONFAC) NCHECK=1
      WRITE(6,40)(RTOT(K),K=1,3),(R(I),I=1,3)
40   FORMAT(/5X,'X-NORM OF TOTAL LOADS =',E18.6/
1     5X,'Y-NORM OF TOTAL LOADS =',E18.6/
2     5X,'NORM OF SUM OF TOTAL LOADS =',E13.6/
3     5X,'X-NORM RESIDUAL RATIO =',E18.6/
4     5X,'Y-NORM RESIDUAL RATIO =',E18.6/
5     5X,'NORM OF RESIDUAL SUM RATIO =',E13.6,5X)
      WRITE(6,50)SUMD,SUMTD,SUM,NCHECK
50   FORMAT(/5X,'NORM OF CURRENT INCREMENTED DISPLACEMENT =',E18.6/
1     5X,'NORM OF CURRENT TOTAL INCREMENTED DISPLACEMENT =',E12.6/
2     5X,'NORM OF DISPLACEMENT RATIO =',E18.6,5X,'NCHECK =',I2)
      IF(IT.GT.1) GO TO 60
      RAB(1)=RMAX(1)
      RAB(2)=RMAX(2)
      GO TO 80
60   DO 70 I=1,2
70   RMAX(I)=100.*RMAX(I)/RAB(I)
80   WRITE(6,90)(RMAX(K),K=1,2)
90   FORMAT(/5X,'MAXIMUM X-RESIDUAL =',E18.6/
1     5X,'MAXIMUM Y-RESIDUAL =',E18.6)
      PRATIO=-100.
      TPWORK=TPWORK+PWORK
      IF(TPWORK.NE.0.)PRATIO=100.*PWORK/TPWORK
      WRITE(6,100)PWORK,TPWORK,PRATIO
100  FORMAT(/5X,'ITERATIVE PLASTIC WORK =',E18.6,2X,'INCREMENTAL'
1     ' PLASTIC WORK =',E18.6/
2     5X,'PERCENTAGE PLASTIC WORK =',F7.2)

      RETURN
      END

```

Subroutine CORNN:

This subroutine determines if node IX is a corner node.

Written:

Last modified: JUL 24 1984

Called by: SLIPP

SUBROUTINE CORNN(NADD,NSFR,NP,IFLAG,IX)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)

,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)

REAL CORN

J=0

10 J=J+1

IF(J.GT.4000) THEN

  WRITE(6,20)IX

20 FORMAT(' ERROR -- NODE ',I3,' NOT FOUND IN '

1 'CONNECTIVITY ARRAY')

  STOP

ELSE

  IF(NOP(J).NE.IX)GOTO 10

  CORN=FLOAT(J-1)/FLOAT(NSFR)

  CORN=CORN-IFIX(CORN)

  IF(CORN.NE.0.0)RETURN

  NADD=NSFR

If it is a corner node, IFLAG = 1.

IFLAG=1

```
      RETURN
      ENDIF
```

```
      END
```

•  
•  
• Subroutine DATALST:  
• Writes title, line numbers for files (presently not used).

•  
• Written:  
• Last modified: JUL 24 1984

•  
• Called by: SCRUBS  
•

#### SUBROUTINE DATALST(IOIN,IOSC,IOPR)

```
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
```

```
COMMON/DLIST/ LN,LNCT,TITL(20)
```

```
C      DIMENSION IA(8)
      DIMENSION IA(20)
```

```
10      LN=LNCT
      WRITE(IOPR,20) TITL
C20      FORMAT(6X,8A10//)
20      FORMAT(6X,20A4//)
1    14X,'10',8X,'20',8X,'30',8X,'40',8X,'50',8X,'60',8X,'70',8X,
2    '80',//,6X,'123456789012345678901234567890123456789012345678'
3    '90123456789012345678901234567890')  

C30      READ(IOIN,40) IA
30      READ(IOIN,40,END=70) IA
C40      FORMAT(8A10)
40      FORMAT(20A4)
C      IF.EOF(IOIN)) 70,50
50      WRITE(IOSC,40) IA
      WRITE(IOPR,60) IA
C60      FORMAT(6X,8A10)
60      FORMAT(6X,20A4)
```

```

LN=LN-1
IF(LN LE.0) GO TO 10
GO TO 30
70    ENDFILE IOSC
      REWIND IOSC

      RETURN
      END

```

---



---



---

• Subroutine DROP:  
 • Checks for elements about to fail and adjusts geometry for  
 failure.  
 •  
 • Written:  
 • Last modified: JUL 19 1984

---



---



---

• Called by: RESIDUE

---



---



---

• Subroutines called: RZBASEEXIT

---



---



---

#### SUBROUTINE DROP(NUMEL,NUMNP,AK)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,

2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,

3 TPWORK,KNE

COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),GAMMA

COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)

1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)

COMMON/BOUN/NBC(400),NFIIX(400),U(800),ANG(400),TRC(800),

1 US(400,2)

COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOFR(30),IONARY(1000)

DIMENSION IBTMS(4),MSN(2,4)

• Check for elements ready to fall.

---

```

DO 200 I=1,NUMNP
  FLG=FLAG(I)
  IF(FLG.EQ.4.) GO TO 20
  IF(FLG.EQ.8.) GO TO 10
  GO TO 200
10   CONTINUE
  NN=2*I
  ZOLD=CORD(I,2)-TDIS(2,I)
  ZNEW=AK
  GO TO 100
20   CONTINUE

```

• Drop to znew.

---

ZOLD=CORD(I,2)-TDIS(2,I)

• Find bottom element numbers.

---

```

IBTMS(1)=0
IBTMS(2)=0
IBTMS(3)=0
IBTMS(4)=0
ICNT=0
L=NSFR*4
DO 40 N=1,NUMEL
  DO 30 K=1,4
    KK=(N-1)*NSFR*4+K
    IF(NOP(KK).NE.I) GO TO 30
    ICNT=ICNT+1

```

```

IBTMS(ICNT)=N
30      CONTINUE
40      CONTINUE
      GO TO (50,60,70,70) ICNT

```

---

\* ICNT=1, top corner node drop.

---

```

50      IBOT=IBTMS(1)
      MX=IMAT(IBOT)
      IF(MX.GE.100) MX=MX-100
      AREA=BULK(IBOT,2)
      ALPH=ORT(MX,8)
      ANEW=AREA/ALPH
      IREF=(IBOT-1)*NSFR*4
      I1=NOP(IREF+1)
      I2=NOP(IREF+1+NSFR)
      I3=NOP(IREF+1+NSFR*2)
      I4=NOP(IREF+1+NSFR*3)
      CALL RZBASE(I,IBOT,I1,I2,I3,I4,R,Z,RLEN,ZBASE)
      ZLEN=ANEW/RLEN
      GO TO 90

```

---

\* ICNT=2, side boundary element drop.

---

```

60      CONTINUE
      DO 70 K=1,ICNT
      IBOT=IBTMS(K)
      IREF=(IBOT-1)*NSFR*4
      I1=NOP(IREF+1)
      I2=NOP(IREF+1+NSFR)
      I3=NOP(IREF+1+NSFR*2)
      I4=NOP(IREF+1+NSFR*3)
      ZAVG=(CORD(I1,2)+CORD(I2,2)+CORD(I3,2)+CORD(I4,2))* .25
      ZAVG=ZAVG-.25*(TDIS(2,I1)+TDIS(2,I2)+TDIS(2,I3)+  

      1          TDIS(2,I4))
      MX=IMAT(IBOT)
      IF(MX.GE.100) MX=MX-100

```

```

ALPH=ORT(MX,8)
AREA=BULK(IBOT,2)
IF(ZAVG.GT.ZOLD) GO TO 75
MX=IMAT(IBOT)
IF(MX.GE.100) MX=MX-100
ALPH=ORT(MX,8)
AREA=BULK(IBOT,2)
ANEW=AREA/ALPH
CALL RZBASE(I,IBOT,I1,I2,I3,I4,R,Z,RLEN,ZBASE)
ZLEN=ANEW/RLEN
75    CONTINUE
      GO TO 90

```

---

•  
•     ICNT=4, interior node drop.  
•  
•

---

```

70    CONTINUE
      ZBASSET=0.0
      RLENT=0.0
      ALPH=0.0
      AREA=0.0
      ZDST=0.0
      DO 80 K=1,ICNT
        IBOT=IBTMS(K)
        IREF=(IBOT-1)*NSFR*4
        I1=NOP(IREF+1)
        I2=NOP(IREF+1+NSFR)
        I3=NOP(IREF+1+NSFR*2)
        I4=NOP(IREF+1+NSFR*3)
        ZAVG=(CORD(I1,2)+CORD(I2,2)+CORD(I3,2)+CORD(I4,2))* 25
        ZAVG=ZAVG-.25*(TDIS(2,I1)+TDIS(2,I2)+TDIS(2,I3)+1
1      TDIS(2,I4))
        IF(ZAVG.GT.ZOLD) GO TO 80
        MX=IMAT(IBOT)
        IF(MX.GE.100) MX=MX-100
        ALPH=ALPH+ORT(MX,8)
        AREA=AREA+BULK(IBOT,2)
        CALL RZBASE(I,IBOT,I1,I2,I3,I4,R,Z,RLEN,ZBASE)
        RLENT=RLENT+RLEN
        ZBASSET=ZBASSET+ZBASE
        C1=CORD(I1,2)-TDIS(2,I1)
        C2=CORD(I2,2)-TDIS(2,I2)

```

```

C3=CORD(I3,2)-TDIS(2,I3)
C4=CORD(I4,2)-TDIS(2,I4)
ZD1=ABS(C3-C1)
ZD2=ABS(C2-C4)
ZZZ=.5*(ZD1+ZD2)
ZDST=ZDST+ZZZ
80      CONTINUE
ALPH=.5*ALPH
ANEW=AREA/ALPH
C      ZLEN=ANEW/RLEN

```

---

- ZLEN is recomputed here to circumvent errors when sloping elements are used, ZLEN is computed as the average of the bulked vertical distance between diagonals of one of the bottom elements.

---

```

ZLEN=.5*ZDST
ZLEN=ZLEN/ALPH
ZBASE=.5*ZBASSET
90      CONTINUE
ZNEW=ZBASE+ZLEN
IF(ZNEW.GT.ZOLD) ZNEW=ZOLD
100     CONTINUE
FLAG(I)=10.
DRP=ZNEW-ZOLD
CORD(I,2)=ZNEW
TDIS(2,I)=DRP
WRITE(6,110) I,ZNEW,ZOLD,DRP,AK,ZLEN,ZBASE,ANEW,RLEN,
1          ALPH,AREA
110     FORMAT(' I,ZNEW,ZOLD,DRP,AK,ZLEN,ZBASE,ANEW,RLEN,'
1          'ALPH,AREA',/I5,5E15.5/5E15.5)
IF(NSFR.NE.2)GO TO 140
DO 130 IE=1,4
N=(IBTMS(IE)-1)*8
DO 120 M=1,7,2
MM=M+N
IF(NOP(MM).NE.1)GO TO 120
MSN(1,IE)=NOP(MM+1)
IF(MM.EQ.7)MSN(2,IE)=NOP(MM-6)
120     CONTINUE
IM=MSN(1,IE)
II=MSN(2,IE)

```

```

        CORD(IM,2)=(CORD(I,2)+CORD(II,2))/2.0
130      TDIS(2,IM)=(TDIS(2,I)+TDIS(2,II))/2.0

```

---

- Until bulking is defined, fix nodes after fall.

---

```

140      NBTOP=NB
        DO 160 KK=1,NB
          ICHECK=NBC(KK)
          IF(ICHECK.EQ.1) NFIX(KK)=11
          IF(ICHECK.EQ.1) GO TO 170
          IF(ICHECK.LE.1) GO TO 160
          NBTOP=NB+1
          NBCN=I
          NFIXN=11
          DO 150 JJ==KK,NBTOP
            NBCMOV=NBC(JJ)
            NFIXMOV=NFIX(JJ)
            NBC(JJ)=NBCN
            NFIX(JJ)=NFIIXN
            NBCN=NBCMOV
            NFIIXN=NFIXMOV
150      CONTINUE
        GO TO 170
160      CONTINUE
        NBTOP=NB+1
        NBC(NBTOP)=I
        NFIX(NBTOP)=11
170      NB=NBTOP
        IF(NBTOP LE 400) GO TO 190
        WRITE(6,180)
180      FORMAT(' ***** NB EXCEEDS DIMENSIONED VALUE IN '
1           'DROP*****')
        CALL EXIT
190      CONTINUE
200      CONTINUE

```

---

- Find bulked elements, set BULK(N,1)=2.0

---

```

DO 210 I=1,NUMEL
  IREF=(I-1)*NSFR*4
  I1=NOP(IREF+1)
  I2=NOP(IREF+1+NSFR)
  I3=NOP(IREF+1+NSFR*2)
  I4=NOP(IREF+1+NSFR*3)
  SUM=FLAG(I1)+FLAG(I2)+FLAG(I3)+FLAG(I4)
  IF(SUM.NE.40.) GO TO 210
  BULK(I,1)=2.0
210   CONTINUE

      RETURN
      END

```

---



---



---

\* Subroutine FLAGE:

\* Makes impact node calculations and new node assignments.

\* Written:

\* Last modified: JUL 19 1984

---



---



---

\* Called by: SCRUBS

---



---



---

\* Subroutines called: NEWNOD EXIT

---



---



---

SUBROUTINE FLAGE (NUMNP,NUMEL,NTAPE,IIF)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,  
 1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,  
 2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,  
 3 TPWORK,KNE  
 COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),GAMMA  
 COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)

```
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)
DIMENSION IBIE(100)
```

•-----  
•-----  
•     Reads number of impact boundary nodes and writes it to  
•     SCRUBS.LIS.  
•-----

```
READ(NTAPE,10) NBIE
10     FORMAT(15)
      WRITE(6,20) NBIE
20     FORMAT(' NUMBER OF BOUNDARY IMPACT NODES IS',I5)
      IF(NBIE.GT.100) GO TO 140
      IF(NBIE.EQ.0) GO TO 80
      NCARD=1+NBIE/16
```

•-----  
•-----  
•     Writes impact node list after updating.  
•-----

```
30     WRITE(6,30)
      FORMAT(' IMPACT NODE LIST ')
      DO 80 K=1,NCARD
         KSTART=1+(K-1)*16
         KEND=KSTART+15
         READ(NTAPE,40) (IBIE(KK),KK=KSTART,KEND)
40     FORMAT(16I5)
      IF(IIF.GE.0) GOTO 60
      DO 50 KK=KSTART,KEND
50     CALL NEWNOD(IBIE(KK))
60     WRITE(6,70)(IBIE(KK),KK=KSTART,KEND)
70     FORMAT(1X,16I5)
80     CONTINUE
```

•-----  
•-----  
•     Makes impact node calculations.  
•-----

```
DO 100 I=1,NUMNP
```

```

ICOUNT=0
FLAG(I)=0.0
L=NSFR*4
DO 90 J=1,NUMEL
  DO 90 K=1,L,NSFR
    KK=NSFR*4*(J-1)+K
    IF(NOP(KK).EQ.I) ICOUNT=ICOUNT+1
90   CONTINUE
    IF(ICOUNT.EQ.2) FLAG(I)=2.0
    IF(ICOUNT.EQ.1) FLAG(I)=3.0
100  CONTINUE
    IF(NSFR.NE.2) GOTO 120
    NOP8=NUMEL*8
    DO 110 I=2,NOP8,2
      MDSD=NOP(I)
110   FLAG(MDSD)=20.0
120   CONTINUE
    DO 130 I=1,NBIE
      IFIX=IBIE(I)
      IF(FLAG(IFIX).EQ.2.) FLAG(IFIX)=6.
      IF(FLAG(IFIX) EQ 3.) FLAG(IFIX)=7.
130   CONTINUE
    RETURN

```

---



---



---

\* Error trap for excessive number of boundary nodes.

---



---

```

140      WRITE(6,150) NBIE
150      FORMAT(' NBIE IS INPUT AS',I5,'BUT CANNOT BE LARGER
     +      THAN 100')
      CALL EXIT
END

```

Subroutine GAUSSP: Initializes gaussian constants.

Written:

Last modified: MAR 19 1984

Called by: GDATA

SUBROUTINE GAUSSP(M,X,W)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)  
DIMENSION X(6),W(6)

GO TO (10,20,30,40,50,60),M

10       X(1)=0.

          W(1)=1.

          RETURN

20       X(1)=-0.577350269189626

          W(1)=1.

          GO TO 70

30       X(1)=-0.774596669241483

          X(2)=0.

          W(1)=0.55555555555556

          W(2)=0.888888888888889

          GO TO 70

40       X(1)=-0.861136311594053

          X(2)=-0.339981043584856

          W(1)=0.347854845137454

          W(2)=0.652145154862546

          GO TO 70

50       X(1)=-0.906179845938664

          X(2)=-0.538469310105683

          X(3)=0.

          W(1)=0.236926885056189

          W(2)=0.478628670499366

          W(3)=0.568888888888889

          GO TO 70

```

60      X(1)=-0.932469354203152
       X(2)=-0.661209386466265
       X(3)=-0.238619186083197
       W(1)=0.171324492379170
       W(2)=0.360761573048139
       W(3)=0.467913934572691
70      N=M/2
       DO 80 J=1,N
          NASH=M+1-J
          X(NASH)=-X(J)
80      W(NASH)=W(J)

      RETURN
      END

```

---



---



---



---



---



---

\* Subroutine GDATA:

\* Reads geometrical data, boundary conditions, and gaussian  
\* integration data.

\* Written:

\* Last modified: JUL 24 1984

\* Called by: SCRUBS

\* Subroutines called: SLIPNODEXY

\* NEWNOD GAUSSP

SUBROUTINE GDATA

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,

2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO, PWORK,

## 3 TPWORK

```

COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
COMMON/BOUN/NBC(400),NFX(400),U(800),ANG(400),TRC(800),
1   US(400,2)
COMMON/GID/XG(6),CG(6),XMG(6),CMG(6),NGAUS,MGAUS,MCN
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1   NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
DIMENSION NOPE(12),DX(3),QUID(3),IB(12),NOPD(12)
REAL CORDDUM(1000,2)

```

---

- - Reads number of slip planes (NNP), singular points (NSING),
  - boundary points (NNBB), summed reaction nodes (MPR),
  - indexing vector (IB), and writes to SCRUBS.LIS.
  -
- 

```

READ(5,5) NNP,NSING,NNBB,MPR,(IB(I),I=1,12)
5   FORMAT(16I5)
IF(NB.GT.0.AND.NNBB.EQ.0) NNBB=NB
WRITE(6,7)NNP,NSING,MPR,(IB(I),I=1,12)
7   FORMAT(1X,/
1     ' NUMBER OF SLIP PLANES-----',I3//'
2     ' NUMBER OF SINGULAR POINTS----',I3//'
3     ' NO OF SUMMED REACTION NODES--',I3//'
4     ' IB VECTOR-----',12I4)
IF(IB(1).NE.0) GO TO 40
DO 10 I=1,12
10  IB(I)=NSFR
IF(NSFR-2)40,30,20
C20  IB(5)=IB(6)=IB(11)=IB(12)=1
20  IB(5)=1
IB(6)=1
IB(11)=1
IB(12)=1
GO TO 40
C30  IB(4)=IB(8)=1
30  IB(4)=1
IB(8)=1
40  CONTINUE
DO 50 II=1,NP
      DO 50 JJ=1,NCORD
50  CORD(II,JJ)= 0.

```

• Reads nodal point data from QMESH9.DAT.

60           READ(9) (CORDDUM(N,1),CORDDUM(N,2),N=1,NP)

DO 60 N=1,NP  
CORD(N,1)=CORDDUM(N,1)

CORD(N,2)=CORDDUM(N,2)

• Reads element data from QMESH9.DAT.

70           IF (NCN.EQ.8) GO TO 70  
READ(9)((NOP(NCN\*(K-1)+M),M=1,NCN),IMAT(K)),K=1,NE  
GO TO 80  
READ(9)((NOP(8\*(K-1)+1),NOP(8\*(K-1)+3),NOP(8\*(K-1)+5),  
NOP(8\*(K-1)+7),NOP(8\*(K-1)+2),NOP(8\*(K-1)+4),  
NOP(8\*(K-1)+6),NOP(8\*(K-1)+8),IMAT(K)),K=1,NE)

• Reads boundary data from QMESH9.DAT.

80           IF(NNBB.LE.0) GOTO 100

DO 90 I=1,NNBB

90           READ (5,95) NBC(I),NFIIX(I), (US(I,J),J=1,NDF) ,ANG(I)

95           FORMAT(2I5,4F10.3)

100          CONTINUE

• Adds slip plane if needed.

IF(NNP.GT.0)CALL SLIPP

• Generates coordinates for intermediate nodes.

---

C IF(NSFR.GT.1) CALL NODEXY  
IF(NSING.EQ.0) GOTO 140  
IF(NNP.GT.0) CALL NEWNOD(NSING)

---

• Singular point calculations.

---

```

DO 130 K=1,NE
    DO 110 I=1,8
        ICK=NOP((K-1)*8+I)
        IF(ICK.EQ.NSING) GOTO 120
110      CONTINUE
        GOTO 130
120      IFP=I-2
        IF(IFP.EQ.-1) IFP=7
        IF(IFP.EQ.0) IFP=8
        NFAR=NOP((K-1)*8+IFP)
        XQP=0.25*CORD(NFAR,1)+0.75*CORD(NSING,1)
        ZQP=0.25*CORD(NFAR,2)+0.75*CORD(NSING,2)
        IQP=I-1
        IF(IQP.EQ.0) IQP=8
        NQP=NOP((K-1)*8+IQP)
        CORD(NQP,1)=XQP
        CORD(NQP,2)=ZQP
        IFP=I+2
        IF(IFP.EQ.9) IFP=1
        IF(IFP.EQ.10) IFP=2
        NFAR=NOP((K-1)*8+IFP)
        XQP=0.25*CORD(NFAR,1)+0.75*CORD(NSING,1)
        ZQP=0.25*CORD(NFAR,2)+0.75*CORD(NSING,2)
        IQP=I+1
        IF(IQP.EQ.9) IQP=8
        NQP=NOP((K-1)*8+IQP)
        CORD(NQP,1)=XQP
        CORD(NQP,2)=ZQP
130      CONTINUE

```

```

140      CONTINUE
        IF(NB.EQ.0) GO TO 180


---


*          Writes fixed boundary conditions to SCRUBS.LIS.
*
*-----



145      WRITE(6,145)
145      FORMAT(' BOUNDARY CONDITIONS'/
1        ' NODE FIX X VALUE Y VALUE ANGLE')
        DO 150 I=1,NB
150      WRITE (6,95) NBC(I),NFIIX(I), (US(I,J),J=1,NDF),ANG(I)
        IF(MPR.EQ.0) GO TO 180
        READ (5,5)(NOPR(I),I=1,MPR)
        IF(IIF.GE.0) GOTO 170
        DO 160 I=1,MPR
160      CALL NEWNOD(NOPR(I))
170      WRITE(6,5)(NOPR(I),I=1,MPR)
180      CONTINUE


---


*          Reads gaussian integration data and writes constants to SCRUBS.LIS.
*
*-----



190      WRITE(6,190)
190      FORMAT(' GAUSSIAN INTEGRATION CONSTANTS')
        CALL GAUSSP(NGAUS,XG,CG)
        DO 210 I=1,NGAUS
            WRITE(6,200)XG(I),CG(I)
200      FORMAT(2F15.8)
210      CONTINUE
        CALL GAUSSP(MGAUS,XMG,CMG)
        DO 220 I=1,MGAUS
            WRITE(6,200)XMG(I),CMG(I)
220      RETURN
        END

```

Subroutine INVAR:  
Calculates invariants and sets the yield stress accordingly.

Written:  
Last modified: JUL 24 1984

Called by: RESIDUESTIFM

#### SUBROUTINE INVAR (SSS)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK
COMMON/INV/SMEAN,ST J2,ST J3,SIGMA,PHI,APNI,STN,Cphi,YIELD
COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST,
1 TABSTN(10),TABSTR(10,15)
DIMENSION SSS(4)
```

Calculates invariants.

```
X=SSS(1)
Y=SSS(2)
Z=SSS(4)
XY=SSS(3)
SMEAN=(X+Y+Z)/3.
```

```
C     SSS(1)=X=X-SMEAN
      TEMP=X-SMEAN
      X=TEMP
      SSS(1)=TEMP
C     SSS(2)=Y=Y-SMEAN
```

```

TEMP=Y-SMEAN
Y=TEMP
SSS(2)=TEMP
C      SSS(4)=Z=Z-SMEAN
      TEMP=Z-SMEAN
      Z=TEMP
      SSS(4)=TEMP
      STJ2=XY*XY+.5*(X*X+Y*Y+Z*Z)
      IF(STJ2.EQ.0.0) STJ2= 00001
      STJ3=Z*(Z*Z-STJ2)
      SIGMA=SQRT(STJ2)
      STN=-2.5980762113*STJ3/(STJ2*SIGMA)
      IF(STN.LT.1.0.AND.STN.GT.-1.0) GO TO 10
      IF(STN.LE.-.9999) STN=-.9999
      IF(STN GE .9999) STN=.9999
10      CONTINUE
      PHI=ASIN(STN)/3.
      CPHI=COS(PHI)
      CON=1.73205080756888
      MYIELD=NYIELD
      IF(NYIELD.GT.100)MYIELD=NYIELD-100
      GO TO (20,30,40,50),MYIELD

```

---

- Von Mises yield condition.
- 

---

```

20      YIELD=CON*SIGMA
      RETURN

```

---

- Tresca yield condition.
- 

---

```

30      YIELD=2.*SIGMA*CPHI
      RETURN

```

---

- Drucker yield condition.
-

---

40           YIELD=3.\*ALPHA\*SMEAN+SIGMA  
RETURN

---

•  
•         Beltrami yield condition.  
•

---

50           YIELD=SQRT((3.+6.\*PR)\*SMEAN\*SMEAN+2.\*(1.-PR)\*STJ2)  
RETURN  
END

---

•  
•  
•         Subroutine JOINTM:  
•         Calculates incremental stresses and residuals.

---

•  
•         Written:  
•         Last modified: JUL 19 1984

---

•  
•  
•         Called by: RESIDUE

---

•  
•  
•         Subroutines called: ROTATE

---

SUBROUTINE JOINTM(L,STRN,STRS,MOSH,YIELD,PSTRN)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

DOUBLE PRECISION K,MU,LAMB

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1         NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,

2         NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,

```

3      TPWORK
COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1      ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
2      ,SIG(4),PSIG(4),DSIG(4),EP(4),NG(16),NGSTP(16)
DIMENSION STRN(4),STRS(4),T(4),TT(4),E(4)

```

---

- Assigns material parameters.

---

```

K=-ORT(L,1)
G=-ORT(L,2)
CO=ORT(L,3)
MU=ORT(L,4)
TH=ORT(L,5)
FAIL=ORT(L,7)
DEL=ORT(L,9)
GS=ORT(L,10)

```

---

- Checks for delta and Gs equal to zero.

---

```

IF(GS EQ 0.0)GS=1.0
IF(DEL GT.0) GOTO 20
WRITE(6,10)
10     FORMAT(/,' ERROR-- FRACTURE SPACING (DELTA) MUST BE'
&           ' POSITIVE & NONZERO')
STOP

```

---

- Rotates incremental strain vector to local system.

---

```

•      z or y/ / /
•      ' / / / <- crack array
•      | / / /
•      | / / /
•      | / / /
•      | / / /

```

- | / /
  - | / / <- angle theta
  - -----> r or x
  - 
  - Coordinate system for crack array
  -
- 

20               CONTINUE  
 STRN(3)=STRN(3)/2.  
 CALL ROTATE(STRN,E,TH)

- - Gets total stress vector and rotates.
  -
- 

DO 30 I=1,4  
 STRS(I)=TSTS(I,MOSH)  
 30               CONTINUE  
 CALL ROTATE(STRS,TT,TH)

- - Solves for incremental stresses.
  -
- 

TRTDOT=(K-2.\*G/3.)\*(E(1)+E(2)+E(4))  
 T(1)=2.\*G\*E(1)+TRTDOT  
 T(2)=2.\*G\*E(2)+TRTDOT  
 C     T1TOT=TT(1)+T(1)  
 T2TOT=TSTS(2,MOSH)+T(2)

- - Tests for tensile failure of crack.
  - However, for this application allows tensile strength.
  -
- 

C               FAIL=0.0  
 C     IF(T1TOT.GT.FAIL) THEN  
 C       WRITE(6,\*)' FAILURE STRESS= ',T1TOT

```

C      T(1)=0.0
C      ENDIF
C      FAIL=0.0
C      IF(T2TOT.GT.FAIL) THEN
C          WRITE(6,*)' FAILURE STRESS= ',T2TOT
C          TSTS(2,MOSH)=FAIL
C          T(2)=0.0
C      ENDIF
T(3)=2.*G*E(3)/(1.+G/DEL/GS)
T(4)=2.*G*E(4)+TRTDOT

```

---

- Checks for plastic slip.

---

```

C      F=DABS(TT(3)+T(3))+MU*(TT(1)+T(1))-CO
C      F=DABS(TT(3)+T(3))+MU*(TT(2)+T(2))-CO
IF(F.LE.0) GOTO 50
XX=(2.*G/(1.+G/DEL/GS))
Y=XX*E(3)+TT(3)

```

---

- Solves for plastic strain.

---

```

C      IF (Y.LE.0) LAMB=E(3)+(CO-MU*(TT(1)+T(1))+TT(3))/XX
C      IF (Y.GT.0) LAMB=E(3)-(CO-MU*(TT(1)+T(1))-TT(3))/XX
          IF (Y.LE.0) LAMB=E(3)+(CO-MU*(TT(2)+T(2))+TT(3))/XX
          IF (Y.GT.0) LAMB=E(3)-(CO-MU*(TT(2)+T(2))-TT(3))/XX

```

---

- Determines shear stress for plastic condition.

---

```

40      CONTINUE
ELAS=E(3)-LAMB
T(3)=2.*G*ELAS/(1.+G/DEL/GS)
EPSTN(5,MOSH)=EPSTN(5,MOSH)+LAMB

```

```
50      CONTINUE
C     YIELD=DABS(TT(1)+T(1))*MU
      YIELD=DABS(TT(2)+T(2))*MU
```

•  
•       Rotates incremental stress matrix to global system.  
•  
-----

```
CALL ROTATE(T,STRS,-TH)
STRN(3)=STRN(3)*2.
```

```
RETURN
END
```

•  
•  
•       Subroutine LDATA: Reads load control data.  
•  
•  
•       Written:  
•       Last modified:JUL 14 1984  
•  
-----

•  
•  
•       Called by: SCRUBS  
•  
-----

•  
•  
•       Subroutines called:SFRAUX
 NEWNOD  
•  
-----

#### SUBROUTINE LDATA(IIF)

```
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
DIMENSION R(3)
DIMENSION NOPL(4),PS(4,2),PQ(2),DJ(2),DENS(10)
COMMON//FG// FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),GAMMA
COMMON//CONTR//TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
```

```

1      NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2      NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO, PWORK,
3      TPWORK
      COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
      COMMON/GID/XG(6),CG(6),XMG(6),CMG(6),NGAUS,MGAUS,MCN
      COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST
1      ,TABSTN(10,15),TABSTR(10,15)
      COMMON/LDS/R1(2000),RL(2000),RT(2000)
      COMMON/NUME/P(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),
1      NOFE(12),DISE(2,12),RP,RPB,XYP(3)
      COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1      ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
      COMMON/GRAV/GRAV

```

---

- Reads and writes load control data.

---

```

      READ(5,10)TITLE
10     FORMAT(20A4)
      READ(5,20)NSTRS,NRE,NRG,NRPRS,NRT,NRC
20     FORMAT(8I5)
      WRITE(6,30)TITLE,ILD,NSTRS
30     FORMAT(1X,20A4,5X, 'LOAD CASE=',I3,I5)
      WRITE(6,40)NRE,NRG ,NRPRS,NRT,NRC
40     FORMAT(' NRE=',I3,2X,'NRG=',I2,2X,'NRPRS=',I2,2X,'NRT=',I2,2X,'NRC=',I2)
1     IF(NRE EQ 0) GO TO 80

```

---

- Reads external loads at nodes.

---

```

      WRITE(6,50)
50     FORMAT(' LOADS FROM CARDS ')
      DO 70 I=1,NRE
      READ(5,60) NQ,(R(K),K=1,NDF)
60     FORMAT(I10,3F10.3)

```

---

\* Changes node no. to new node no. if slip plane has been added.

```
IF(IIF.LT.0)CALL NEWNOD(NQ)
WRITE(6,60) NQ,(R(K),K=1,NDF)
DO 70 K=1,NDF
  IC=(NQ-1)*NDF+K
  RL(IC)=RL(IC)+R(K)
```

70 CONTINUE

\* Reads gravity, centrifugal and density data.

```
80      CONTINUE
       IF((NRC+NRG).EQ.0) GOTO 230
       READ(5,90)THETA,GRAV,ANGVEL
90      FORMAT(8E10.3)
       WRITE(6,100)THETA,GRAV,ANGVEL
100     FORMAT(' ANGLE=',F7.2,' GRAVITY CONSTANT=',E10.4,' ANGULAR VELOC'
1      ' ITY=',F10.4)
       READ (5,90)(DENS(I),I=1,NMAT)
       WRITE(6,90)(DENS(I),I=1,NMAT)
       DENSAV=0.0
       DO 110 IA=1,NMAT
       DENSAV=DENSAV+DENS(IA)
       GAMMA=DENSAV*GRAV/NMAT
       GUSH=0.
       IF(NRC.EQ.0) GO TO 120
       GUSH=ANGVEL*ANGVEL/GRAV
120     THETA=THETA/57.295779514
C      WRITE(6,130)
130     FORMAT(' DENSITY CONSTANTS FOR VARIOUS ELEMENTS')
       DO 220 M=1,NE
         L=IMAT(M)
         IF(L.GT.NMAT)L=L-100
         THICK=ORT(L,6)
         DENSE=DENS(L)
C      PQ(1)=PQ(2)=0.
         PQ(1)=0.
         PQ(2)=0.
         IF(DENSE.EQ.0.)GO TO 220
```

```

        IF(NRC.NE.0)GOTO 150
C      DO 140 IJ=1,NMAT
C140    DENS(IJ)=DENS(IJ)*GRAV
150    IF(NRG.EQ.0) GO TO 170
        PQ(1)=DENSE*SIN(THETA)*GRAV
        PQ(2)=-DENSE*COS(THETA)*GRAV
C      WRITE(6,160)M,L,PQ(1),PQ(2),DET
160    FORMAT(2I10,2F15.5,3X,D12.3)
170    NASH=NCN*(M-1)
        DO 190 K=1,NCN
            MASH=NOP(NASH+K)
            DO 180 I=1,NCORD
                XYE(I,K)=CORD(MASH,I)
            NOPE(K)=MASH
            DO 210 IGAUS=1,NGAUS
                DO 210 JGAUS=1,NGAUS
                    G=XG(IGAUS)
                    H=XG(JGAUS)
                    CALL SFR(G,H)
                    CALL AUX(M)
                    DV=DET*CG(IGAUS)*CG(JGAUS)
                    IF(NPP.EQ.2)DV=DV*RP*6.28318530718
                    IF(NCORD.EQ.3)DV=DV*XYP(3)
                    IF(THICK.NE.0.)DV=DV*THICK
                    PQ(1)=PQ(1)+DENSE*GUSH*XYP(1)
                    DO 200 I=1,NCN
                        IC=(NOPE(I)-1)*2
                        DO 200 K=1,2
                            IC=IC+1
                            RL(IC)=RL(IC)+PQ(K)*P(I)*DV
200    CONTINUE
210    CONTINUE
220    CONTINUE
230    IF(NRPRS.EQ.0) GO TO 330
        READ(5,20)LNE
        WRITE(6,20)LNE
        NLN=NSFR+1

```

---

- 
- 
- Reads pressure data.
- 
- 

---

DO 320 LNEW=1,LNE

READ (5,20)(NOPL(J),J=1,NLN)

---

- Changes node no. to new node no. if slip plane has been added.

---

```
DO 240 J=1,NLN
240   IF(HF.LT.0)CALL NEWNOD(NOPL(J))
      WRITE(6,20)(NOPL(J),J=1,NLN)
```

---

- Reads pressure load.

---

```
READ (5,250)((PS(I,J),I=1,NLN),J=1,NDF)
250   FORMAT(8F10.3)
      IF(PS(3,1).NE.0.)GO TO 270
      PRT=PS(2,1)
      DO 260 I=1,NLN
         PS(I,1)=PS(1,1)
260   PS(I,2)=PRT
      WRITE(6,250)((PS(I,J),I=1,NLN),J=1,NDF)
      H=-1.
      DO 280 J=1,NLN
         MASH=NOPL(J)
         DO 280 K=1,NCORD
            XYE(K,J)=CORD(MASH,K)
280   CONTINUE
      DO 310 IGAUS=1,NGAUS
         G=XG(IGAUS)
         CALL SFR(G,H)
         DO 300 I=1,NCORD
            GASH=GOSH=GISH=0.
            GASH=0.
            GOSH=0.
            GISH=0.
            DO 290 K=1,NLN
               GASH=GASH+XYE(I,K)*P(K)
               IF(I.GT.2) GO TO 290
               GOSH=GOSH+PS(K,I)*P(K)
               GISH=GISH+XYE(I,K)*DEL(I,K)
```

```

290      CONTINUE
        XYP(I)=GASH
        IF(I.GT.2) GO TO 300
        PQ(I)=GOSH
        DJ(I)=GISH
300      CONTINUE
        DV=CG(JGAUS)
        IF(NCORD.EQ.3)DV=DV*XYP(3)
        IF(NPP.EQ.2)DV=6.2831853072*DVE*XYP(1)
        DV1=DV*DJ(1)
        DV2=DV*DJ(2)
        AY=DV1*PQ(1)+DV2*PQ(2)
        AX=DV1*PQ(2)-DV2*PQ(1)
        DO 310 I=1,NLN
          NASH=2*NOPL(I)
          MASH=NASH-1
          RL(MASH)=RL(MASH)+P(I)*AX
          RL(NASH)=RL(NASH)+P(I)*AY
310      CONTINUE
320      CONTINUE
330      CONTINUE
C      WRITE(6,340)
340      FORMAT(' TOTAL NON-ZERO LOADS'/2X,
1      NODE  X VALUE  Y VALUE)
           I=1
350      IF(RL(I).EQ.0.) GO TO 360
           K=(10*I/NDF+9) / 10
           J=(K-1)*NDF+1
           JND=J+NDF-1
C      WRITE(6,60) K, (RL(I), I=J,JND)
           I=JND
360      CONTINUE
           I=I+1
           IF(I.LE.NSZF) GO TO 350

      RETURN
      END

```

Subroutine LINEAR:  
Helps to update stress and strain.

Written:  
Last modified: JUL 19 1984

Called by: RESIDUE

#### SUBROUTINE LINEAR(STRN,STRS,W)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD

COMMON/NUME/F(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),

1 NOPE(12),DISE(2,12),RP,RPB,XYP(3)

COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST,

1 TABSTN(10),TABSTR(10,15)

DIMENSION STRN(4),STRS(4)

DO 20 I = 1,2

DO 20 J = 1,2

GASH=0.

DO 10 K = 1,NCN

10 GASH=GASH+DISE(I,K)\*DI(J,K)

20 DIJ(I,J)=GASH

Calculate strain at a point.

STRN(1)=DIJ(1,1)  
STRN(2)=DIJ(2,2)  
STRN(3)=(DIJ(1,2)+DIJ(2,1))  
STRN(4)=0.

• Calculate rotation, W.

---

```

W=.5*(DIJ(2,1)-DIJ(1,2))
IF(NPP.NE.2) GO TO 40
GISH=0.
DO 30 K=1,NCN
30 GISH=GISH+DISE(1,K)*P(K)
IF(RP.EQ.0.) RP=.000001
STRN(4)=GISH/RP
40 IF(NPP.EQ.1)STRN(4)=-PPR*(STRN(1)+STRN(2))
GASH=CLAME*(STRN(1)+STRN(2)+STRN(4))
DO 50 I=1,4
50 STRS(I)=GM*STRN(I)+GASH
STRS(3)=(STRS(3)-GASH)*.5

      RETURN
      END

```

---

• Subroutine MAKEEL.

• This subroutine adds a new element to the connectivity containing  
corner nodes I and K.

• Written:

• Last modified: JUL 19 1984

• Called by: SLIPP

SUBROUTINE MAKEEL(MMM,I,K,IANG)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,  
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,

```

2      NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3      TPWORK,KNE
4      COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1      ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)

JSTART=I
IF(IANG.EQ.2)GOTO 10
IF(CORD(I,2).LT.CORD(K,2))JSTART=K
GOTO 20
10     IF(CORD(I,1).GT.CORD(K,1))JSTART=K
20     CONTINUE
L=NSFR*4
DO 30 M=1,L,NSFR
MM=MMM+M
IF(NOP(MM).NE.JSTART)GOTO 30
JSTRT=MM
IFLAG=M
30     CONTINUE
NEW=NE*L+1
NOP(NEW)=NOP(JSTRT)
DO 40 N=1,NSFR
NEW=NEW+1
IF(IFLAG.EQ.1)JSTRT=JSTRT+L
JSTRT=JSTRT-1
40     NOP(NEW)=NOP(JSTRT)
DO 50 N=1,NSFR
NOP(NEW+1)=NOP(NEW)+1
50     NEW=NEW+1
IX=NSFR-1
DO 60 N=1,IX
60     NOP(NEW+N)=NOP(NEW-NSFR-N)+1
NEW=NEW+IX
DO 70 N=NSFR,1,-1
70     NEW=NEW+1
NOP(NEW)=JSTART+N
NE=NE+1
IMAT(NE)=NMAT-NL

RETURN
END

```

- 
- Subroutine MOD:
- Forms D matrix for different stress/strain cases.
- 
- Written:
- Last modified: JUL 14 1984
- 
- 
- 
- Called by: RESIDUE STIFM
- 
- 
- 

SUBROUTINE MOD(L,M)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

& NCORD

COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)

COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST

YM=ORT(L,1)

PR=ORT(L,2)

YST=ORT(L,3)

HM=ORT(L,4)

ALPHA=ORT(L,5)

DELTA=ORT(L,9)

GS=ORT(L,10)

Allows for bulk properties.

IF(YM.LT.0.0) GO TO 30

PPR=PR/(1.-PR)

GM=YM/(1.+PR)

Note!!!!!!\*\*\*\*\* GM=2•SHEAR MODULUS \*\*\*\*\*

---

```

CLAME=PR•GM/(1.-2.•PR)
IF(M.EQ.1)RETURN
D(3,3)=GM•.5
C      D(1,3)=D(3,1)=D(2,3)=D(3,2)=0.
D(1,3)=0.0
D(3,1)=0.0
D(2,3)=0.0
D(3,2)=0.0
IF(NPP.EQ. 1) GO TO 10
YM=YM/(1 -PR•PR)
PR=PR/(1 -PR)
10      CONTINUE

```

---

For plane stress/strain cases.

---

```

CD=YM/(1.-PR•PR)
CDU=CD•PR
C      D(1,1)=D(2,2)=CD
D(1,1)=CD
D(2,2)=CD
C      D(1,2)=D(2,1)=CDU
D(1,2)=CDU
D(2,1)=CDU
IF(NPP.NE.2) GO TO 20

```

---

D matrix for axisymmetric case.

---

```

D(4,4)=CD
C      D(1,4)=D(4,1)=D(2,4)=D(4,2)=CDU
D(1,4)=CDU
D(4,1)=CDU
D(2,4)=CDU
D(4,2)=CDU

```

```

C      D(3,4)=D(4,3)=0.
      D(3,4)=0.
      D(4,3)=0.
20    CONTINUE
      PR=ORT(L,2)
      RETURN
30    CONTINUE
      BM=YM
      GM=ABS(PR)*2.

```

---

\* Note!!!!!!\*\*\*\*\* GM=2\*SHEAR MODULUS \*\*\*\*\*

---

```

CLAME=BM-GM/3.
PR=.5
PPR=PR/(1.-PR)
IF(M EQ.1) RETURN
D(1,1)=CLAME+GM
D(2,2)=CLAME+GM
D(3,3)=GM/2.
IF(ORT(L,2).LT.0) D(3,3)=D(3,3)/(1.+GM/2./DELTA/GS)
D(1,2)=CLAME
D(1,3)=0.0
D(2,1)=CLAME
D(2,3)=0.0
D(3,1)=0.0
D(3,2)=0.0
IF(NPP.NE.2) GO TO 40
D(4,4)=CLAME+GM
D(1,4)=CLAME
D(2,4)=CLAME
D(3,4)=0.0
D(4,1)=CLAME
D(4,2)=CLAME
D(4,3)=0.0

```

```

40    RETURN
END

```

Subroutine NEWNOD:  
This subroutine finds the new node number of node N.

Written:  
Last modified: JUL 19 1984

Called by: FLAGEGDATAALDATA  
SLIPP

#### SUBROUTINE NEWNOD(N)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK,KNE
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2),
1 NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)
COMMON/SLP/DCOR(1000,2)
```

K=0

DO 10 I=1,NP

IF(DCOR(N,1).EQ.CORD(I,1).AND.DCOR(N,2).EQ.CORD(I,2)) K=I

N=K

IF(K NE 0) RETURN

WRITE(6,20) N

```
20 FORMAT(' ***** ERROR IN MAPPING: NO NEW NODE FOUND FOR OLD '
+ 'NODE ',I3,' *****')
```

STOP

END

Subroutine NFLOW:  
Calculates the amount of yield which results.

Written:  
Last modified: MAR 19 1984

Called by: RESIDUESTIFM

#### SUBROUTINE NFLOW(SSS)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK
COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST,
1 TABSTN(10,15),TABSTR(10,15)
COMMON/INV/SMEAN,STJ2,STJ3,SIGMA,PHI,APHI,STN,CPHI,YIELD
COMMON/FLW/ABETA,AA(4),DD(4)
DIMENSION SSS(4),A1(4),A2(4),A3(4)
```

Initializes vector A1.

```
C      A1(1)=A1(2)=A1(4)=1.
      A1(1)=1.
      A1(2)=1.
      A1(4)=1.
      A1(3)=0.
```

Calculates vector A2.

---

```

SSS(3)=2.*SSS(3)
GASH=2.*SIGMA
DO 10 I=1,4
10      A2(I)=SSS(I)/GASH

```

---



---

•      Calculates vector A3.

---

```

CON=STJ2/3.
A3(1)=CON+SSS(2)*SSS(4)
A3(2)=CON+SSS(1)*SSS(4)
A3(3)=-SSS(4)*SSS(3)
A3(4)=CON+ SSS(1)*SSS(2)-25*SSS(3)*SSS(3)
CON=1.73205080756888
APHI=PHI*57.29577951308232
MYIELD=NYIELD
IF(NYIELD.GT.100)MYIELD=NYIELD-100
GO TO (20,30,50,60),MYIELD

```

---



---

•      Von Mises yield criteria.

---

```

20      C1=0.
C2=CON
C3=0.
GO TO 70

```

---



---

•      Tresca yield criteria.

---

```

30      C1=0.
AAPHI=ABS(APHI)
IF(AAPHI.LT.29.0) GO TO 40

```

```

C2=CON
C3=0.
GO TO 70
40      SN=SIN(PHI)
CTS=SQRT(1.-STN*STN)
C2=2.*CPHI+SN*STN/CTS)
C3=CON*SN/(STJ2*CTS)
GO TO 70

```

---

- Drucker yield criteria.

---

```

50      C1=ALPHA
C2=1.
C3=0.
GO TO 70

```

---

- Beltrami yield criteria.

---

```

60      C1=(1.+2.*PR)*SMEAN/YIELD
C2=(1.-PR)*GASH/YIELD
C3=0.
70      CONTINUE
DO 80 I=1,4
80      AA(I)=C1*A1(I)+C2*A2(I)+C3*A3(I)
IF(NPP.NE.1) GO TO 90
CON=AA(4)
AA(4)=-PPR*(AA(1)+AA(2))
90      GASH=CLAME*(AA(1)+AA(2)+AA(4))
GISH=HM
DO 100 I=1,4
DD(I)=GM*AA(I)+GASH
IF(I.EQ.3) DD(I)=.5*AA(I)*GM
100     GISH=GISH+AA(I)*DD(I)
ABETA=1./GISH
IF(NPP.EQ.1) AA(4)=CON

```

RETURN

END

Subroutine NODEXY:

Sets x,y values of new intermediate coordinates of quadratic or cubic elements.

Written:

Last modified MAR 19 1984

Called by: GDATASLIPP

#### SUBROUTINE NODEXY(ISTART)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD

COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2),

1 NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)

ANSFR=NSFR

NQ=NSFR-1

DO 30 N=ISTART,NE

NASH=NCN\*(N-1)

DO 30 NLV=1,NCN,NSFR

NV1=NOP(NASH+NLV)

NL1=NLV+NSFR

IF(NL1.GT.NCN) NL1=1

NV2=NOP(NASH+NL1)

DO 20 I=1,NQ

M=NLV+I

J=NOP(NASH+M)

GISH=I

GOSH=ANSFR-GISH

DO 10 K=1,2

CORD(J,K)=(GOSH\*CORD(NV1,K)+CORD(NV2,K)\*GISH)/ANSFR

10 CONTINUE

20

30 CONTINUE

RETURN  
END

---



---



---

Subroutine OUTPUT:  
Wntes displacements, reactions, stresses and strains to SCRUBS.LIS

---

Written:  
Last modified:JUL 19 1984

---



---

Called by: SCRUBS

---



---

#### SUBROUTINE OUTPUT

```
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
COMMON/ELPRNT/ NELP,NPEL(50),NONODE
DIMENSION SAVG(6)
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK
COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
COMMON/BOUN/NBC(400),NFIX(400),U(800),ANG(400),TRC(800),
1 US(400,2)
COMMON/LDS/R1(2000),RL(2000),RT(2000)
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2),
1 NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)

MOUT=NOUT(INC)
IF(MOUT.LT.100)GO TO 10
M=MOUT/100
MOUT=MOUT-M*100
IF(IT.EQ.1)MOUT=M
10 IF(MOUT.EQ.0)RETURN
IF(NONODE.GT.0) GO TO 50
```

• Writes x and y displacements.

---

```

      WRITE(6,20)
20      FORMAT(' DISPLACEMENTS',5X,'X',15X,'Y',13X,'TOTAL X',11X,
1           'TOTAL Y')
      DO 30 N=1,NP
30      WRITE(6,40)N,(DIS(I,N),I=1,NDF),(TDIS(I,N),I=1,NDF)
40      FORMAT(I10,6E16.6)
50      CONTINUE
      IF(MOUT EQ.1)RETURN

```

---

• Writes node numbers and corresponding displacements and reactions.

---

```

      WRITE(6,60)
60      FORMAT(6X,'NODE NO',10X,'DISPLACEMENTS',16X,'REACTIONS')
      NASH=0
      DO 70 I=1,NB
          NBC(I)
          MASH=MASH+1
          NASH=NASH+1
70      WRITE(6,80)N,(TDIS(J,N),J=1,2),(TRC(J),J=MASH,NASH)
80      FORMAT(I10,6E16.6)
      IF(MPR EQ.0)GO TO 130
C      SUMX=SUMY=0.0
      SUMX=0.0
      SUMY=0.0
      DO 110 I=1,MPR
          NASH=NOPR(I)
          DO 90 J=1,NB
              NBC(J)
              IF(N EQ.NASH) GO TO 100
90      CONTINUE
      GO TO 110
100     MASH=2•J
          SUMX=SUMX+TRC(MASH-1)
          SUMY=SUMY+TRC(MASH)

```

---

110 CONTINUE

---

- \*
- \*
- Writes total reactions at specified points.
- \*
- \*

---

```

WRITE(6,120)SUMX,SUMY
120 FORMAT(' TOTAL REACTIONS AT SPECIFIED POINTS ALONG X=',  

1      E16.6,' ALONG Y=', E16.6)
130 IF(MOUT.EQ.2)RETURN

```

---

- \*
- \*
- Writes stresses at sampling points.
- \*
- \*

---

```

WRITE(6,140)
140 FORMAT(' STRESSES AT SAMPLING POINTS '/  

1      ' GAUSS P',1X,'SIG X',6X,'SIG Y',6X,'TAU XY',6X,' SIG Z',6X,  

2      ' YIELD',6X,'PL. STRN')
MCN=NSTORE/NE
DO 290 M=1,NE
IF(NELP.LT.0) GO TO 160
DO 150 K=1,NELP
IF(M.EQ.NPEL(K)) GO TO 160
150 CONTINUE
GO TO 290
160 CONTINUE
WRITE(6,170) M
170 FORMAT(' EL NO ',I3)
K=MCN*(M-1)
EPS=0.
DO 190 L=1,MCN
J=K+L
WRITE(6,180)L,(TSTS(I,J),I=1,5),EPSTN(5,J)
180 FORMAT(I2,6(1PE12.3))
EPS=EPS+EPSTN(5,J)
190 CONTINUE
XMCN=MCN
EPS=EPS/XMCN
DO 200 I==1.6
200 SAVG(I)==0.0

```

```

      DO 210 I=1,5
      DO 210 L=1,MCN
      J=K+L
210       SAVG(I)=SAVG(I)+TSTS(I,J)
      DO 220 I=1,5
220       SAVG(I)=SAVG(I)/XMCN
      SMEAN=(SAVG(1)+SAVG(2)+SAVG(4))/3
      IF(SAVG(5).EQ.0)GOTO 230
      RATIO=SMEAN/SAVG(5)
230       WRITE(6,240) (SAVG(I),I=1,5),EPS,SMEAN,RATIO
240       FORMAT(' AV',6(1PE12.4),' SIG MEAN='1PE10.3,' R=',1PE10.3)
      DO 250 I=1,4
250       SAVG(I)=0.0
      DO 260 I=1,4
      DO 260 L=1,MCN
      J=K+L
260       SAVG(I)=SAVG(I)+EPSTN(I,J)
      DO 270 I=1,4
270       SAVG(I)=SAVG(I)/XMCN

```

---

- 
- Writes plastic strains.
- 

---

```

      WRITE(6,280) (SAVG(I),I=1,4)
280       FORMAT(3X,4E12.4,' (PLASTIC STRAINS)')
290       CONTINUE
      IF(MOUT.EQ.3)RETURN

```

---

- 
- Writes residual forces at the nodes.
- 

---

```

      WRITE(6,300)
300       FORMAT(' RESIDUAL FORCES AT NODAL POINTS'/
1           5X,'NODE NO',9X,'X VALUE',9X,'Y VALUE')
      DO 310 J=1,NP
      N=2*J
310       WRITE(6,320)J,R1(N-1),R1(N)
320       FORMAT(I10,3E20.6)

```

```
RETURN
END
```

---



---



---

\*           Subroutine PDISP:

\*           Initializes the displacement vector according to number of  
\*           loading increments.

\*           Written:

\*           Last modified: MAR 19 1984

\*           Called by: SCRUBS

SUBROUTINE PDISP(L)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1        NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,  
2        NSTORE

COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)

COMMON/BOUN/NBC(400),NFIX(400),U(800),ANG(400),TRC(800),

1        US(400,2)

IF(L-1)10,60,30

10       IC=NB\*NDF

DO 20 I=1,IC

20       U(I)=0.

RETURN

30       FACT=FAC(L)

IC=1

NZ=10\*\*[NDF-1]

DO 50 I=1,NB

   JZ=NFIX(I)

   IZ=NZ

DO 50 J=1,NDF

   IF(JZ.LT.IZ) GO TO 40

   U(IC)=US(I,J)\*FACT

```

IC=IC+1
JZ=JZ-IZ
40      IZ=IZ/10
50      CONTINUE
       RETURN
60      FACT=FAC(INC)
       IC=0
       DO 70 I=1,NB
          DO 70 J=1,NDF
             IC=IC+1
70      U(IC)=US(I,J)*FACT

       RETURN
       END

```

---



---



---



---

\* Subroutine READF:

\* Reads the mining parameters: which elements, and when.

\* Written:

\* Last modified: JUL 24 1984

\* Called by: SCRUBS

---



---



---

SUBROUTINE READF(NRFF)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10)

---



---



---

\* Reads number of elements to be mined per increment.

---



---



---

READ (5,10)(NME(I),I=1,NRFF)

10 FORMAT(2SI5)

```

      WRITE(6,20)
20    FORMAT(' LIST OF FAILURE(MINING) SEQUENCE ')
     1      ' INCREMENT NUMBER OF ELEMENTS ',15X,'ELEMENT LIST')

```

---

- 
- Reads the element numbers.
- 

---

```

DO 50 I=1,NRFF
      NL=NME(I)
      IF(NL.GT.25)GOTO 30
      READ(5,10) (MINES(I,K),K=1,NL)
      WRITE(6,25) (I,NL,(MINES(I,K),K=1,NL))
25    FORMAT(16I5)
      GOTO 50
30    READ(5,10) (MINES(I,K),K=1,25)
      READ(5,10) (MINES(I,K),K=26,NL)
      WRITE(6,25) (I,NL,(MINES(I,K),K=1,14))
      IDUM=(NL+2)/16
      IY=1
      DO 40 IZ=1,IDUM
          IY=IY+14
          IYY=IY+13
          IF(IYY.GT.NL)IYY=NL
40    WRITE(6,45) (MINES(I,K),K=IY,IYY)
45    FORMAT(10X,14I5)
50    CONTINUE

      RETURN
      END

```

- 
- Subroutine REMLD:
- Removes gravity load from failed elements.
- 

- Written:
- Last modified JUL 19 1984
- 

- Called by: FTEST
- 

- Subroutines called: SFRAUX
- 

#### SUBROUTINE REMLD(M)

```

IMPLICIT DOUBLE PRECISION (A-H,O-Z)
DIMENSION R(3)
DIMENSION NOPL(4),PS(4,2),PQ(2),DJ(2),DENS(10)
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK
COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
COMMON/GID/XG(6),CG(6),XMG(6),CMG(6) NGAUS,MGAUS,MCN
COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST
1 ,TABSTN(10,15),TABSTR(10,15)
COMMON/LDS/R1(2000),RL(2000),RT(2000)
COMMON/NUME/P(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),
1 NOPE(12),DISE(2,12),RP,RPB,XYP(3)
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
COMMON/GRAV/GRAV

GUSH=0.0
L=IMAT(M)
IF(L.GT.NMAT)L=L-100

```

```

THICK=ORT(L,6)
DENSE=DENS(L)
C      PQ(1)=PQ(2)=0.
      PQ(1)=0.
      PQ(2)=0.
      IF(DENSE.EQ.0.)GO TO 60
10      NASH=NCN*(M-1)
      DO 30 K=1,NCN
      MASH=NOP(NASH+K)
      DO 20 I=1,NCORD
      XYE(I,K)=CORD(MASH,I)
      NOPE(K)=MASH
      DO 50 IGAUS=1,NGAUS
      DO 50 JGAUS=1,NGAUS
      G=XG(IGAUS)
      H=XG(JGAUS)
      CALL SFR(G,H)
      CALL AUX(M)
      DV=DET*CG(IGAUS)*CG(JGAUS)
      IF(NPP.EQ.2)DV=DV*RP*6.28318530718
      IF(NCORD.EQ.3)DV=DV*XYP(3)
      IF(THICK.NE.0.)DV=DV*THICK
      PQ(1)=PQ(1)+DENSE*GUSH*XYP(1)*GRAV*FACTOR
      DO 40 I=1,NCN
      IC=(NOPE(I)-1)*2
      DO 40 K=1,2
      IC=IC+1
C      RL(IC)=RL(IC)-PQ(K)*P(I)*DV
      RT(IC)=RT(IC)-PQ(K)*P(I)*DV
40      CONTINUE
50      CONTINUE
60      CONTINUE

      RETURN
      END

```

•  
 •  
 •  
 • Subroutine RESIDUE:  
 • Determines element failure, rubbleization, and residual.

•  
 • Written:  
 • Last modified JUL 19 1984

•  
 •  
 • Called by: SCRUBS

•  
 •  
 • Subroutines called:MODSFR  
 AUXLINEARJOINTM  
 INVARNFLOWTEST  
 CONRUBDROP

#### SUBROUTINE RESIDUE (TIME1,IFCOUNT,MTGPY)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK
COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
COMMON/BOUN/NBC(400),NFIX(400),U(800),ANG(400),TRC(800),
1 US(400,2)
COMMON/LDS/R1(2000),RL(2000),RT(2000)
COMMON/BOTTOM/ AK
COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),GAMMA
COMMON/GID/XG(6),CG(6),XMG(6),CMG(6),NGAUS,MGAUS,MCN
COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST
1 ,TABSTN(10,15),TABSTR(10,15)
COMMON/NUME/P(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),
1 NOPE(12),DISE(2,12),RP,RPB,XYP(3)
COMMON/INV/SMEAN,ST J2,ST J3,SIGMA,PHI,APH1,STN,CPhi,YIELD
COMMON/FLW/ABETA,AA(4),DD(4)
```

```

COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
2 ,SIG(4),PSIG(4),DSIG(4),EP(4),NG(16),NGSTP(16)
DIMENSION STRN(4),STRS(4),TSIG(4)
DIMENSION SAVG(5)
REAL TIME1,TIME2,TIME3

```

```

NECN=NE*NCN
READ (8)(NOP(J),J=1,NECN),(IMAT(I),I=1,NE),((DISN(K,I),
1 TDIS(K,I)),K=1,2),(CORD(I,J),J=1,NCORD),I=1,NP),(((TSTS(I,J),
2 EPSTN(I,J)),I=1,5),J=1,NSTORE)
REWIND 8
IFCOUNT=0
IF(IT GT.1) GO TO 20

```

---

\* For initial iteration step set increment equal to zero.

---

```

DO 10 I=1,2
DO 10 J=1,NP
10 DISN(I,J)=0.
20 CONTINUE

```

---

\* Update coordinates, total displacements, and displacement increment.

---

```

DO 30 I = 1,NDF
DO 30 J=1,NP
      GASH=DIS(I,J)
      CORD(J,I)=CORD(J,I)+GASH
      TDIS(I,J)=TDIS(I,J)+GASH
      DISN(I,J)=DISN(I,J)+GASH
30 CONTINUE
DO 40 J=1,NSZF
40 R1(J)=0.
      PWORK=0.
      WRITE(6,50)FACTOR,IT
50 FORMAT(' LFACTOR  ='F7.3,2X,'ITERATION NO =',I3)
      MTGPY=0

```

---

- 
- Control loop on all elements.
- 

---

```
DO 360 MNEW=1,NE
MASH=MNEW-1
NOSH=MASH*NCN
MOSH=MASH*MCN
```

---

- 
- Find coordinates and connectivity.
- 

---

```
DO 70 K=1,NCN
MASH=NOP(NOSH+K)
DO 60 I=1,NCORD
XYE(I,K)=CORD(MASH,I)
IF(I.GT.2) GO TO 60
DISE(I,K)= DIS(I,MASH)
60      CONTINUE
NOPE(K)=MASH
70      CONTINUE
L=IMAT(MNEW)
IF(L.GT.NMAT)L=L-100
```

---

- 
- Get elasticity matrix.
- 

---

```
CALL MOD(L,1)
THICK=ORT(L,6)
IF(THICK.EQ.0.)THICK=1.
NPLST=0
IJG=0
```

---

- 
- Loop on integration points.
-

---

```

DO 280 IGAUS=1,MGAUS
DO 280 JGAUS=1,MGAUS
IJG=IJG+1
NG(IJG)=0
NGSTP(IJG)=0
G=XMG(IGAUS)
H=XMG(JGAUS)

```

---

- Compute shape functions and derivatives.

---

```

CALL SFR(G,H)
CALL AUX(MNEW)
DV=DET*CMG(IGAUS)*CMG(JGAUS)*THICK
IF(NPP.EQ.2)DV=DV*RP*6.283185307179586
IF(NCORD.EQ.3)DV=DV*XYP(3)
MOSH=MOSH+1

```

---

- Compute elastic strains and stresses in element.

---

```

CALL LINEAR(STRN,STRS,W)
BRING=1.
IF(NL.NE.1) GO TO 90

```

---

- If element rubbleizes, set stresses to zero.

---

```
IF(BULK(MNEW,1) EQ 0.0) GO TO 90
```

```
DO 80 J=1,4
```

```
STRS(J)=0.000001
```

```
CONTINUE
```

```
IF(BULK(MNEW,1).NE.0.0) GO TO 100
```

80

90

For jointed media material find incremental stresses and residuals  
in subroutine JOINTM.

---

```
IF(ORT(L,2).GE.0) GOTO 100
CALL JOINTM(L,STRN,STRS,MOSH,YIELD,PSTRN)
```

---

Set incremental stresses equal to elastic strains.

```
100      DO 110 I=1,4
          DSIG(I)=STRS(I)
          EP(I)=EPSTN(I,MOSH)
C110      TSIG(I)=SIG(I)=TSTS(I,MOSH)
          TEMP=TSTS(I,MOSH)
          TSIG(I)=TEMP
          SIG(I)=TEMP
110      CONTINUE
          IF (NALGO EQ 0) GO TO 240
          PSTRN=EPSTN(5,MOSH)
          PSTY=TSTS(5,MOSH)
```

---

Add incremental stress to total stress.

```
120      DO 120 I=1,4
          TSIG(I)=TSIG(I)+STRS(I)
          IF(ORT(L,2) LT 0) GOTO 240
          CALL INVAR (TSIG)
          RD=1.
          DF=YST-PSTY
          IF(DF.LE.0.0) GO TO 130
          DF1=YIELD-YST
          IF(DF1.LE.0.0) GO TO 240
          RD=DF1/(DF+DF1)
          GO TO 140
```

```

130      DF1=YIELD-PSTY
          IF(DF1.LE.0.0) GO TO 240
          -----
          *
          * Compute plastic step.
          *
          -----
140      MSTEP=DF1*8.0/YST+1.
          ASTEP=MSTEP
          RD1=1.-RD
          DO 150 I=1,4
          C           TSIG(I)=PSIG(I)=SIG(I)+RD1*STRS(I)
          TEMP=SIG(I)+RD1*STRS(I)
          TSIG(I)=TEMP
          PSIG(I)=TEMP
150      STRS(I)=RD*STRS(I)/ASTEP
          TLEMDA=0.
          NG(IJG)=MOSH
          NGSTP(IJG)=MSTEP
          NPLST=NPLST+1
          DO 200 ISTEP=1,MSTEP
              CALL INVAR (TSIG)
          -----
          *
          * Find position on effective curve.
          *
          -----
          MASH=0.
160      MASH=MASH+1
          IF(PSTRN.LT TABSTN(L,MASH)) GO TO 170
          GO TO 160
170      NASH=MASH
          MASH=NASH-1
          ETAB=TABSTN(L,NASH)-TABSTN(L,MASH)
          HM=(TABSTR(L,NASH)-TABSTR(L,MASH))/ETAB
          -----
          *
          * Compute AA,ABETA,PD,TSIG.
          *
          -----

```

```

CALL NFLOW(TSIG)
GASH=0.
DO 180 I=1,4
180 GASH=GASH+AA(I)*STRS(I)
DLEMDA=GASH*ABETA
IF(DLEMDA.LT.0.) DLEMDA=0.
GASH=0.
DO 190 I=1,4
GASH=GASH+AA(I)*PSIG(I)
EP(I)=EP(I)+AA(I)*DLEMDA
C190 TSIG(I)=PSIG(I)=PSIG(I)+STRS(I)-DLEMDA*DD(I)
TEMP=PSIG(I)+STRS(I)-DLEMDA*DD(I)
PSIG(I)=TEMP
TSIG(I)=TEMP

190 CONTINUE
GASH=GASH*DLEMDA
PSTRN=PSTRN+GASH/YIELD
PWORK=PWORK+GASH*DVE
TLEMDA=TLEMDA+DLEMDA

200 CONTINUE
DO 210 I=1,4
GASH=TSIG(I)-SIG(I)
PSIG(I)=DSIG(I)-GASH
210 DSIG(I)=GASH
CALL INVAR (TSIG)
MASH=0
220 MASH=MASH+1
IF(PSTRN.LT.TABSTN(L,MASH)) GO TO 230
GO TO 220

230 NASH=MASH
MASH=NASH-1
ETAB=TABSTN(L,NASH)-TABSTN(L,MASH)
GASH=(PSTRN-TABSTN(L,MASH))/ETAB
MASH=MASH-1
CYIELD=TABSTR(L,MASH+1)*(1.-GASH)+GASH*
1 TABSTR(L,MASH+2)
IF(YIELD.GT.CYIELD)BRING=CYIELD/YIELD

```

---

\* Add Jaumann stress to DSIG.

---

240 CONTINUE

```

DSIG(1)=DSIG(1)+2.*W*TSTS(1,MOSH)
DSIG(2)=DSIG(2)-2.*W*TSTS(2,MOSH)
DSIG(3)=DSIG(3)+W*(TSTS(2,MOSH)-TSTS(1,MOSH))

```

---

- Add increment to total stress.

---

```

DO 250 I=1,4
GASH=BRING*(SIG(I)+DSIG(I))
EPSTN(I,MOSH)=EP(I)
C250      STRS(I)=TSTS(I,MOSH)=GASH
           STRS(I)=GASH
           TSTS(I,MOSH)=GASH
250      CONTINUE
           YIELD=BRING*YIELD
           EPSTN(5,MOSH)=PSTRN
           TSTS(5,MOSH)=YIELD
           DO 260 I=1,ICS
260      STRS(I)=DV*STRS(I)

```

---

- Compute residual.

---

```

DO 270 K=1,NCN
GASH=0.
IF(NPP.EQ.2)GASH=P(K)*STRS(4)/RP
MASH=2*NOPE(K)-1
NASH=MASH+1
R1(MASH)=R1(MASH)+DI(1,K)*STRS(1)-
1          DI(2,K)*STRS(3)+GASH
           R1(NASH)=R1(NASH)+DI(1,K)*STRS(3)-
1          DI(2,K)*STRS(2)
270      CONTINUE
280      CONTINUE
           IF(NL.NE.1) GO TO 350

```

---

- Rubble failure logic.

---

```

DO 290 I=1,5
290      SAVG(I)=0.0
          JJ=MCN*(MNEW-1)
          DO 300 I=1,MCN
              JJ1=JJ+I
              DO 300 J=1,5
                  SAVG(J)=SAVG(J)+TSTS(J,JJ1)
                  DO 310 I=1,5
                      SAVG(I)=SAVG(I)* 25
                      MATNO=IMAT(MNEW)
                      IF(MATNO GT.100) MATNO=MATNO-100
                      CALL FTEST(MNEW,SAVG,MATNO,IFLFG)
                      IFCOUNT=IFCOUNT+IFLFG
                      IF(IFLFG EQ 0) GO TO 350

```

---

- If element has failed, adjust R1 array and set coordinates, displacements and stresses.
  - First check for continuum/rubble interaction.
- 

```

CALL CONRUB(SIGRES,MNEW,NMAT)
INDEX=(MNEW-1)*MCN
DO340 IGAUS=1,MGAUS
    DO340 JGAUS=1,MGAUS
        G=XMG(IGAUS)
        H=XMG(JGAUS)
        CALL SFR(G,H)
        CALL AUX(MNEW)
        DV=DET*CMG(IGAUS)*CMG(JGAUS)*THICK
        IF(NPP EQ.2)DV=DV*RP*6.283185307179586
        IF(NCORD EQ.3)DV=DV*XYP(3)
        INDEX=INDEX+1
        DO 320 I=1,ICS
            STRS(I)=DV*TSTS(I,INDEX)
320      TSTS(I,INDEX)=SIGRES
            TSTS(3,INDEX)=0.0
            TSTS(5,INDEX)=1.73205*SIGRES
            DO 330 K=1,NCN

```

```

GASH=0.
IF(NPP.EQ.2)GASH=P(K)*STRS(4)/RP
MASH=2*NOPE(K)-1
NASH=MASH+1
R1(MASH)=R1(MASH)-DI(1,K)*STRS(1)-
1 DI(2,K)*STRS(3)-GASH
R1(NASH)=R1(NASH)-DI(1,K)*STRS(3)-DI(2,K)*STRS(2)
330    CONTINUE
340    CONTINUE
350    CONTINUE
      MTGPY=MTGPY+NPLST
360    CONTINUE
      IF(NL.EQ.1) CALL DROP(NE,NP,AK)
      WRITE(8)(NOP(J),J=1,NECN),(IMAT(I),I=1,NE),((DISN(K,I),
1      TDIS(K,I)),K=1,2),(CORD(I,J),J=1,NCORD ),I=1,NP),(((TSTS(I,J),
2      EPSTN(I,J)),I=1,5),J=1,NSTORE)
      REWIND 8
      WRITE(6,370)MTGPY,IFCOUNT
370    FORMAT(' TOTAL GAUSS POINTS YIELDED DURING ITERATION =',15/
1      ' TOTAL NUMBER OF ELEMENTS RUBBLEIZED DURING ITERATION =',15)
      TIME4=SECNDS(TIME1)
      WRITE(6,380)TIME4
380    FORMAT(' RESULTANT FORCES OBTAINED AT',F10.3)

      RETURN
      END

```

---



---

• Subroutine RESOLV:  
 • Updates stiffness equation solution.

---



---

• Written:  
 • Last modified: JUL 18 1984

---



---

• Called by: SCRUBS

---



---

SUBROUTINE RESOLV

```

IMPLICIT DOUBLE PRECISION (A-H,O-Z)
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK
COMMON/BOUN/NBC(400),NFIIX(400),U(800),ANG(400),TRC(800),
1 US(400,2)
COMMON/LDS/R1(2000),RL(2000),RT(2000)
COMMON/SCR/SK(20000) ,R

READ(4) NTP ,(SK(I),I=NSK,NTP )
NBUF=NSK-1
ND=1
NNP=1
DO 60 L=1,NP
    DO 50 I=1,NDF
        IC=I+NDF*(L-1)
        R=R1(IC)
        NBUF=NBUF+1
        NSZ=SK(NBUF)
        NBUF=NBUF+1
        IF(SK(NBUF) GT .0.) GO TO 10
        RS=-R
        R=-U(ND)
        ND=ND+1
        R1(IC)=SK(NBUF)*R+RS
        GO TO 20
10    CONTINUE
        R1(IC)=SK(NBUF)*R
20    CONTINUE
        IF(L+I-NP-NDF) 30,70,30
30    NBUF=NBUF+1
        DO 40 J=1,NSZ
            IK=IC+J
            R1(IK)=R1(IK)-SK(NBUF)*R
40    NBUF=NBUF+1
        NBUF=NBUF+1
        IF(NBUF.LT.NTP) GO TO 50
        READ(4) NTP ,(SK(II),II=NSK,NTP)
        NBUF=NSK-1
        NNP=0
50    NNP=NNP+
60    CONTINUE

70    RETURN

```

END

---



---



---

- Subroutine ROSB:
- Adjusts stiffness matrix.

- Written:
- Last modified: JUL 14 1984

---



---

- Called by: STIFM

---



---

#### SUBROUTINE ROSB

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD

COMMON/BOUN/NBC(400),NFIIX(400),U(800),ANG(400),TRC(800),

1 US(400,2)

COMMON/NUME/P(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),

1 NOPE(12),DISE(2,12),RP,RPB,XYP(3)

COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)

1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)

2 ,COJ(2,2),COJIN(2,2),B(4,24),ESTIFM(24,24),DVD(4,4),DVDB(4)

DO 60 I=1,NCN

DO 10 M=1,NB

IF(NOPE(I).EQ.NBC(M)) GO TO 20

10 CONTINUE

GO TO 60

20 IF(ANG(M).EQ.0.) GOTO 60

GASH=ANG(M)\*.017453292

CS=COS(GASH)

TN=TAN(GASH)

MASH=2\*I-1

NASH=MASH+1

DO 30 K=1,LV

STFUC=ESTIFM(MASH,K)\*CS

```

        STFVC=ESTIFM(NASH,K)*CS
        ESTIFM(MASH,K)=STFUC+STFVC*TN
        ESTIFM(NASH,K)=STFVC-STFUC*TN
30      CONTINUE
        DO 40 K=MASH,NASH
          STFUC=ESTIFM(K,MASH)*CS
          STFVC=ESTIFM(K,NASH)*CS
          ESTIFM(K,MASH)=STFUC+STFVC*TN
          ESTIFM(K,NASH)=STFVC-STFUC*TN
40      CONTINUE
        DO 50 J=MASH,NASH
          DO 50 K=1,LV
            ESTIFM(K,J)=ESTIFM(J,K)
50      CONTINUE
60      CONTINUE

      RETURN
      END

```

• Subroutine ROTATE:  
 • This subroutine rotates 2D stress or strain vector by angle THETA.

• Written:  
 • Last modified: MAR 19 1984

• Called by: JOINTM

SUBROUTINE ROTATE(A,B,THETA)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)  
 DIMENSION A(4),B(4)

```

C=DCOS(THETA)
S=DSIN(THETA)
B(1)=A(1)*C*C+A(2)*S*S-2.*A(3)*C*S
B(2)=A(1)*S*S+A(2)*C*C+2.*A(3)*C*S

```

```
B(3)=A(1)*C*S+A(2)*C*S+A(3)*C*C+A(3)*S*S
B(4)=A(4)
```

```
RETURN
END
```

---



---



---

- Subroutine RUBDRAW:
- Writes the rubble file RUB.MOV.

---



---

- Written:
- Last modified: JUL 19 1984

---



---

- Called by: SCRUBS

---



---

SUBROUTINE RUBDRAW(NUMEL,TT,NUMNP)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,  
 1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,  
 2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,  
 3 TPWORK,KNE

DIMENSION EPX4(20,1),R(1),Z(1),IX(5,1)

COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)

COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),GAMMA

COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)

,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)

DIMENSION IXAR(4000)

DIMENSION IXN(20),RN(12),ZN(12),ZETA(12),ETA(12)

REAL TIME1,TIME2,TIME3

DIMENSION IDUM(12)

REAL CORDDUM(1000,2),R1,R2,R3,R4,Z1,Z2,Z3,Z4,ZERO

DATA IXN/1,2,6,-4,2,3,8,-6,4,5,10,-9,5,7,11,-10,7,8,12,-11/

DATA ZETA/-1.,0.,1.,-1.,-5.,0.,-5.,1.,-1.,-5.,5.,1./

DATA ETA/-1.,-1.,-1.,0.,0.,0.,0.,0.,1.,1.,1.,1.,1./

DATA IDUM/8,16,24,31,39,47,55,62,70,78,86,94/

```

NP1=1
NP2=NUMEL
IBEGIN=NUMEL
ICNT=1

```

- Eliminates plotting of boundary around rubble.

```

IR1=0
DO 20 I=1,NUMEL
  IF(BULK(I,1).EQ.0.0) GO TO 10
  NP2=NP2-1
  ICNT=ICNT+1
  GO TO 20
10   CONTINUE
     IR2=4*NSFR*(I-1)
     IXAR(IR1+1)=NOP(IR2+1)
     IXAR(IR1+2)=NOP(IR2+1+NSFR)
     IXAR(IR1+3)=NOP(IR2+1+NSFR*2)
     IXAR(IR1+4)=-NOP(IR2+1+NSFR*3)
     IR1=IR1+4*NSFR
20   CONTINUE
     WRITE(14,30) TT,ICNT
30   FORMAT (E15.5,I5)
     NONE=1
     NCON=4*NP2*NSFR
     WRITE(14,60) NONE,NUMNP,NP2,NCON
     WRITE (14,60) NP1,NP2
     ZERO=0.0
     DO 40 I=1,NUMNP
       CORDDUM(I,1)=SNGL(CORD(I,1))
40   CORDDUM(I,2)=SNGL(CORD(I,2))
     WRITE(14,50) ((CORDDUM(I,1),CORDDUM(I,2),ZERO),I=1,NUMNP)
50   FORMAT (6E12.5)
     WRITE(14,60) (IXAR(I),I=1,NCON)
60   FORMAT (16I5)
     ICNT=0
     NP1=NP2
     DO 100 I=1,NUMEL
       IF (BULK(I,1) EQ 0.0) GO TO 100
       ICNT=ICNT+1
       NP1=NP2+1

```

```

NP2=NP1+4*NSFR
INDEX=4*(I-1)*NSFR
I1=NOP(INDEX+1)
I2=NOP(INDEX+1+NSFR)
I3=NOP(INDEX+1+NSFR*2)
I4=NOP(INDEX+1+NSFR*3)
Z1=SNGL(CORD(I1,2))
Z2=SNGL(CORD(I2,2))
Z3=SNGL(CORD(I3,2))
Z4=SNGL(CORD(I4,2))
R1=SNGL(CORD(I1,1))
R2=SNGL(CORD(I2,1))
R3=SNGL(CORD(I3,1))
R4=SNGL(CORD(I4,1))
ISWSW=0
IF(ISWSW.EQ.0) GO TO 80
IF(BULK(I,1).EQ.2.0) GO TO 80
DO 70 KK=1,12
  IF(I.EQ.IDUM(KK)) ISWSW=1
CONTINUE

```

70

---

- Leaves gap for unconsolidated rubble.
- 

---

```

ZMAX=AMAX1(Z1,Z2,Z3,Z4)
ZMIN=AMIN1(Z1,Z2,Z3,Z4)
IELE=IMAT(I)
ALPH=ORT(IELE,8)
RMAX=AMAX1(R1,R2,R3,R4)
RMIN=AMIN1(R1,R2,R3,R4)
C      RDEL=RMAX-RMIN
C      AREA=BULK(I,2)
C      ANEW=AREA/ALPH
C      ZDEL=ANEW/RDEL
C      ZNEW=ZMIN+ZDEL
C      ZAVG=(Z1+Z2+Z3+Z4)*.25
C1=CORD(I1,2)-TDIS(2,I1)
C2=CORD(I2,2)-TDIS(2,I2)
C3=CORD(I3,2)-TDIS(2,I3)
C4=CORD(I4,2)-TDIS(2,I4)
ZD1=ABS(C3-C1)
ZD2=ABS(C4-C2)

```

```

ZDST=.5*(ZD1+ZD2)
ZLEN=ZDST/ALPH
ZNEW=ZMIN+ZLEN
ZNEW=SNGL(ZNEW)
IF(Z1.GT.ZAVG.AND.FLAG(I1).GT.1.0) Z1=ZNEW
IF(Z2.GT.ZAVG.AND.FLAG(I2).GT.1.0) Z2=ZNEW
IF(Z3.GT.ZAVG.AND.FLAG(I3).GT.1.0) Z3=ZNEW
IF(Z4.GT.ZAVG.AND.FLAG(I4).GT.1.0) Z4=ZNEW

```

80 CONTINUE

---

\*  
\* Computes nodal coordinates for intra-element rubble.  
\*

---

```

DO 90 INDEX=1,12
F1=1.-ZETA(INDEX)
F2=1.+ZETA(INDEX)
G1=1.-ETA(INDEX)
G2=1.+ETA(INDEX)
RN(INDEX)=.25*(F1*G1*R1+F2*G1*R2+F2*G2*R3+F1*G2*R4)
ZN(INDEX)=.25*(F1*G1*Z1+F2*G1*Z2+F2*G2*Z3+F1*G2*Z4)

```

90 CONTINUE

```

NJ=12
NPT=5
NCON=20
WRITE(14,60) NONE,NJ,NPT,NCON
WRITE(14,60) NP1,NP2
WRITE (14,50) ((RN(J),ZN(J),ZERO),J=1,12)
WRITE (14,60) (IXN(J),J=1,20)

```

100 CONTINUE

```

RETURN
END

```

---

---

---

• Subroutine RZBASE:

• This subroutine finds the base R and Z dimensions for fall  
calculations.

• Written:

• Last modified: MAR 19 1984

• Called by: DROP

• Subroutines called: EXIT

SUBROUTINE RZBASE(I,IBOT,I1,I2,I3,I4,R,Z,RLEN,ZBASE)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)

1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)

R1=CORD(I1,1)

R2=CORD(I2,1)

R3=CORD(I3,1)

R4=CORD(I4,1)

Z1=CORD(I1,2)

Z2=CORD(I2,2)

Z3=CORD(I3,2)

Z4=CORD(I4,2)

RAVG=(R1+R2+R3+R4)\* .25

ZAVG=(Z1+Z2+Z3+Z4)\* .25

RMX=0.0

IF(R1.GT.RAVG)RMX=RMX+R1

IF(R2.GT.RAVG)RMX=RMX+R2

IF(R3.GT.RAVG)RMX=RMX+R3

IF(R4.GT.RAVG)RMX=RMX+R4

RMX=RMX\*.5

```

RMN=0.0
IF(R1 LT.RAVG)RMN=RMN+R1
IF(R2 LT.RAVG)RMN=RMN+R2
IF(R3.LT.RAVG)RMN=RMN+R3
IF(R4.LT.RAVG)RMN=RMN+R4
RMN=RMN*.5
RLEN=RMX-RMN

```

---

- Determines ZBASE node.

---

```

IF(I.NE.I1) GO TO 10
ITEST1=I2
ITEST2=I4
GO TO 60
10   IF(I.NE.I2) GO TO 20
ITEST1=I1
ITEST2=I3
GO TO 60
20   IF(I.NE.I3) GO TO 30
ITEST1=I2
ITEST2=I4
GO TO 60
30   IF(I.NE.I4) GO TO 40
ITEST1=I3
ITEST2=I1
GO TO 60
40   WRITE(6,50) I,IBOT
50   FORMAT(' NODE NUMBER ',I5,' IS NOT OF ELEMENT ',I5/)
CALL EXIT
60   CONTINUE
IF(CORD(ITEST1,2).LT.CORD(ITEST2,2)) GO TO 70

```

---

- ITEST2 is ZBASE node.

---

```
ZBASE=CORD(ITEST2,2)
```

```
RETURN
```

```
*-----  
*  
*      ITEST1 is ZBASE node.  
*  
*-----
```

```
70      ZBASE=CORD(ITEST1,2)
```

```
      RETURN  
      END
```

•  
•  
• Main SCRUBS: Program designed to compute the failure, collapse,  
and resulting subsidence of geologic materials.

•  
• Elastic Plastic analysis of plane stress/strain and axisymmetric  
problems for linear, parabolic, and cubic elements.

•  
• Written by:  
G. NAYAK.....University College of Swansea

•  
• Compiled for CDC 7600 by:  
C. ANDERSON.....Los Alamos Scientific Laboratory  
RV BROWNING.....Los Alamos Scientific Laboratory

•  
• Modified to treat finite strain, large deformation, and  
geotechnical rubble formation by:  
S.E. BENZLEY.....Brigham Young University

•  
•  
• Called by SCRUBSV (a file driver)

•  
•  
• Subroutines called: SOLVEREADF  
ZONEOUTPUTLDATA  
GDATASET\_PDISP  
FLAGETFORMRESIDUE  
RESOLVBSUBSTIFM  
CONVGRUBDRAWDATALST (not used at present)

#### SUBROUTINE SCRUBS

IMPLICIT DOUBLE PRECISION (A-H,O-Z)  
COMMON/ELPRNT/ NELP,NPEL(50),NONODE

COMMON/DUMM/ SAVG(4),SPLT(4,1000)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,  
NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,

```

2      NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3      TPWORK,KNE
COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
COMMON/BOUN/NBC(400),NFIIX(400),U(800),ANG(400),TRC(800),
1      US(400,2)
COMMON/LDS/R1(2000),RL(2000),RT(2000)
COMMON/GID/XG(6),CG(6),XMG(6),CMG(6),NGAUS,MGAUS,MCN
COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST
1      ,TABSTN(10,15),TABSTR(10,15)
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),
1      CORD(1000,2)
1      ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),
2      DUMMY(1000)
COMMON/DLIST/ LN,LNCT,TITL (20)
COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),
1      GAMMA
COMMON/BOTTOM/ AK
COMMON/QMESH/NEL
DIMENSION IRAY(2)
REAL TINC,UDUM(2,1000),SPLTDUM(4,1000),CORDDUM(1000,2)
REAL TIME1,TIME2,TIME3,TITLD(20)
DATA LNCT/55/
DATA IRAY(1),IRAY(2)/10,12/

C      CALL FTNBIN(1,2,IRAY)
C      REWIND 12
C      CALL DATALST(12,5,6)
NRS=0

```

---

\* \* \* \* \* Opens and reads data from QMESH9.DAT file in subroutine ZONE.

---

```

CALL ZONE(NRS)
IF(NRS.NE.1) GO TO 20

```

---

\* \* \* \* \* Reads restart file, SCRUBS.RST.

---

```
REWIND(2)
```

```

      READ(2) (TITLE(I),I=1,57),(FAC(I),I=1,1210),(NBC(I),I=1,1800),
1  (R1(I),I=1,6000),(XG(I),I=1,27),((D(I,J),I=1,4),J=1,4),
2  ((DIS(I,J),I=1,2),J=1,1000),LN,LNCT,(TITL(I),I=1,20),
3  (FLAG(I),I=1,3510),AK,NELP,(NPEL(I),I=1,51)

      NECN=NE*NCN
      READ(2) (NOP(J),J=1,NECN),(IMAT(I),I=1,NE),(((DISN(K,I),
1   TDIS(K,I)),K=1,2),(CORD(I,J),J=1,NCORD ),I=1,NP),(((TSTS(I,J),
2   EPSTN(I,J)),I=1,5),J=1,NSTORE)
3   ,((TABSTN(I,J),I=1,10),J=1,15),((TABSTR(I,J),I=1,10),J=1,15)
      REWIND (8)
      WRITE(8)(NOP(J),J=1,NECN),(IMAT(I),I=1,NE),(((DISN(K,I),
1   TDIS(K,I)),K=1,2),(CORD(I,J),J=1,NCORD ),I=1,NP),(((TSTS(I,J),
2   EPSTN(I,J)),I=1,5),J=1,NSTORE)
      REWIND (8)

```

---

- 
- Writes the solution controls to SCRUBS LIS.
- 

---

```

      WRITE(6,10) (TITLE(I),I=1,20)
10  FORMAT(' ',20A4,' **** THIS PROBLEM HAS BEEN RESTARTED '
1   '****/')
      WRITE(6,15) NP,NE,NB,NLD,NDF,NMAT,NSFR,NGAUS,NALGO,NPP,
1   NYIELD,NT,NL,NSIZ,NCORD,MGAUS
15  FORMAT('          CONTROL PARAMETERS'
1   '          NUMBER OF NODAL POINTS----',I3//'
2   '          NUMBER OF ELEMENTS-----',I3//'
3   '          NUMBER OF BOUNDARY POINTS---',I3//'
4   '          NUMBER OF LOAD CASES-----',I2//'
5   '          NUMBER OF DEGREES OF FREEDOM--',I2//'
6   '          NUMBER OF MATERIALS-----',I2//'
7   '          ORDER OF THE ELEMENTS-----',I2//'
8   '          NUMBER OF GAUSS POINTS-----',I2//'
9   '          SOLUTION ALGORITHM-----',I2//'
A   '          GEOMETRY NUMBER-----',I2//'
B   '          YIELD CONDITION NUMBER-----',I2//'
C   '          NUMBER OF ARBITRARY STIFF---',I2//'
D   '          BLANK-----',I2//'
E   '          BAND WIDTH (NOT NEEDED)----',I2//'
F   '          NUMBER OF COORDINATES-----',I2//'
G   '          GAUSS PTS FOR. RES. CALC----',I2)
      CALL OUTPUT
      GO TO 30

```

20 CONTINUE

- 
- Reads NPROB, the number of problems, from SCRUBS.DAT, and
- writes NPROB and the starting time to SCRUBS.LIS.
- 

---

```

READ(5,25) NPROB
25   FORMAT(16I5)
      DO 760 NPR=1,NPROB
          TIME1=SECNDS(0.0)
          WRITE(6,26) NPR,TIME1
26   FORMAT(' PROBLEM NO.',I3,3X,'EXECUTION STARTED AT ',
1           F10.3)
```

---

- - Reads the title from SCRUBS.DAT and writes it to SCRUBS.LIS.
  -
- 

```

READ(5,27) (TITLE(I),I=1,20)
27   FORMAT(20A4)
      WRITE(6,27) (TITLE(I),I=1,20)
```

---

- - Reads solution control data from SCRUBS.DAT.
  -
- 

```

FACTOR=0.
READ (5,25)NP,NE,NB,NLD,NDF,NMAT,NSFR,NGAUS,NALGO,NPP,
1     NYIELD,NT,NL,NSIZ,NCORD,MGAUS
```

---

- - Opens RUB.MOV file if rubble flag is set equal to 1.
  -
- 

```

IF(NL.EQ.1)OPEN(UNIT=14,TYPE='NEW',ACCESS='SEQUENTIAL',
1           NAME='RUB.MOV')
```

- 
- Reads comment header from first line of QMESH9.DAT,
- then the number of elements (NE) and the
- number of nodal points (NP).
- 

---

REWIND 9

C     READ(9) KOMT  
      IF(NEL EQ 0) READ(9) KOMT  
      READ(9) NE,NP

---

- - Writes the solution controls to SCRUBS.LIS.
  -
- 

IF(NCORD.EQ.0) NCORD=2  
   IF(MGAUS.EQ.0)MGAUS=NGAUS  
   WRITE(6,15)NP,NE,NB,NLD,NDF,NMAT,NSFR,NGAUS,NALGO,NPP,  
 1    NYIELD,NT,NL,NSIZ,NCORD,MGAUS

---

- - Reads material properties.
  -
- 

30           CONTINUE  
 DO 40 L=1,NMAT  
      READ (5,35)N,(ORT(N,I),I=1,6)  
 35       FORMAT(I10,6G10.4)  
 40       IF(ORT(N,2) LT 0.0) READ (5,50) (ORT(N,I),I=9,10)  
 50       FORMAT(2G12.5)  
      WRITE(6,60)  
 60       FORMAT(' MATERIAL PROPERTIES'/  
 1           '    MATL   YOUNGS MOD   POIS RAT    YIELD'  
 2           '    HARD MOD   ANGLE THICK ')  
      DO 90 N=1,NMAT  
       IF(NYIELD NE 3) GO TO 70

---

- Adjusts the yield stress and the yield angle for Von Mises failure criteria.
  -
- 

```

C=ORT(N,3)
THETA=ORT(N,5)
SN=SIN(THETA)
DNOM=1.73205080757*(3.-SN)
ORT(N,3)=6.*C*COS(THETA)/DNOM
ORT(N,5)=2.*SN/DNOM
70   WRITE(6,80)N,(ORT(N,I),I=1,6)
80   FORMAT(I10,G12.4,G12.4,2G12.4,3G9.4)
90   IF(ORT(N,2).LT.0.0)WRITE(6,100) (ORT(N,I),I=9,10)
100  FORMAT('      JOINTED MEDIA MATERIAL-- DELTA=',F8.4,
1      'GS=',E10.4)

```

---

- Tabulated stress/plastic-strain data.
  -
- 

```

110   WRITE(6,110)
      FORMAT(' TABULATED PLASTIC STRAIN-STRESS DATA')
      DO 180 N=1,NMAT
         TABSTR(N,1)=ORT(N,3)
         IF(ORT(N,4).LT.0.) GO TO 120
         NTAB=2
         TABSTN(N,2)=1.
         TABSTR(N,2)=TABSTR(N,1)+ORT(N,4)
         GO TO 140

```

---

- Reads tabulated stress/strain data from SCRUBS.DAT.
  -
- 

```

120   READ(5,35) NTAB
      READ(5,130)(TABSTR(N,I),I=2,NTAB)
130   FORMAT(10F8.0)
      READ(5,130) (TABSTN(N,I),I=2,NTAB)
140   CONTINUE

```

TABSTN(N,1)=0.0

• Writes tabulated stress/strain data to SCRUBS.LIS.

```

      WRITE(6,150)
150   FORMAT(' TABULATED STRESS VALUES')
      WRITE(6,160) (TABSTR(N,I),I=1,NTAB)
160   FORMAT(' ',15E9.3)
      WRITE(6,170)
170   FORMAT(' TABULATED STRAIN VALUES')
      WRITE(6,180) (TABSTN(N,I),I=1,NTAB)
180   FORMAT(1X,15E9.3)
190   IF(NRS.EQ.1) GO TO 290

```

• Reads and sets bulking parameters.

```

IF(NL.EQ.0) GO TO 260
DO 200 L=1,NMAT
200   READ(5,35) N,(ORT(N,I),I=7,8)
      WRITE(6,210)
      FORMAT(' BULKING PROPERTIES/' ' MATL FAILURE '
     1 'STRESS ALPHA/')
      DO 220 N=1,NMAT
220   WRITE(6,80),N,(ORT(N,I),I=7,8)
      READ(5,230) AK
230   FORMAT(E10.3)
      WRITE(6,240) AK
240   FORMAT(' +++++++ LOWER BOUNDARY INDICATOR, AK =',E15.4)
```

• Reads failure parameters, NRFF = number of load steps with defined  
element removal.

READ(5,25) NRFF

```

        WRITE(6,250) NRFF
250      FORMAT(' FAILURE READ FLAG (I.E. NUMBER OF LOAD '
1           'STEPS) = ',I5)
        IF(NRFF NE 0) CALL READF(NRFF)
260      CONTINUE

```

---

- Preset discs.

---

```

REWIND 3
REWIND 4
REWIND 8
ICS=3
IF(NPP.EQ.2)ICS=4
NCN=4*NSFR
MCN=MGAUS*MGAUS
NSZF=NP*NDF
LV=NCN*NDF
NSTORE=MCN*NE
WRITE(6,270)NCN,MCN,LV,NSZF,ICS,NSTORE
270      FORMAT(' NODES/ELEMENT=',I2,2X,' GAUSSIAN POINTS=',I3,
1           'UNKNOWNS/ELEMENT=',I3,2X,'TOTAL UNKNOWNS=',I4,2X,
2           'DMATRIX SIZE=',I2,2X,'STRESS STORE=',I4)

```

---

- Recomputes NSTORE if slip plane is added.

---

```

IIF=1
IF(NNP.GT.0)IIF=-1

```

---

- Reads geometrical data.

---

CALL GDATA (IIF)

---

\* Sets initial areas.

---

```

IF(NL.EQ.0) GO TO 290
DO 280 N=1,NE
  K1=(N-1)*NSFR*4+1
  K2=K1+NSFR
  K3=K2+NSFR
  K4=K3+NSFR
  J1=NOP(K1)
  J2=NOP(K2)
  J3=NOP(K3)
  J4=NOP(K4)
  COE1=CORD(J2,1)-CORD(J4,1)
  COE2=CORD(J3,2)-CORD(J1,2)
  COE3=CORD(J3,1)-CORD(J1,1)
  COE4=CORD(J4,2)-CORD(J2,2)
  AREA=.5*(COE1*COE2+COE3*COE4)
  BULK(N,1)=0.
  BULK(N,2)=AREA
280      CONTINUE
290      CONTINUE

```

---

\* Writes first record for plot tape output (SCRUBS MOV).

---

```

DO 300 I=1,20
300      TITLD(I)=TITLE(I)
         WRITE(10) TITLD,NE,NP
         DO 310 I=1,NP
           CORDDUM(I,1)=SNGL(CORD(I,1))
310      CORDDUM(I,2)=SNGL(CORD(I,2))
         WRITE(10)(CORDDUM(I,1),I=1,NP),(CORDDUM(I,2),I=1,NP),
         1((NOP(NCN*(K-1)+M),K=1,NE),M=1,NCN),(IMAT(I),I=1,NE)
         IF(NRS.EQ.1) GO TO 360

```

---

\* Sets element spacing and checks bandwith and stiffness dimensioning.

---

---

 CALL SET
 

---

- Inputs loads.

---

```

DO 750 ILD=1,NLD
    TTWORK=0.
    READ(5,25)ISTS,LDTYPE
    WRITE(6,320)ISTS,LDTYPE
320    FORMAT(' INITIAL STRESS COUNTER=',I2,2X,'LOAD TYPE '
1           'COUNTER=',I2)
    NASH=0
    DO 330 J=1,NP
        DO 330 I=1,NDF
            NASH=NASH+1
C           330 TDIS(I,J)=RL(NASH)=DISN(I,J)=RT(NASH)=R1(NASH)=0>
            TDIS(I,J)=0.
            RL(NASH)=0.0
            DISN(I,J)=0.0
            RT(NASH)=0.0
            R1(NASH)=0.0
330    CONTINUE
        DO 340 J=1,NSTORE
            DO 340 I=1,5
                EPSTN(I,J)=0.
340    TSTS(I,J)=0.
        NECN=NE*NCN
        WRITE(8)(NOP(J),J=1,NECN),(IMAT(I),I=1,NE),(((DISN(K,I),
1           TDIS(K,I)),K=1,2),(CORD(I,J),J=1,NCORD ),I=1,NP),
2           ((TSTS(I,J),EPSTN(I,J)),I=1,5),J=1,NSTORE)
            REWIND 8
            NASH=0
            DO 350 I=1,NB
                DO 350 K=1,2
                    NASH=NASH+1
350    TRC(NASH)=0.
        IF(LDTYPE EQ 2) GO TO 410
        CALL LDATA(IIF)
360    CONTINUE
        READ (5,25)NINC
    
```

```

        WRITE(6,370) NINC
370      FORMAT(' NO. OF INCREMENTS =',I2/
1           ' INCREMENT    OUTPUT LD FACTOR')
           READ (5,380)(FAC(I),I=1,NINC)
380      FORMAT(16F5.3)
           READ (5,25)(NOUT(I),I=1,NINC)
           DO 390 I=1,NINC
390      WRITE(6,400)I,NOUT(I),FAC(I)
400      FORMAT(2I10,F10.3)
           GO TO 420
410      FACTOR=1.
420      CONTINUE
           READ (5,35)NIT,CONFAC
           WRITE(6,430)NIT,CONFAC
430      FORMAT(' NUMBER ITERATIONS =',I2,5X,'CONVERGENCE '
1           'FACTOR =',F10.2)
           IF(NL.EQ.1.AND.NRS.NE.1) CALL FLAGE(NP,NE,5,IIF)

```

---

- Sets print controls.

---

```

           READ(5,440) NELP,NONODE
440      FORMAT(16I5)
           IF(NELP.LE.0) GO TO 470
           READ(5,440) (NPEL(K),K=1,NELP)
           WRITE(6,450)
450      FORMAT(' ELEMENTS TO BE PRINTED')
           WRITE(6,460) (NPEL(K),K=1,NELP)
460      FORMAT(1X,26I5/26I5)
           CONTINUE

```

---

- Begins loop for each increment.

---

```

           DO 740 INC=1,NINC
           TPWORK=0.
           WRITE(6,480)INC
480      FORMAT(' LOAD INCREMENT NO. =',I3)
           IF(LDTYPE.EQ.2) GO TO 500

```

```

GASH=FAC(INC)
FACTOR=FACTOR+GASH
NASH=0
DO 490 J=1,NP
    DO 490 I=1,NDF
        NASH=NASH+1
        GOSH=RL(NASH)*GASH
        RT(NASH)=RT(NASH)+GOSH
        R1(NASH)=R1(NASH)+GOSH
490     CONTINUE
        CALL TFORM
        GO TO 510
500     CALL LDATA(IIF)
        IF(INC.GT.1 .AND. NALGO.NE.1) GO TO 530
        CALL PDISP(1)
        CALL STIFM
        TIME3=SECNDS(TIME1)
        WRITE(6,520)TIME3
520     FORMAT(' STIFFNESS FORMULATION FINISHED AT',F10.3)
        CALL SOLVE
        GO TO 540
530     CALL PDISP(INC)
        CALL RESOLV
540     CALL BSUB
        IF(NALGO.EQ.0) CALL RESIDUE (TIME1,IFCOUNT,MTGPY)
        IF(NALGO.EQ.0) GO TO 600
        CALL PDISP(0)

```

---



---



---



---

Begins loop for each iteration.

---



---

```

DO 580 IT=1,NIT
    CALL RESIDUE (TIME1,IFCOUNT,MTGPY)
    CALL CONVG(NCHECK)
    CALL TFORM
    IF(IT.EQ.1 .AND. NOUT(INC).GT.100)CALL OUTPUT
    IF(NCHECK.EQ.0) GO TO 600
    IF(NALGO.LT.2)GO TO 560
    IF(NALGO.GT.2)GO TO 550
    IF(IT.NE.1)GO TO 560
    CONTINUE
550

```

---

- If no elements have yielded or rubblized, do not reform stiffness matrix.

---

```

IICK=IFCOUNT+MTGPY
IF(IICK.EQ.0) GO TO 560
CALL STIFM
TIME3=SECNDS(TIME1)
WRITE(6,520)TIME3
CALL SOLVE
GO TO 570
560 CALL RESOLV
570 CALL BSUB
580 CONTINUE
IT=NIT+1
CALL RESIDUE (TIME1,IFCOUNT,MTGPY)
CALL CONVG(NCHECK)
WRITE(6,590) INC
590 FORMAT('      NO CONVERGENCE ON INCREMENT NO',I3)
      GO TO 760
600 CONTINUE
CALL OUTPUT

```

---

- Write restart tape (SCRUBS.RST).

---

```

REWIND(2)
WRITE(2) (TITLE(I),I=1,57),(FAC(I),I=1,1210),(NBC(I),
1     I=1,1800),(R1(I),I=1,6000),(XG(I),I=1,27),((D(I,J),
2     I=1,4),J=1,4),((DIS(I,J),I=1,2),J=1,1000),LN,LNCT,
3     (TITL(I),I=1,20),(FLAG(I),I=1,3510),AK,NELP,
4     (NPEL(I),I=1,51)
      NECN=NE*NCN
      WRITE(2)(NOP(J),J=1,NECN),(IMAT(I),I=1,NE),
1     (((DISN(K,I),TDIS(K,I)),K=1,2),(CORD(I,J),J=1,NCORD ),
2     I=1,NP),(((TSTS(I,J),EPSTN(I,J)),I=1,5),J=1,NSTORE),
3     ((TABSTN(I,J),I=1,10),J=1,15),((TABSTR(I,J),I=1,10),
4     J=1,15))
      WRITE(6,610)

```

```

610      FORMAT(' * * * RESTART FILE HAS BEEN '
1      'WRITTEN * * *')
      IF(NALGO EQ 0) GO TO 740
      TTWORK=TTWORK+TPWORK
      WRITE(6,620)INC,TTWORK
620      FORMAT(' INC NO ,I2,5X,'TOTAL PLASTIC WORK =',E12.4)
      TIME2=SECNDS(TIME1)
      WRITE(6,630) TIME2
630      FORMAT(4X,'EXECUTION FINISHED AT ',F10.3)

```

---

- 
- 
- Computes average stress in each element.
- 
- 

---

```

XMCN=MCN
DO 670 M=1,NE
      K=MCN*(M-1)
      DO 640 I=1,4
      SAVG(I)=0.0
      DO 650 I=1,4
      DO 650 L=1,MCN
      J=K+L
      SAVG(I)=SAVG(I)+TSTS(I,J)
      DO 660 I=1,4
      SAVG(I)=SAVG(I)/XMCN
      SPLT(1,M)=SAVG(1)
      SPLT(2,M)=SAVG(2)
      SPLT(3,M)=SAVG(4)
      SPLT(4,M)=SAVG(3)
670      CONTINUE

```

---

- 
- 
- Writes displacements, stresses, and strains for plot tape
- SCRUBS MOV.
- 
- 

---

```

TINC=INC
WRITE(10) TINC
DO 680 I=1,NP
      UDUM(1,I)=SNGL(TDIS(1,I))
      UDUM(2,I)=SNGL(TDIS(2,I))
680

```

```

DO 690 J=1,NE
  DO 690 I=1,4
690      SPLTDUM(I,J)=SNGL(SPLT(I,J))
      WRITE(10) (UDUM(1,I),UDUM(2,I),I=1,NP),
1      (UDUM(1,I),UDUM(2,I),I=1,NP),
2      (UDUM(1,I),UDUM(2,I),I=1,NP)
      WRITE(10) ((SPLTDUM(I,J),J=1,NE),I=1,4)

```

---

- - Writes rubble file (RUB.MOV).
  -
- 

```
IF(NL.EQ.1) CALL RUBDRAW(NE,TINC,NP)
```

---

- - Computes average strain in each element.
  -
- 

```

DO 730 M=1,NE
  K=MCN*(M-1)
  DO 700 I=1,4
700      SAVG(I)=0.0
  DO 710 I=1,4
    DO 710 L=1,MCN
      J=K+L
710      SAVG(I)=SAVG(I)+EPSTN(I,J)
      DO 720 I=1,4
720      SAVG(I)=SAVG(I)/XMCN
      SPLTDUM(1,M)=SNGL(SAVG(1))
      SPLTDUM(2,M)=SNGL(SAVG(2))
      SPLTDUM(3,M)=SNGL(SAVG(4))
      SPLTDUM(4,M)=SNGL(SAVG(3))
730      CONTINUE
      WRITE(10) ((SPLTDUM(I,J),J=1,NE),I=1,4)
740      CONTINUE
750      CONTINUE
760      CONTINUE

      RETURN
      END

```

Subroutine SCRUBSV: This subroutine opens and closes the files used by the main program, SCRUBS. The files:

UNITNAME  
2SCRUBS.RST  
3scratch file  
4scratch file  
5SCRUBS.DAT  
6SCRUBS.LIS  
8scratch file  
9QMESH9.DAT  
10SCRUBS.MOV  
14RUB.MOV

Written:

Last modified: MAR 19 1984

Subroutines called: SCRUBSEXIT

#### PROGRAM SCRUBSV

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK,KNE
COMMON/QMESH/NEL
```

The files are opened.

```
OPEN(UNIT=2,TYPE='UNKNOWN',ACCESS='SEQUENTIAL',
```

```
1 NAME='SCRUBS.RST',FORM='UNFORMATTED')
```

```
OPEN(UNIT=3,TYPE='SCRATCH',ACCESS='SEQUENTIAL',
```

```
1      FORM='UNFORMATTED')
      OPEN(UNIT=4,TYPE='SCRATCH',ACCESS='SEQUENTIAL',
1      FORM='UNFORMATTED')
      OPEN(UNIT=5,TYPE='OLD',ACCESS='SEQUENTIAL',NAME='SCRUBS.DAT')
      OPEN(UNIT=6, TYPE='NEW',ACCESS='SEQUENTIAL',NAME='SCRUBS.LIS')
      OPEN(UNIT=10,TYPE='NEW',ACCESS='SEQUENTIAL',NAME='SCRUBS.MOV',
1      FORM='UNFORMATTED')
      OPEN(UNIT=9,TYPE='UNKNOWN',ACCESS='SEQUENTIAL',
1      NAME='QMESH9.DAT',FORM='UNFORMATTED')
      OPEN(UNIT=8,TYPE='SCRATCH',ACCESS='SEQUENTIAL',
1      FORM='UNFORMATTED')
```

- 
- The main program, SCRUBS, is called.
- 

CALL SCRUBS

- 
- The files are closed, and the system call EXIT is used.
- 

```
CLOSE(UNIT=2)
CLOSE(UNIT=3)
CLOSE(UNIT=4)
CLOSE(UNIT=5)
CLOSE(UNIT=6)
IF(NEL EQ 0) CLOSE(UNIT=9)
IF(NEL NE 0) CLOSE(UNIT=9,DISPOSE='DELETE')
IF(NL EQ 1)CLOSE(UNIT=10)
CLOSE(UNIT=8)
CALL EXIT
```

STOP  
END

---



---



---

Subroutine SET:  
Sets element spacing and determines bandwidth and resulting  
stiffness storage required.

---



---

Written:  
Last modified: MAR 19 1984

---



---



---

Called by: SCRUBS

#### SUBROUTINE SET

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS  
 1 ,NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,  
 2 NSTORE  
 COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)  
 COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)  
 1 ,NOP(4000),IMAT(1000),ION(6,1000)

DO 10 J=1,6  
 DO 10 I=1,NP  
 10 ION(J,I)=0

---



---



---

Selects spacing.

DO 50 L=1,NE  
 NASH=NCN\*(L-1)  
 IST=NOP(NASH+1)  
 MAX=IST  
 MIN=IST  
 DO 20 N=2,NCN  
 NTH=NOP(NASH+N)

```

IF (NTH .EQ. 0) GO TO 30
IF ( MAX .LT. NTH) MAX=NTH
IF ( MIN .LE. NTH) GO TO 20
MIN=NTH
20      CONTINUE
30      IF (NSIZ .LT. (MAX-MIN)*NDF) NSIZ=(MAX-MIN)*NDF
I=MIN
DO 40 M=1,6
IF(ION(M,I).NE.0) GO TO 40
ION(M,I)=L
GO TO 50
40      CONTINUE
50      CONTINUE
L=1
DO 70 I=1,NP
DO 60 M=1,6
IF(ION(M,I).EQ.0) GO TO 70
IONARY(L)=ION(M,I)
60      L=L+1
70      CONTINUE
IONARY(L)=0

```

---

- 
- Determines if bandwidth is too high and stiffness dimensioning
- is exceeded.
- 

---

```

NSK=((NSIZ+NDF)*(NSIZ +NDF+1))/2+1
IF(NSK.LT.NSZF+1) NSK=NSZF+1
IF(NSK.LE.9000) RETURN
WRITE(6,80)
80      FORMAT(' PROGRAM HALTED IN SET, '
1 'STIFFNESS SPACE EXCEEDED')
STOP
END

```

Subroutine SFR:  
Sets shape functions according to element type.

Written:  
Last modified: JUL 14 1984

Called by: LDATAREMLDRESIDUE  
STIFM

#### SUBROUTINE SFR(G,H)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD

COMMON/NUME/P(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),

1 NOPE(12),DISE(2,12),RP,RPB,XYP(3)

G and H denote the xi and eta values at the point considered.

GG = G\*G

GH = G\*H

HH = H\*H

GGH = GG\*H

GHH = G\*HH

IF(NSFR-2)10,20,30

Linear shape functions and their first derivatives for  
four noded arbitrary quadrilateral.

10            $P(1) = (1.-G-H+GH)/4.$   
                $P(2) = (1.+G-H-GH)/4.$   
                $P(3) = (1.+G+H+GH)/4.$   
                $P(4) = (1.-G+H-GH)/4.$   
                $DEL(1,1) = (-1.+H)/4.$   
                $DEL(1,2) = -DEL(1,1)$   
                $DEL(1,3) = (1.+H)/4.$   
                $DEL(1,4) = -DEL(1,3)$   
                $DEL(2,1) = (-1.+G)/4.$   
                $DEL(2,2) = (-1.-G)/4.$   
                $DEL(2,3) = -DEL(2,2)$   
                $DEL(2,4) = -DEL(2,1)$   
               RETURN

---

- - Parabolic shape functions and their first derivatives for curved 8-nodal arbitrary quadrilateral.
  - 
  -
- 

20            $G2 = G*2.$   
                $H2 = H*2.$   
                $GH2 = GH*2.$   
                $P(1) = (-1.+GH+GG+HH-GGH-GHH)/4.$   
                $P(2) = (1.-H-GG+GGH)/2.$   
                $P(3) = (-1.-GH+GG+HH-GGH+GHH)/4.$   
                $P(4) = (1.+G-HH-GHH)/2.$   
                $P(5) = (-1.+GH+GG+HH+GGH+GHH)/4.$   
                $P(6) = (1.+H-GG-GGH)/2.$   
                $P(7) = (-1.-GH+GG+HH+GGH-GHH)/4.$   
                $P(8) = (1.-G-HH+GHH)/2.$   
                $DEL(1,1) = (H+G2-GH2-HH)/4.$   
                $DEL(1,2) = -G+GH$   
                $DEL(1,3) = (-H+G2-GH2+HH)/4.$   
                $DEL(1,4) = (1.-HH)/2.$   
                $DEL(1,5) = (H+G2+GH2+HH)/4.$   
                $DEL(1,6) = -G-GH$   
                $DEL(1,7) = (-H+G2+GH2-HH)/4.$   
                $DEL(1,8) = (-1.+HH)/2.$   
                $DEL(2,1) = (G+H2-GG-GH2)/4.$   
                $DEL(2,2) = (-1.+GG)/2.$   
                $DEL(2,3) = (-G+H2-GG+GH2)/4.$   
                $DEL(2,4) = -H-GH$   
                $DEL(2,5) = (G+H2+GG+GH2)/4.$

```

DEL(2,6)=( 1.-GG)/2.
DEL(2,7)=(-G+H2+GG-GH2)/4.
DEL(2,8)= -H+GH
RETURN
30    CONTINUE
GGG = GG*G
HHH = H*HH
GGGH = GGG*H
GHHH = G*HHH

```

---

\*  
\* Cubic shape functions and their first derivatives for  
\* curved 12-nodal arbitrary quadrilateral.  
\*

---

```

G9 = G*9.
G10 = G*10.
G18 = G*18.
G27 = G*27.
H9 = H*9.
H10 = H*10.
H18 = H*18.
H27 = H*27.
GG9 = GG*9.
GG27 = GG*27.
GG81 = GG*81.
GH10 = GH*10.
GH18 = GH*18.
GH27 = GH*27.
HH9 = HH*9.
HH27 = HH*27.
HH81 = HH*81.
GGG9 = GGG*9.
GGG27 = GGG*27.
GGH9 = GGH*9.
GGH27 = GGH*27.
GGH81 = GGH*81.
GHH9 = GHH*9.
GHH27 = GHH*27.
GHH81 = GHH*81.
HHH9 = HHH*9.
HHH27 = HHH*27.
GGGH9 = GGGH*9

```

```

GGGH27 = GGGH*27.
GHHH9 = GHHH*9.
GHHH27 = GHHH*27.
P(1)= -10.+G10+H10+GG9-GH10+HH9-GGG9-GGH9-GHH9-HHH9+GGGH9+GHHH9
P(2)= 9.-G27-H9-GG9+GH27+GGG27+GGH9-GGGH27
P(3)= 9.+G27-H9-GG9-GH27-GGG27+GGH9+GGGH27
P(4)= -10.-G10+H10+GG9+GH10+HH9+GGG9-GGH9+GHH9-HHH9-GGGH9-GHHH9
P(5)= 9.+G9-H27-GH27-HH9-GHH9+HHH27+GHHH27
P(6)= 9.+G9+H27+GH27-HH9-GHH9-HHH27-GHHH27
P(7)= -10.-G10-H10+GG9-GH10+HH9+GGG9+GGH9+GHH9+HHH9+GGGH9+GHHH9
P(8)= 9.+G27+H9-GG9+GH27-GGG27-GGH9-GGGH27
P(9)= 9.-G27+H9-GG9-GH27+GGG27-GGH9+GGGH27
P(10)=-10.+G10-H10+GG9+GH10+HH9+GGG9+GGH9-GHH9+HHH9-GGGH9-GHHH9
P(11)= 9.-G9+H27-GH27-HH9+GHH9-HHH27+GHHH27
P(12)= 9.-G9-H27+GH27-HH9+GHH9+HHH27-GHHH27
DEL(1, 1)= 10.+G18-H10-GG27-GH18-HH9+GGH27+HHH9
DEL(1, 2)=-27.-G18+H27+GG81+GH18-GGH81
DEL(1, 3)= 27.-G18-H27-GG81+GH18+GGH81
DEL(1, 4)=-10.+G18+H10+GG27-GH18+HH9-GGH27-HHH9
DEL(1, 5)= 9.-H27-HH9+HHH27
DEL(1, 6)= 9.+H27-HH9-HHH27
DEL(1, 7)=-10.+G18-H10+GG27+GH18+HH9+GGH27+HHH9
DEL(1, 8)= 27.-G18+H27-GG81-GH18-GGH81
DEL(1,10)= 10.+G18+H10-GG27+GH18-HH9-GGH27-HHH9
DEL(1, 9)=-27.-G18-H27+GG81-GH18+GGH81
DEL(1,11)=-9.-H27+HH9+HHH27
DEL(1,12)=-9.+H27+HH9-HHH27
DEL(2, 1)= 10.-G10+H18-GG9-GH18-HH27+GGG9+GHH27
DEL(2, 2)=-9.+G27+GG9-GGG27
DEL(2, 3)= 9.-G27+GG9+GGG27
DEL(2, 4)= 10.+G10+H18-GG9+GH18-HH27-GGG9-GHH27
DEL(2, 5)=-27.-G27-H18-GH18+HH81+GHH81
DEL(2, 6)= 27.+G27-H18-GH18-HH81-GHH81
DEL(2, 7)=-10.-G10+H18+GG9+GH18+HH27+GGG9+GHH27
DEL(2, 8)= 9.+G27-GG9-GGG27
DEL(2, 9)= 9.-G27-GG9+GGG27
DEL(2,10)=-10.+G10+H18+GG9-GH18+HH27-GGG9-GHH27
DEL(2,11)= 27.-G27-H18+GH18-HH81+GHH81
DEL(2,12)=-27.+G27-H18+GH18+HH81-GHH81
DO 50 J=1,12
DO 40 I=1,2
    DEL(I,J)=DEL(I,J)/32.
CONTINUE
P(J)=P(J)/32.
CONTINUE

```

RETURN  
END

---



---



---

- Subroutine SLIPP:
- This subroutine reads the slip plane data, adjusts the geometry and elements accordingly, and then records the adjusted information.

---

- Written:
- Last modified: MAR 19 1984

---

- Called by: GDATA

---

- Subroutines called: NEWNODCORN  
MAKEELNODEXY

---

#### SUBROUTINE SLIPP

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,JLD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK,KNE
COMMON/BOUN/NBC(400),NFI(400),U(800),ANG(400),TRC(800),
1 US(400,2)
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)
COMMON/SLP/DCOR(1000,2)
DIMENSION MAP(1000,2)
INTEGER SLIP(500,2),CORNER(500),EL
```

NSP=IABS(NNP)

\*  
 \*       Saves old information.  
 \*

---



---

```
NEOLD=NE
NPOLD=NP
DO 10 N=1,NP
DCOR(N,1)=CORD(N,1)
10 DCOR(N,2)=CORD(N,2)

      WRITE(6,20)
20   FORMAT(//,1X,10('*'),' SLIP PANE BOUNDARY DATA ',10('*'))
      WRITE(6,30) NSP
30   FORMAT(//,' NUMBER OF SLIP PLANES = ',I2)
```

---



---

\*  
 \*       Loops on number of slip planes.  
 \*

---



---

```
DO 340 INSP=1,NSP
```

---



---

\*  
 \*       Reads in slip plane data.  
 \*

---



---

```
READ(5,40) NSLIP,IANG,DELTA
40   FORMAT(2I5,G10.3)

      K=(NSLIP-1)/16+1
      J=1
      DO 60 I=1,K
      JJ=J+15
      IF(JJ.GE.NSLIP)JJ=NSLIP
      READ(5,50) (SLIP(N,1),N=J,JJ)
50   FORMAT(16I5)
60   J=J+16
      IF(DELTA.LE.0)DELTA=[DABS(CORD(1,1)-CORD(2,1))+  

      + DABS(CORD(1,2)-CORD(2,2))]/50.
```

\* Changes slip node array to new node numbers.

```
IF(INSP.LE.1) GOTO 80
DO 70 N=1,NSLIP
70     CALL NEWNOD(SLIP(N,1))
80     CONTINUE
     L=4*NSFR
     NECN=NCN*NE
```

\* Loops on number of slip plane nodes.

```
DO 210 I=1,NSLIP
NADD=1
IX=SLIP(I,1)
SLIP(I,2)=0
CORDN=CORD(IX,IANG)+DELTA
```

\* Determines if node is a corner node.

```
CALL CORNN(NADD,NSFR,NP,SLIP(I,2),IX)
```

\* Adds NADD to all numbers in connectivity greater than IX.

```
DO 120 J=1,NECN
     IXX=NOP(J)-IX
     IF(IXX)120,90,110
90     EL=(J+L-1)/L
     X=0.0
     MMM=L*(EL-1)
```

```

DO 100 M=1,L,NSFR
  MM=MMM+M
100   X=X+CORD(NOP(MM),IANG)/4.
      IF(X.LT.CORDN)GOTO 120
110   NOP(J)=NOP(J)+NADD
120   CONTINUE

```

---



---



---

- Updates remaining slip plane node numbers.

---



---

```

DO 130 N=1,NSLIP
130   IF(SLIP(N,1).GT.SLIP(I,1))SLIP(N,1)=SLIP(N,1)+NADD

```

---



---



---

- Updates coordinate array numbers (add NADD to those < IX).

---



---

```

DO 140 J=NP,IX,-1
  IJ=J+NADD
  CORD(IJ,1)=CORD(J,1)
140   CORD(IJ,2)=CORD(J,2)

```

---



---



---

- Assigns coordinate to new node created.

---



---

```

CORD(IJ,IANG)=CORDN
NP=NP+NADD
NUMDUM=0
JJ=NB

```

---



---



---

- Updates boundary arrays, giving new nodes same boundary conditions as corresponding slip plane nodes.

---



---

```

      DO 200 JJJ=1,JJ
      J=JJJ+NUMDUM
      IXX=NBC(J)-IX
      IF(IXX)200,150,190
150     DO 180 II=1,NADD
      NB=NB+1
      IJ=J+II
      DO 170 N=NB,IJ,-1
      NBC(N)=NBC(N-1)
      NFIX(N)=NFIX(N-1)
      DO 160 NN=1,NDF
160     US(N,NN)=US((N-1),NN)
      ANG(N)=ANG(N-1)
170     NBC(IJ)=NBC(IJ)+1
      NUMDUM=NADD
      GOTO 200
180     NBC(J)=NBC(J)+NADD
200     CONTINUE
210     CONTINUE

```

---

- 
- Adds row of slip elements to connectivity.
- 
- Sets up array of corner nodes.
- 

---

```

      NCORN=0
      DO 220 I=1,NSLIP
      IF(SLIP(I,2).EQ.0)GOTO 220
      NCORN=NCORN+1
      CORNER(NCORN)=SLIP(I,1)
220     CONTINUE
      IQUIT=1
      K=0
      I=1

```

---

- 
- Finds corner node in connectivity array.
- 

---

230 J=0

240            J=J+1  
           IF(J.GT.NECN)GOTO 290  
           IF(NOP(J).NE.CORNER(I))GOTO 240

---

- Determines element number of element containing node.
  -
- 

$$EL=(J+L-1)/L$$

- 
- - Finds other corner node contained in same element.
  -
- 

      MMM=L\*(EL-1)  
       DO 260 M=1,L,NSFR  
          MM=MMM+M  
       DO 250 N=1,NCORN  
          IF(N.EQ.I)GOTO 250  
          IF(NOP(MM).EQ.CORNER(N))K=N  
250       CONTINUE  
260       CONTINUE

- 
- Prints error if no such node exists.
  -
- 

      IF(K.GT.0)GOTO 280  
       WRITE(6,270)  
270       FORMAT(' ERROR-- HALTED IN SLIPP, ERROR IN CONNECTIVITY')  
       STOP

- 
- Makes new element.
  -
- 

280       IF(K.EQ.KK)GOTO 240

CALL MAKEEL(MMM,CORNER(I),CORNER(K),IANG)

• Checks to see how many elements are made.

```
IQUIT=IQUIT+1
IF(IQUIT.GE.NCORN)GOTO 300
KK=I
IF(I.EQ.1)KKK=K
I=K
```

• Branches to next element.

```
GOTO 230
290      I=1
         KK=KKK
         GOTO 230
```

• Writes slip plane data.

```
300      CONTINUE
         WRITE(6,310) INSP,DELTA,IANG
310      FORMAT(//,' SLIP PLANE ',I2,
+           /,' THICKNESS=',G10.3,
+           /,' ANGLE FLAG=',I2,
+           /,' NODE LIST: ')
         KNUM=(NSLIP-1)/16.+1
         KSTART=1
         DO 330 ITT=1,KNUM
             KEND=KSTART+15
             IF(KEND.GT.NSLIP)KEND=NSLIP
             WRITE(6,320) (SLIP(J,1),J=KSTART,KEND)
320      FORMAT(16I5)
```

330 KSTART=KSTART+16  
 340 CONTINUE

---

- Writes mapping of old to new nodes into scrubs.ls.

---

```
J=0
DO 350 I=1,NPOLD
  N=I
  CALL NEWNOD(N)
  IF(N.EQ.I)GOTO 350
  J=J+1
  MAP(J,1)=I
  MAP(J,2)=N
350  CONTINUE
  WRITE(6,360)
360  FORMAT(//, '***** NODE NUMBERS WERE CHANGED DUE TO SLIP PLANE'
+  ' ADDITION *****',//,' NODAL MAPPING OF NODES CHANGED',//,
+  ',4X,4('ORIGINAL  NEW   '),/,5X,4('NODE#  NODE#   '))
  K=J/4
  KK=K*4-J
  K1=0
  IF(KK.LE.-1)K1=1
  K2=K1
  IF(KK.LE.-2)K2=K2+1
  K3=K2
  IF(KK.LE.-3)K3=K3+1
  DO 380 M=1,K
    WRITE(6,370) MAP(M,1),MAP(M,2),MAP(M+K+K1,1),MAP(M+K+K1,2),
+    MAP(M+2*K+K2,1),MAP(M+2*K+K2,2),MAP(M+3*K+K3,1),MAP(M+3*K+K3,2)
370  FORMAT(6X,4(I3,6X,I3,7X))
380  CONTINUE
  WRITE(6,370) (MAP(N,1),MAP(N,2),N=K+1,K3*(K+1),K+1)
  WRITE(6,390)
390  FORMAT(//,' SLIP PLANE ELEMENTS CREATED',//,7X,'ELEMENT #'
+  ,6X,'CONNECTIVITY',/)
  ISTART=L*NEOLD+1
  DO 410 N=NEOLD+1,NE
    IEND=ISTART+L-1
    WRITE(6,400) N,(NOP(I),I=ISTART,IEND)
400  FORMAT(10X,I3,4X,12I5)
410  ISTART=IEND+1
```

• Numbers new mid-side nodes.

```
N=NEOLD+1  
IF(NSFR.GT.1)CALL NODEXY(N)
```

```
RETURN  
END
```

• Subroutine SOLVE:

• Solves stiffness equations, modifies loads.

• Written:

• Last modified: JUL 14 1984

• Called by: SCRUBS

#### SUBROUTINE SOLVE

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,  
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,  
3 TPWORK

COMMON/BOUN/NBC(400),NFX(400),U(800),ANG(400),TRC(800),

1 US(400,2)

COMMON/LDS/R1(2000),RL(2000),RT(2000)

COMMON/SCR/SK(20000),R

1 ,ESTIFM(24,24),NN(12),SKS(1200),NOPS(24),ACT(48)

NBF=10000

NSIZ=0

NNP=0

```

NBUF=NSK-1
NZ=1
ND=1
L=0
IF (NT) 10,60,10
10 WRITE (6,20)
20 FORMAT(' ELASTIC STIFFNESSES READ IN')
READ(5,30)NPSP
30 FORMAT(16I5)
NACT=NDF•NPSP
NSKS=NACT•(NACT+1)/2
READ(5,30)(NOPS(I),I=1,NPSP)
READ(5,40)(ACT(I),I=1,NACT)
40 FORMAT(4E20.13)
READ(5,40)(SKS(I),I=1,NSKS)
MASH=0
DO 50 I=1,NPSP
  NASH=(NOPS(I)-1)•NDF
  DO 50 J=1,NDF
    MASH=MASH+1
    NASH=NASH+1
50 R1(NASH)=R1(NASH)+ACT(MASH)
60 CONTINUE
DO 70 N=1,NBF
70 SK(N)=0.
NC=1
READ(3)
1 N,(NN(I),I=1,NCN),((ESTIFM(I,J),J=1,LV),I=1,LV)
80 L=L+1
DO 140 M=1,6
  IF(N.EQ.0) GO TO 150
  DO 90 I=1,NCN
    IF (NN(I) .EQ. L) GO TO 100
90 CONTINUE
GO TO 150
100 NC=NC+1
DO 130 I=1,NCN
  IF(NN(I).EQ.0) GO TO 130
  II=(NN(I)-L)•NDF
  DO 120 J=1,NCN
    IF(NN(J).EQ.0) GO TO 120
    JJ=(NN(J)-L)•NDF
    DO 110 IL=1,NDF
      IA=II+IL
      IC=(I-1)•NDF+IL
110
120
130
140
150

```

```

DO 110 JM=1,NDF
JB=JJ+JM
IF(IA.GT.JB) GO TO 110
JD=(J-1)*NDF+JM
IAB=((JB-1)*JB)/2+IA
SK(IAB)=SK(IAB)+ESTIFM(IC,JD)
110      CONTINUE
120      CONTINUE
NX=(NN(I)-L)*NDF
IF(NSIZ.LT.NX) NSIZ=NX
130      CONTINUE
READ(3)
1      N,(NN(I),I=1,NCN),((ESTIFM(I,J),J=1,LV),I=1,LV)
140      CONTINUE

```

-----  
\*  
\* Sets up load.  
\*  
-----

```

150      CONTINUE
IF (NT) 200,200,160
160      DO 170 II=1,NPSP
        IF(L.EQ.NOPS(II))GO TO 180
170      CONTINUE
        GO TO 200
180      IJ=(II-1)*NDF
        DO 190 I2=1,NDF
          II=IJ+I2
          DO 190 JJ=II,NACT
            I3=(10*JJ/NDF+9)/10
            I5=JJ*(JJ-1)/2+II
            JB=NDF*(NOPS(I3)-L-I3+1)+JJ
            IA=JB*(JB-1)/2+I2
            SK(IA)=SK(IA)+SKS(I5)
190      CONTINUE
200      CONTINUE
NSZ=NSIZ+NDF
JZ=0
IF(NZ EQ NB+1) GO TO 210
IF(L NE NBC(NZ)) GO TO 210
JZ=NFIX(NZ)
IZ=10** (NDF-1)
NZ=NZ+1

```

```

210      DO 390 I=1,NDF
          NSZ=NSZ-1
          IC=I+NDF*(L-1)
          R=R1(IC)
          NBD=0
          IF(JZ.EQ.0) GO TO 230
          IF(JZ.LT.IZ) GO TO 220
          LZ=(NZ-2)*NDF+I
          U(ND)=U(LZ)
          RS=-R
          R=U(ND)
          ND=ND+1
          NBD=1
          JZ=JZ-IZ
220      IZ=IZ/10
230      CONTINUE
          IF (SK(1).GE.0.) GO TO 250
          WRITE(6,240)L,I,SK(1)
240      FORMAT(' NODE NO ',I5,I10,' D.F. ','SK(1) = ',E15.6)
          SK(1)=0.
250      CONTINUE
          NBLK=NSZ+4
          IF((NBUF+NBLK).LE.NBF) GO TO 260
          WRITE(4)NBUF,(SK(J),J=NSK,NBUF)
          NBUF=NSK-1
          NNP=0
260      NNP=NNP+1
          NBUF=NBUF+1
          SK(NBUF)=NSZ
          NBUF=NBUF+1
          IA=NBUF+1

```

---

•

• Invert diagonal term.

•

---

```

          IF(NBD.EQ.1) GO TO 300
          IF(SK(1).NE.0.) GO TO 280
          WRITE(6,270)L,I
270      FORMAT(' PROGRAM HALTED IN SOLVE'/
           ' NEGATIVE OR ZERO DIAGONAL STIFFNESS'/
           ' NODE NO.',I4,I10,' D.F.')
          STOP

```

```

280      CONTINUE
        XK=1./SK(1)
        SK(NBUF)=XK


---


*-----*
*-----*
*-----* Modify loads and off-diagonal terms.
*-----*
*-----*


---


290      R1(IC)=XK*R
        GO TO 310
300      SK(NBUF)=-SK(1)
        R1(IC)=SK(1)*R+RS
        XK=1.
        R=-R
310      CONTINUE
        IF(L+I-NP-NDF) 320,400,320
320      NBUF=NBUF+1
        KJ=1
        DO 330 J=1,NSZ
          KJ=KJ+J
          SK(NBUF)=XK*SK(KJ)
          IF(NBD.EQ.1) SK(NBUF)=-SK(NBUF)
330      NBUF=NBUF+1
        SK(NBUF)=NSZ
        NBUF=NBUF+1
        SK(NBUF)=NNP
        DO 360 J=1,NSZ
          IF(SK(IA).EQ.0.) GO TO 360
          IF(NBD.EQ.1) GO TO 350
          JB=(J*(J+1))/2+1
          KJ=1
          DO 340 K=1,J
            KJ=KJ+K
            IJ=JB+K
340      SK(IJ)=SK(IJ)-SK(KJ)*SK(!A)
350      JB=IC+J
          R1(JB)=R1(JB)-SK(IA)*R
360      IA=IA+1
          DO 370 J=1,NSZ
            IK=(J*(J-1))/2
            IJ=IK+J+1
            DO 370 K=1,J
              IA=IK+K

```

```

        JB=IJ+K
370      SK(IA)=SK(JB)
        IJ=(NSZ*(NSZ+1))/2+1
        IK=IJ+NSZ
        DO 380 K=IJ,IK
380      SK(K)=0.
390      CONTINUE
        NSIZ=NSIZ-NDF
        GO TO 80
400      WRITE(4) NBUF,(SK(J),J=NSK,NBUF)
        IF(NSIZ.EQ.0) NSIZ=NDF

        RETURN
        END

```

---



---



---



---

• Subroutine STIFM:

Forms and updates stiffness matrix, and calculates body forces.

---



---



---

• Written:

Last modified: JUL 14 1984

---



---



---

• Called by: SCRUBS

---



---



---

• Subroutines called:MODSFR

AUXINVARNFLOW

ROSB

---



---



---

SUBROUTINE STIFM

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,

1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,

2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,

```

3      TPWORK,LNEW
      COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
      COMMON/BOUN/NBC(400),NFIIX(400),U(800),ANG(400),TRC(800),
1      US(400,2)
      COMMON/GID/XG(6),CG(6),XMG(6),CMG(6),NGAUS,MGAUS,MCN
      COMMON/MATP/D(4,4),YM,PR,GM,HM,PPR,CLAME,ALPHA,YST
1      ,TABSTN(10,15),TABSTR(10,15)
      COMMON/NUME/P(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),
1      NOPE(12),DISE(2,12),RP,RPB,XYP(3)
      COMMON/INV/SMEAN,STJ2,STJ3,SIGMA,PHI,APHI,STN,CPHI,YIELD
      COMMON/FLW/ABETA,AA(4),DD(4)
      COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1      ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
2      ,COJ(2,2),COJIN(2,2),B(4,24),ESTIFM(24,24),DVD(4,4),DVDB(4)
      COMMON/FG/ FLAG(1000),BULK(1000,2),MINES(10,50),NME(10),GAMMA
      DIMENSION STRS(4)

```

```

NECN=NE*NCN
READ (8)(NOP(J),J=1,NECN),(IMAT(I),I=1,NE),(((DISN(K,I),
1      TDIS(K,I)),K=1,2),(CORD(I,J),J=1,NCORD ),I=1,NP),(((TSTS(I,J),
2      EPSTN(I,J)),I=1,5),J=1,NSTORE)
REWIND 8
DO 170 M=1,NE
      LNEW=IONARY(M)
      NASH=NCN*(LNEW-1)
      NG=MCN*(LNEW-1)
      L=IMAT(LNEW)

```

---

- 
- Uses new stiffness for failed material.
- 

---

```

10      IF(NL.NE.1) GO TO 10
      IF(BULK(LNEW,1).NE.0.) L=NMAT
      CONTINUE

```

---

- 
- Note material no. of element along sloping boundary is greater
 than NMAT by 100.
- 

---

```

IF(L.GT.NMAT) L=L-100
DO 30 K=1,NCN
  MASH=NOP(NASH+K)
  DO 20 I=1,NCORD
    XYE(I,K)=CORD(MASH,I)
20   CONTINUE
    NOPE(K)=MASH
30   CONTINUE
    CALL MOD(L,0)

```

---

- Sets initial values as zeroes.
  - 
  -
- 

```

DO 40 I=1,LV
  DO 40 J=1,LV
    ESTIFM(I,J)=0.
    IF(I.LE.4) B(I,J)=0.
40   CONTINUE
    THICK=ORT(L,6)
    IF(THICK.EQ.0.) THICK=1.

```

---

- - Formulates stiffness.
  - 
  -
- 

```

DO 160 IGAUS=1,NGAUS
  DO 160 JGAUS=1,NGAUS
    G=XG(IGAUS)
    H=XG(JGAUS)
    CALL SFR(G,H)
    CALL AUX(M)
    DV=DET*CG(IGAUS)*CG(JGAUS)*THICK
    IF(NPP.EQ.2)DV=DV*RP*6.283185307179586
    IF(NCORD.EQ.3)DV=DV*XYP(3)

```

---

- Calculates B matrix from DI matrix.
  - 
  -
-

```

NASH=0
DO 50 I=1,NCN
  MASH=NASH+1
  NASH=MASH+1
  B(1,MASH)=DI(1,I)
  B(2,NASH)=DI(2,I)
  B(3,MASH)=DI(2,I)
  B(3,NASH)=DI(1,I)
  IF(NPP.EQ.2) B(4,MASH)=P(I)/RP
50      CONTINUE

```

---

- 
- Calculates DVD matrix.
- 

---

```

DO 60 I=1,ICS
  DO 60 J=1,ICS
    DVD(I,J)=DV*D(I,J)
60      CONTINUE

```

---

- 
- Tangential stiffness calculations.
- 

---

```

NG=NG+1
PSTY=TSTS(5,NG)
PSTRN=EPSTN(5,NG)
IF(ORT(L,2).LT.0.0) GO TO 110
IF(PSTRN.EQ.0.) GO TO 110
MASH=0
70      MASH=MASH+1
        IF(PSTRN.LT.TABSTN(L,MASH)) GO TO 80
        GO TO 70
80      NASH=MASH
        MASH=NASH-1
        ETAB=TABSTN(L,NASH)-TABSTN(L,MASH)
        GASH=(PSTRN-TABSTN(L,MASH))/ETAB
        CYIELD=TABSTR(L,MASH)*((1-GASH)+GASH*TABSTR(L,NASH))
        IF(PSTY.LT.9999*CYIELD) GO TO 110
        HM=(TABSTR(L,NASH)-TABSTR(L,MASH))/ETAB
        DO 90 I=1,4

```

```

90      STRS(I)=TSTS(I,NG)
        CALL INVAR  (STRS)
        CALL NFLOW(STRS)
        CON=DV*ABETA
        DO 100 I=1,ICS
          DO 100 J=1,ICS
            DVD(I,J)=DV-CON*DD(I)*DD(J)
100      DO 150 J=1,LV
          DO 130 K=1,ICS
            GASH=0.
            DO 120 I=1,ICS
              GASH=GASH+DVD(K,I)*B(I,J)
120      DVDB(K)=GASH
130      DO 150 I=J,LV
              GASH=ESTIFM(I,J)
              DO 140 K=1,ICS
                GASH=GASH+B(K,I)*DVDB(K)
140      ESTIFM(J,I)=GASH
150      ESTIFM(I,J)=GASH
160      CONTINUE
        IF(IMAT(LNEW) GT NMAT) CALL ROSB
        WRITE(3)
1       LNEW,(NOPE(I),I=1,NCN),((ESTIFM(I,J),J=1,LV),I=1,LV)
170      CONTINUE
        A=0.
        N=0
        WRITE(3)N,(N,I=1,NCN),((A,J=1,LV),I=1,LV)
        REWIND 3

        RETURN
      END

```

•  
•  
• Subroutine SWITCH:  
• Switches coordinates.

•  
• Written:  
• Last modified: JUL 19 1984

•  
• Called by: FTEST

SUBROUTINE SWITCH(J,K)

I=K

K=J

J=I

RETURN

END

•  
•  
• Subroutine TFORM:  
• Makes adjustments for inclined boundary situations

•  
• Written:  
• Last modified: JUL 14 1984

•  
•  
• Called by: SCRUBS

SUBROUTINE TFORM

```
IMPLICIT DOUBLE PRECISION (A-H,O-Z)
COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD
COMMON/BOUN/NBC(400),NFIIX(400),U(800),ANG(400),TRC(800),
1 US(400,2)
COMMON/LDS/R1(2000),RL(2000),RT(2000)

DO 10 M=1,NB
   IF(ANG(M).EQ.0.) GOTO 10
   N=NBC(M)
   NASH=2*N
   MASH=MASH-1
   GASH=ANG(M)*.017453292
   CS=COS(GASH)
   TN=TAN(GASH)
   RXC=R1(MASH)*CS
   RYC=R1(NASH)*CS
   R1(MASH)=RXC+RYC*TN
   R1(NASH)=RYC-RXC*TN
10 CONTINUE

      RETURN
      END
```

• Subroutine AUX:  
 • Creates coordinate jacobian 0 interpolate X; YOCOJ(I,J),XY(1),XY(2)  
 • are respectively the coordinate jacobian matrix, the X  
 • coordinate and the Y coordinate.

• Written:  
 • Last modified: MAR 16 1984

• Called by: LDATAREMLDRESIDUE  
 • STIFM

#### SUBROUTINE AUX(M)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

```

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPP,ICS,
1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2 NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3 TPWORK,LNEW
COMMON/NUME/P(12),DEL(2,12),DET,DI(2,12),DIJ(2,2),XYE(3,12),
1 NOPE(12),DISE(2,12),RP,RPB,XYP(3)
COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000)
2 ,COJ(2,2),COJIN(2,2)

```

DO 20 I = 1,2

DO 20 J = 1,2

GASH = 0.

DO 10 K = 1,NCN

GASH = GASH+XYE(I,K)\*DEL(J,K)

10 CONTINUE

COJ(I,J) = GASH

20 CONTINUE

DO 40 I = 1,NCORD

GASH = 0.

DO 30 K = 1,NCN

GASH = GASH+XYE(I,K)\*P(K)

```

30      CONTINUE
      XYP(I) = GASH
40      CONTINUE
      RP = XYP(1)

```

---

- - Calculates the determinant and inverse of the coordinate Jacobian.
  - DET and COJIN(I,J) are determinant and inverse coordinate jacobian, respectively.
  -
- 

```

DET = COJ(1,1)*COJ(2,2)-COJ(1,2)*COJ(2,1)
IF(DET)50,70,90
50      CONTINUE
C      WRITE(6,60)M,((XYE(JJ,II),JJ = 1,2),II = 1,4),DET,COJ(1,1),
C + COJ(2,2),COJ(1,2),COJ(2,1)
60      FORMAT(' NEGATIVE DET STOPPED AT ELEMENT NO =',
+        I3.,' X1,Y1',2F8.2,' X2,Y2',2F8.2,' X3,Y3',2F8.2,
+        /,' X4,Y4',2F8.2,' DET',D12.4,' COJ(1,1),COJ(2,2)'
+        ,2D12.4,' COJ(1,2),COJ(2,1)',2D12.4)
C      STOP
70      DET = 000001
      WRITE(6,80)M
80      FORMAT(' ZERO DETERMINENT EL NO ',I3)
90      CONTINUE
      COJIN(1,1) = COJ(2,2)/DET
      COJIN(2,2) = COJ(1,1)/DET
      COJIN(1,2) = -COJ(1,2)/DET
      COJIN(2,1) = -COJ(2,1)/DET

```

---

- - Calculates cartesian derivatives of shape functions DI(I,K), I=X,Y.
  -
- 

```

DO 120 I = 1,2
DO 110 K = 1,NCN
      GASH = 0.
      DO 100 J = 1,2
          GASH = GASH+DEL(J,K)*COJIN(J,I)
100     CONTINUE
      DI(I,K) = GASH

```

110 CONTINUE

120 CONTINUE

RETURN

END

---



---

- Subroutine ZONE:
- This subroutine reads meshing cards as done in the CHILES2 program. It is provided here only as an interim capability.
- This subroutine is called by the main program.

---



---

- Written:
- Last modified: JUL 19 1984

---



---

- Called by: SCRUBS

#### SUBROUTINE ZONE (NRS)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)  
 COMMON/SCR/ R(2000),Z(2000),IX(5,2000),CODE(2000)  
 COMMON/QMESH/NEL

---



---

- Reads element properties from SCRUBS.DAT.

---



---

```

READ(5,10) NEL,NODES,NUMPC
10  FORMAT (6I5)
      IBOMB=0
      IF(NEL.NE.0) GO TO 30
      WRITE(6,20)
20  FORMAT(' *****MESH GENERATOR QMESH USED FOR GRID INPUT*****')
      RETURN
30  CONTINUE
  
```

```

        WRITE(6,40) NEL,NODES,NUMPC
40      FORMAT (4X,'NUMBER OF ELEMENTS (NEL)-----',
1           '-----',I5/4X,'NUMBER OF NODAL POINTS (NODES)---'
2           '-----',I5/4X,'NUMBER OF PRESSURE CARDS '
3           '(NUMPC)-----',I5)

```

---

- NEL = 0 for mesh generator, NEL = -1 for restart.
- 

---

```

IF (NEL.LT.0) NRS=1
IF(NRS.EQ.1) RETURN
NFORCE=NUMPC
NUMSC=NUMPC
N=0
50     READ(5,10) M,(IX(I,M),I=1,5)
60     N=N+1
       IF (M-N) 100,80,70
70     IX(1,N)=IX(1,N-1)+1
       IX(2,N)=IX(2,N-1)+1
       IX(3,N)=IX(3,N-1)+1
       IX(4,N)=IX(4,N-1)+1
       IX(5,N)=IX(5,N-1)
80     IF (M-N) 100,90,60
90     IF (NEL-N) 120,120,50
100    WRITE(6,110) M
110    FORMAT (' ***FATAL ERROR  ELEMENT CARD, M=',I5)
       IBOMB=1
120    CONTINUE

```

---

- Read nodal point data.
- 

---

```

N=0
130   READ (5,140) M,CODE(M),R(M),Z(M)
140   FORMAT (I5,F5.0,4E10.0)
       NNL=N+1
       IF (NNL EQ 1) GO TO 150
       ZX=FLOAT(M-N)
       DR=(R(M)-R(N))/ZX

```

```

DZ=(Z(M)-Z(N))/ZX
150    N=N+1
       IF (M-N) 180,170,160
160    IF (CODE(NNL-1).EQ.CODE(M)) CODE(N)=CODE(M)
       R(N)=R(N-1)+DR
       Z(N)=Z(N-1)+DZ
       GO TO 150
170    IF (NODES-M) 180,200,130
180    WRITE (6,190) M
190    FORMAT (' ***FATAL ERROR  NODAL POINT CARD, M=',I5)
       IBOMB=1
200    CONTINUE
       WRITE(9) NEL,NODES
       WRITE(9) (R(I),Z(I),I=1,NODES)
       WRITE(9)((IX(I,M),I=1,5),M=1,NEL)
       REWIND 9

```

---



---



---



---

\* Output mesh.

---



---



---

```

MPRINT=0
DO 230 I=1,NEL
       IF (MPRINT.NE.0) GO TO 210
       MPRINT=50
210    MPRINT=MPRINT-1
       WRITE(6,220) I,(IX(J,I),J=1,5)
220    FORMAT(1I13,4I6,I7)
230    CONTINUE
       MPRINT=0
       DO 260 I=1,NODES
          IF(MPRINT.NE.0) GO TO 240
          MPRINT=50
240    MPRINT=MPRINT-1
          WRITE(6,250) I,R(I),Z(I)
250    FORMAT(6X,I6,2F12.3)
260    CONTINUE

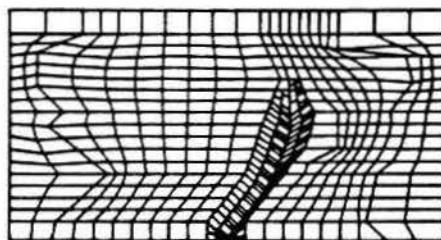
       RETURN
END

```

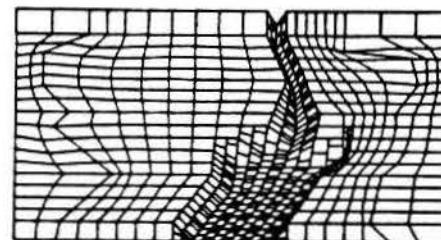
## **APPENDIX D**

### **ADDITIONAL SUBSIDENCE RESULTS**

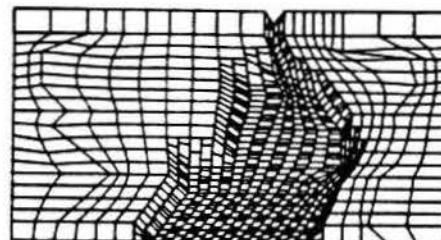
The following appendix contains additional results from running SCRUBS on the subsidence prediction problem found in chapter four. These three runs have been left out of the main report since they were results obtained during the course of trying to find good test parameters and were not considered to be as important to the conclusions as the tests included in the body of the report. However, it was thought that some readers may obtain valuable insights and information from them, so they have been included here. The test parameters varied in these tests were the failure stress. The failure stress used is listed in the figure heading.



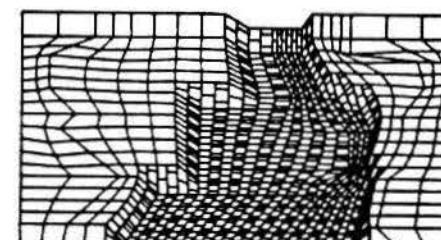
a. One support removed.



b. Three supports removed.

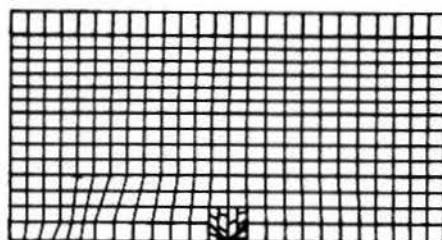


c. Five supports removed.

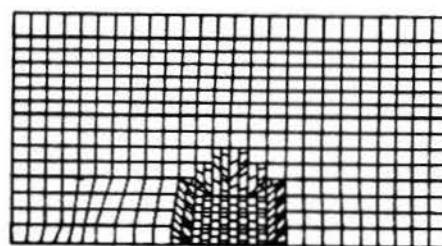


d. Seven supports removed.

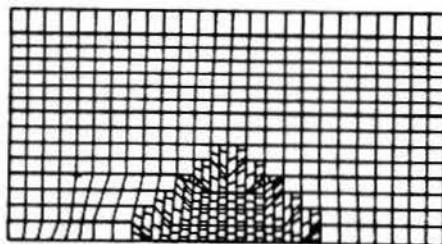
Figure 17 a-d. Jointed media skewed mesh. Failure stress was  $0.1 \times 10^5$  dynes/cm $^2$ .



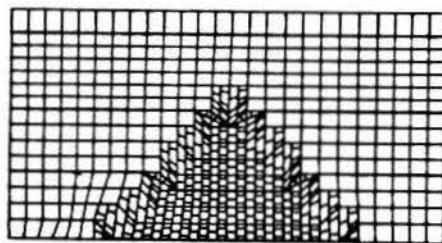
a. One support removed.



b. Three supports removed.

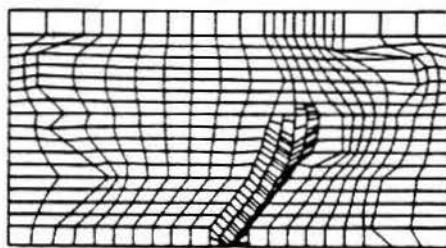


c. Five supports removed.

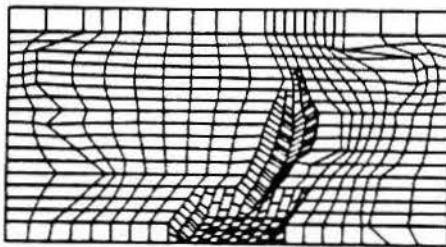


d. Seven supports removed.

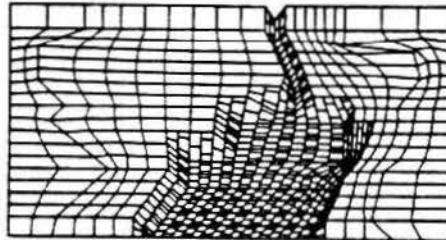
Figure 18 a-d. Discrete slip plane straight mesh. Failure stress was  $0.1 \times 10^9$  dynes/cm $^2$ .



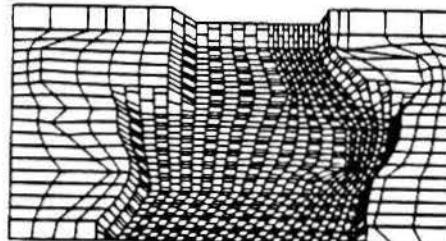
a. One support removed.



b. Three supports removed.



c. Five supports removed.



d. Seven supports removed.

Figure 19 a-d. Discrete slip plane skewed mesh. Failure stress was  $0.1 \times 10^5$  dynes/cm $^2$ .

## **APPENDIX E**

### **SELECTED FILES**

The following appendix contains typical files used in subsidence prediction with SCRUBS.BYU. First is the file FTEST, which is compiled with scrubs but is user-supplied (the one in this appendix is the one used to obtain our results), next are the two QMESH card input files used to create the meshes, and last is a typical SCRUBS.BYU data file used to obtain the combined skewed mesh model. To read the QMESH card files, the reader should consult reference 8. To read the SCRUBS.BYU data file, the user should consult appendix B, the SCRUBS.BYU user's manual. The SCRUBS.BYU subroutine FTEST is written in standard fortran and contains comments to show what is done.

## CARD DESCRIPTIONS

The subroutine FTEST:

- 
- 
- Subroutine FTEST:  
This is a user supplied subroutine to determine the failure of element M.
- 
- Written:  
Last modified: JUL 19 1984
- 
- 
- 
- Called by: RESIDUE
- 
- 
- Subroutines called:REMLDSWITCH
- 
- 
- 

SUBROUTINE FTEST(M,SAVG,MATNO,IFLFG)

IMPLICIT DOUBLE PRECISION (A-H,O-Z)

COMMON/CONTR/TITLE(20),NP,NE,NB,NDF,NCN,NSFR,NSZF,LV,NPF,ICS,

```

1 NCORD,NSK,NSIZ,NL,NBUF,NT,ND,NNP,ILD,NLD,NMAT,IT,NIT,INC,NINC,
2      NSTORE,MPR,LDTYPE,FACTOR,OMEGA,CONFAC,NYIELD,ISTS,NALGO,PWORK,
3      TPWORK,KNE
      COMMON/FG/ FLAG(1000),BULK(1000,2),MINE(10,50),NME(10)
      COMMON/GEP/FAC(40),NOUT(40),ORT(10,10),NOPR(30),IONARY(1000)
      DIMENSION SAVG(5),NM(4),MB(1000)
      COMMON/SCR/DIS(2,1000),TDIS(2,1000),DISN(2,1000),CORD(1000,2)
1 ,NOP(4000),IMAT(1000),TSTS(5,4000),EPSTN(5,4000),DUMMY(1000)
      COMMON/GID/XG(6),CG(6),XMG(6),CMG(6),NGAUS,MGAUS,MCN

```

IFLFG=0

- On first iteration, cycle 1, determines if element below element M has failed and creates MB(M) where MB(M) is the element number of the element below M.
  - 
  -
- 

```
IF (INC.GT.1) GO TO 70
IF (IT.GT.1) GO TO 70
```

---

- - Finds four nodes associated with element M.
  - 
  -
- 

```
N1=NCN*(M-1)
DO 10 I=1,NCN,NSFR
    IX=I+N1
10      NM(I)=NOP(IX)
```

---

- - Finds two lowest nodes of element M.
  - 
  -
- 

```
DO 30 I=1,3
    DO 20 I1=1,3
        I2=I1+1
20      IF(CORD(NM(I1),2).GT.CORD(NM(I2),2))CALL SWITCH(NM(I1),
&          NM(I2))
30      CONTINUE
```

---

- - Finds element below element M (this is the element which has the two bottom nodes of element M as its two top nodes).
  - 
  -
- 

```
MB(M)=-1
DO 60 I=1,NE
    IF(M.EQ.I) GO TO 60
    KKK=NCN*(I-1)
    IM=0
```

```

DO 50 IG=1,NCN,NSFR
  KK=KKK+IG
  IF(NOP(KK) EQ NM(1).OR.NOP(KK) EQ NM(2))GOTO 40
  GOTO 50
40   IM=IM+1
  IF(IM.EQ.2)MB(M)=1
50   CONTINUE
60   CONTINUE
70   CONTINUE

```

---

- - For first iteration, checks for mined out or specified element failure.
  -
- 

```

IF(IT.NE.1) GO TO 90
NMEL=NME(INC)
IF(NMEL.EQ.0) GO TO 90
DO 80 I=1,NMEL
  IF(MINE(INC,I) EQ M) GO TO 170
80   CONTINUE

```

---

- - Sets the failure criteria value to sigfail.
  -
- 

```
90   SIGFAIL=ORT(MATNO,7)
```

```
IF(BULK(M,1).NE.0.0) RETURN
```

---

- - If bottom element MB(M) has failed, and element (M) is a slide line, then fails the slide line directly.
  -
- 

```
MBTEST=MB(M)
IF (NNP.EQ.0) GO TO 110
IF (MBTEST.LT.0) GO TO 110
IF(BULK(MBTEST,1).EQ.0) GO TO 110
```

IF (MATNO.EQ.NMAT-1) GO TO 170

110 CONTINUE

```
MSTRT=(M-1)*MCN
DO 160 I=1,MCN
    INDEX=MSTRT+I
```

- Compares the failure criteria with the current state of stress at this point in the logic for a failure test.

- In this specific application, the failure measure is taken as either the vertical stress or the horizontal stress.

- Also, no element is allowed to fail if the element below it has not failed, nor if it has no elements below it.
- if the element is a slide line, fail with no stress check.

- TSTS(1,INDEX)=HORIZONTAL STRESS
- TSTS(2,INDEX)=VERTICAL STRESS

- BULK(M,1)=0 ELEMENT HAS NOT FAILED
- BULK(M,1)=1 ELEMENT HAS FAILED

```
STR1=TSTS(1,INDEX)
STR2=TSTS(2,INDEX)
IF(MBTEST LT 0) RETURN
IF((STR1.GT.SIGFAIL.AND.BULK(MBTEST,1).NE.0.0).OR.
& (STR2.GT.SIGFAIL.AND.BULK(MBTEST,1).NE.0.0)) GOTO 170
```

160 CONTINUE  
RETURN

- States that element has failed, and increases value of flag by 1 on each node.

170 CONTINUE

```

IFLFG=1
WRITE(6,180) M
180      FORMAT(' * * * * ELEMENT ',I5,' HAS BECOME RUBBLE '
&           ' * * * * ')
DO 190 I=1,4
  KK = 4*(M-1)+I
  NODE=NOP(KK)
190      FLAG(NODE)=FLAG(NODE)+1.0

```

---

- 
- 
- Sets BULK(M,1) = 1.0 for failed element.
- 
- 

---

BULK(M,1) = 1.0

---

- 
- 
- Removes gravity loading from failed element.
- 
- 

---

CALL REMLD(M)

---

- 
- 
- Computes element area just prior to failure.
- 
- 

---

K1=(M-1)\*4+1  
 K2=K1+1  
 K3=K2+1  
 K4=K3+1  
 J1=NOP(K1)  
 J2=NOP(K2)  
 J3=NOP(K3)  
 J4=NOP(K4)  
 COE1=CORD(J2,1)-CORD(J4,1)  
 COE2=CORD(J3,2)-CORD(J1,2)  
 COE3=CORD(J3,1)-CORD(J1,1)  
 COE4=CORD(J4,2)-CORD(J2,2)  
 AREA= 5\*(COE1\*COE2+COE3\*COE4)  
 AOLD=BULK(M,2)

```

        BULK(M,2)=AREA
200      WRITE(6,210) AOLD,AREA
210      FORMAT(' AOLD ANEW ',2E15.5)

        RETURN
        END

```

This is the QMESH input card file used to create the skewed mesh (again, for those readers not familiar with QMESH, see reference 8) :

COMLEN	SKEWED MESH			
POINT	1/	1.6500	62.4500	0
POINT	38/	21.2000	62.4500	0
POINT	45/	30.8000	62.4500	0
POINT	39/	68.9000	62.4500	0
POINT	40/	90.0000	62.4500	0
POINT	2/	118.3500	62.4500	0
POINT	3/	1.6500	56.1000	0
POINT	4/	21.2000	56.1000	0
POINT	46/	30.8000	56.1000	0
POINT	5/	68.9000	56.1000	0
POINT	6/	90.0000	56.1000	0
POINT	7/	118.3500	56.1000	0
POINT	8/	90.0000	52.1000	0
POINT	9/	9.0000	51.1000	0
POINT	10/	103.5000	50.1000	0
POINT	11/	9.0000	42.1000	0
POINT	12/	74.5000	44.1000	0
POINT	13/	11.0000	43.1000	0
POINT	14/	1.6500	35.1000	0
POINT	15/	16.0000	35.1000	0
POINT	16/	63.0000	35.1000	0
POINT	17/	71.0000	35.1000	0
POINT	18/	90.0000	35.1000	0
POINT	19/	104.0000	35.1000	0
POINT	20/	118.3500	35.1000	0
POINT	21/	12.0000	31.1000	0
POINT	22/	90.0000	25.1000	0
POINT	23/	82.0000	21.1000	0
POINT	24/	1.6500	18.1000	0
POINT	25/	28.0000	18.1000	0
POINT	47/	33.0000	18.1000	0
POINT	26/	60.0000	18.1000	0
POINT	27/	65.0000	18.1000	0

POINT	28/	81.0000	18.1000		0
POINT	29/	100.5000	18.1000		0
POINT	30/	118.3500	18.1000		0
POINT	31/	1.6500	5.1000		0
POINT	32/	14.1000	5.1000		0
POINT	41/	24.3000	5.1000		0
POINT	33/	54.9000	5.1000		0
POINT	42/	95.7000	5.1000		0
POINT	34/	97.5000	5.1000		0
POINT	35/	118.3500	5.1000		0
POINT	36/	1.6500	0.0000		0
POINT	43/	24.3000	0.0000		0
POINT	44/	95.7000	0.0000		0
POINT	37/	118.3500	0.0000		0
LINE STR	138/	1 38	0 2	1.0000	0
LINE STR	13/	1 3	0 1	1.0000	100
LINE STR	345/	38 45	0 2	1.0000	0
LINE STR	439/	45 39	0 6	1.0000	0
LINE STR	340/	39 40	0 8	1.0000	0
LINE STR	402/	40 2	0 3	1.0000	0
LINE STR	27/	2 7	0 1	1.0000	100
LINE STR	34/	3 4	0 2	1.0000	40
LINE STR	314/	3 14	0 7	1.0000	100
LINE STR	446/	4 46	0 2	1.0000	40
LINE STR	49/	4 9	0 2	1.0000	50
LINE STR	465/	46 5	0 6	1.0000	40
LINE STR	56/	5 6	0 8	1.0000	40
LINE STR	512/	5 12	0 4	1.0000	60
LINE STR	67/	6 7	0 3	1.0000	40
LINE STR	68/	6 8	0 1	1.0000	90
LINE STR	720/	7 20	0 7	1.0000	100
LINE STR	810/	8 10	0 1	1.0000	90
LINE STR	911/	9 11	0 3	1.0000	50
LINE STR	113/	10 13	0 2	1.0000	90
LINE STR	115/	11 15	0 2	1.0000	50
LINE STR	117/	12 17	0 3	1.0000	60
LINE STR	119/	13 19	0 3	1.0000	90
LINE STR	415/	14 15	0 2	1.0000	30
LINE STR	124/	14 24	0 5	1.0000	100
LINE STR	116/	15 16	0 7	1.0000	30
LINE STR	121/	15 21	0 1	1.0000	50
LINE STR	617/	16 17	0 1	1.0000	30
LINE STR	126/	16 26	0 5	1.0000	70
LINE STR	118/	17 18	0 3	1.0000	30
LINE STR	819/	18 19	0 5	1.0000	30

LINE STR 122/ 18 22 0 3 1.0000 110  
 LINE STR 120/ 19 20 0 3 1.0000 30  
 LINE STR 230/ 20 30 0 5 1.0000 100  
 LINE STR 225/ 21 25 0 4 1.0000 50  
 LINE STR 223/ 22 23 0 1 1.0000 110  
 LINE STR 228/ 23 28 0 1 1.0000 110  
 LINE STR 425/ 24 25 0 2 1.0000 20  
 LINE STR 231/ 24 31 0 4 1.0000 100  
 LINE STR 247/ 25 47 0 2 1.0000 20  
 LINE STR 232/ 25 32 0 4 1.0000 50  
 LINE STR 426/ 47 26 0 5 1.0000 20  
 LINE STR 227/ 26 27 0 1 1.0000 20  
 LINE STR 728/ 27 28 0 3 1.0000 20  
 LINE STR 233/ 27 33 0 4 1.0000 80  
 LINE STR 229/ 28 29 0 6 1.0000 20  
 LINE STR 930/ 29 30 0 2 1.0000 20  
 LINE STR 234/ 29 34 0 4 1.0000 120  
 LINE STR 335/ 30 35 0 4 1.0000 100  
 LINE STR 332/ 31 32 0 2 1.0000 10  
 LINE STR 336/ 31 36 0 1 1.0000 100  
 LINE STR 341/ 32 41 0 2 1.0000 10  
 LINE STR 433/ 41 33 0 6 1.0000 10  
 LINE STR 342/ 33 42 0 8 1.0000 10  
 LINE STR 434/ 42 34 0 1 1.0000 10  
 LINE STR 435/ 34 35 0 2 1.0000 10  
 LINE STR 337/ 35 37 0 1 1.0000 100  
 LINE STR 343/ 36 43 0 4 1.0000 200  
 LINE STR 444/ 43 44 0 14 1.0000 200  
 LINE STR 437/ 44 37 0 3 1.0000 200  
 SIDE 12/ 138 345 439 340 402  
 SIDE 37/ 34 446 465 56 67  
 SIDE 45/ 446 465  
 SIDE 415/ 49 911 115  
 SIDE 517/ 512 117  
 SIDE 619/ 68 810 113 119  
 SIDE 117/ 116 617  
 SIDE 118/ 617 118  
 SIDE 119/ 118 819  
 SIDE 120/ 819 120  
 SIDE 125/ 121 225  
 SIDE 128/ 122 223 228  
 SIDE 226/ 247 426  
 SIDE 227/ 247 426 227  
 SIDE 228/ 227 728  
 SIDE 229/ 728 229

```

SIDE    230/ 229  930
SIDE    333/ 341  433
SIDE    334/ 342  434
SIDE    335/ 332  341  433  342  434  435
SIDE    337/ 343  444  437
REGION  1   1/  12 -27  37 -13
REGION  2   2/  45  517  117  415
REGION  2   3/-116 -126  226  125
REGION  2   4/ 227 -233  333 -232
REGION  2   5/ -56  619  119  517
REGION  2   6/ 118  128  228 -126
REGION  2   7/ 229 -234  334 -233
REGION  3   8/ -34  415 -415 -314
REGION  3   9/-415  125 -425 -124
REGION  3   10/-425 -232 -332 -231
REGION  3   11/ -67 -720 -120  619
REGION  3   12/ 120 -230  230  128
REGION  3   13/-930 -335 -435 -234
REGION  4   14/ 335 -337  337 -336
SCHEME   1M
SCHEME   2MS2S
SCHEME   3MS2S5S
SCHEME   4MS
SCHEME   5MS
SCHEME   6MS2S5S
SCHEME   7MS
SCHEME   8MS
SCHEME   9MS2S
SCHEME   10MS
SCHEME   11MS
SCHEME   12MS
SCHEME   13MS
SCHEME   14MS
END      4
P-L-     36  343  43  444  44  437  37
END

```

This is the QMESH input card file used to create the straight mesh (again, for those readers not familiar with QMESH, see reference 8) :

```

COMMEN STRAIGHT MESH
POINT   1/  1.6500  62.4500      0
POINT   8/ 15.0000  62.4500      0
POINT   20/ 70.0000  62.4500      0

```

POINT	9/	100.0000	62.4500		0		
POINT	2/	118.3500	62.4500		0		
POINT	3/	1.6500	56.1000		0		
POINT	4/	15.0000	56.1000		0		
POINT	5/	70.0000	56.1000		0		
POINT	6/	100.0000	56.1000		0		
POINT	7/	118.3500	56.1000		0		
POINT	10/	1.6500	35.1000		0		
POINT	11/	15.0000	35.1000		0		
POINT	12/	60.0000	35.1000		0		
POINT	13/	70.0000	35.1000		0		
POINT	14/	85.0000	35.1000		0		
POINT	15/	100.0000	35.1000		0		
POINT	16/	118.3500	35.1000		0		
POINT	17/	1.6500	18.1000		0		
POINT	18/	15.0000	18.1000		0		
POINT	19/	60.0000	18.1000		0		
POINT	21/	85.0000	18.1000		0		
POINT	22/	100.0000	18.1000		0		
POINT	23/	118.3500	18.1000		0		
POINT	24/	1.6500	5.1000		0		
POINT	25/	15.0000	5.1000		0		
POINT	26/	24.3000	5.1000		0		
POINT	27/	60.0000	5.1000		0		
POINT	28/	95.7000	5.1000		0		
POINT	29/	100.0000	5.1000		0		
POINT	30/	118.3500	5.1000		0		
POINT	31/	1.6500	0.0000		0		
POINT	32/	24.3000	0.0000		0		
POINT	33/	95.7000	0.0000		0		
POINT	34/	118.3500	0.0000		0		
LINE STR	18/	1	8	0	3	1.0000	0
LINE STR	820/	8	20	0	12	1.0000	0
LINE STR	209/	20	9	0	6	1.0000	0
LINE STR	92/	9	2	0	4	1.0000	0
LINE STR	13/	1	3	0	1	1.0000	100
LINE STR	27/	2	7	0	1	1.0000	100
LINE STR	34/	3	4	0	3	1.0000	40
LINE STR	310/	3	10	0	6	1.0000	100
LINE STR	45/	4	5	0	12	1.0000	40
LINE STR	411/	4	11	0	6	1.0000	50
LINE STR	56/	5	6	0	6	1.0000	40
LINE STR	513/	5	13	0	6	1.0000	60
LINE STR	67/	6	7	0	4	1.0000	40
LINE STR	615/	6	15	0	6	1.0000	90

LINE STR 716/ 7 16 0 6 1.0000 100  
LINE STR 111/ 10 11 0 3 1.0000 30  
LINE STR 117/ 10 17 0 4 1.0000 100  
LINE STR 112/ 11 12 0 10 1.0000 30  
LINE STR 113/ 12 13 0 2 1.0000 30  
LINE STR 119/ 12 19 0 4 1.0000 80  
LINE STR 114/ 13 14 0 3 1.0000 30  
LINE STR 115/ 14 15 0 3 1.0000 30  
LINE STR 121/ 14 21 0 4 1.0000 130  
LINE STR 116/ 15 16 0 4 1.0000 30  
LINE STR 123/ 16 23 0 4 1.0000 100  
LINE STR 118/ 11 18 0 4 1.0000 50  
LINE STR 718/ 17 18 0 3 1.0000 20  
LINE STR 124/ 17 24 0 3 1.0000 100  
LINE STR 819/ 18 19 0 10 1.0000 20  
LINE STR 125/ 18 25 0 3 1.0000 50  
LINE STR 921/ 19 21 0 5 1.0000 20  
LINE STR 127/ 19 27 0 3 1.0000 80  
LINE STR 222/ 21 22 0 3 1.0000 20  
LINE STR 223/ 22 23 0 4 1.0000 20  
LINE STR 229/ 22 29 0 3 1.0000 140  
LINE STR 230/ 23 30 0 3 1.0000 100  
LINE STR 225/ 24 25 0 3 1.0000 10  
LINE STR 226/ 25 26 0 3 1.0000 10  
LINE STR 227/ 26 27 0 7 1.0000 10  
LINE STR 231/ 24 31 0 1 1.0000 100  
LINE STR 228/ 27 28 0 7 1.0000 10  
LINE STR 829/ 28 29 0 1 1.0000 10  
LINE STR 930/ 29 30 0 4 1.0000 10  
LINE STR 334/ 30 34 0 1 1.0000 100  
LINE STR 332/ 31 32 0 6 1.0000 200  
LINE STR 333/ 32 33 0 14 1.0000 200  
LINE STR 433/ 33 34 0 5 1.0000 200  
SIDE 12/ 18 820 209 92  
SIDE 37/ 34 45 56 67  
SIDE 113/ 112 113  
SIDE 114/ 113 114  
SIDE 115/ 114 115  
SIDE 116/ 115 116  
SIDE 122/ 921 222  
SIDE 223/ 222 223  
SIDE 230/ 225 226 227 228 829 930  
SIDE 227/ 226 227  
SIDE 229/ 228 829  
SIDE 334/ 332 333 433

```

REGION  1  1/ 12 -27  37 -13
REGION  2  2/ -45 -513  113 -411
REGION  2  3/-112 -119 -819 -118
REGION  2  4/-819 -127  227 -125
REGION  2  5/ -56 -615  115 -513
REGION  2  6/ 114 -121 -921 -119
REGION  2  7/ 122 -229  229 -127
REGION  3  8/ -34 -411 -111 -310
REGION  3  9/-111 -118 -718 -117
REGION  3  10/-718 -125 -225 -124
REGION  3  11/ -67 -716 -116 -615
REGION  3  12/ 116 -123  223 -121
REGION  3  13/-223 -230 -930 -229
REGION  4  14/ 230 -334  334 -231
SCHEME   1M
SCHEME   2M
SCHEME   3M
SCHEME   4M
SCHEME   5M
SCHEME   6M
SCHEME   7M
SCHEME   8M
SCHEME   9M
SCHEME   10M
SCHEME   11M
SCHEME   12M
SCHEME   13M
SCHEME   14M
END      4
P-L      31  332  32  333  33  433  34
END

```

This is the SCRUBS.BYU data file used to create the failure and subsidence of Figure 15 a-d:

```

0
1
JOINTED MEDIA WITH HORIZONTAL SLIP - SKEWED MESH
0  0  58  1  2  6  1  2  3  0  1  0  1  0  2  2
1- 6000E+110.6000E+060.1000E+21 1.000  0.0000E+000.0000E+00
2- 5500E+12- 2700E+120.1000E+21 1.000  0.0000E+000.0000E+00
10.000  0.10000E+09
3- 5500E+12- 2700E+120.1000E+21 1.000  0.0000E+000.0000E+00
10.000  0.10000E+09

```

40.2000E+130.3000 0.1000E+21 1.000 0.0000E+000.0000E+00  
5- 3450E+120.3450E+120.1000E+32 1.000 0.0000E+000.0000E+00  
6- 6000E+080.6000E+060.1000E+21 1.000 0.0000E+000.0000E+00  
10.1000E+070.9800  
20.1000E+070.9800  
30.1000E+070.9800  
40.0000E+00 60.00  
50.0000E+00 1.000  
60.0000E+000.0000E+00  
0.0000E+00  
5  
0 4 8 8 8

224 228 368 369  
140 144 232 236 366 367 370 371  
132 136 240 244 364 365 372 373  
124 128 248 252 362 363 374 375  
4 0 58 0  
1 11 0.000E+00 0.000E+00 0.000E+00  
2 1 0.000E+00 0.000E+00 0.000E+00  
3 1 0.000E+00 0.000E+00 0.000E+00  
4 1 0.000E+00 0.000E+00 0.000E+00  
5 1 0.000E+00 0.000E+00 0.000E+00  
6 1 0.000E+00 0.000E+00 0.000E+00  
7 1 0.000E+00 0.000E+00 0.000E+00  
8 1 0.000E+00 0.000E+00 0.000E+00  
9 1 0.000E+00 0.000E+00 0.000E+00  
10 1 0.000E+00 0.000E+00 0.000E+00  
11 1 0.000E+00 0.000E+00 0.000E+00  
12 1 0.000E+00 0.000E+00 0.000E+00  
13 1 0.000E+00 0.000E+00 0.000E+00  
14 1 0.000E+00 0.000E+00 0.000E+00  
15 1 0.000E+00 0.000E+00 0.000E+00  
16 1 0.000E+00 0.000E+00 0.000E+00  
17 1 0.000E+00 0.000E+00 0.000E+00  
18 1 0.000E+00 0.000E+00 0.000E+00  
19 1 0.000E+00 0.000E+00 0.000E+00  
20 1 0.000E+00 0.000E+00 0.000E+00  
21 1 0.000E+00 0.000E+00 0.000E+00  
22 11 0.000E+00 0.000E+00 0.000E+00  
23 10 0.000E+00 0.000E+00 0.000E+00  
44 10 0.000E+00 0.000E+00 0.000E+00  
45 10 0.000E+00 0.000E+00 0.000E+00  
66 10 0.000E+00 0.000E+00 0.000E+00  
67 10 0.000E+00 0.000E+00 0.000E+00

```

88 10 0.000E+00 0.000E+00 0.000E+00
89 10 0.000E+00 0.000E+00 0.000E+00
110 10 0.000E+00 0.000E+00 0.000E+00
111 10 0.000E+00 0.000E+00 0.000E+00
132 10 0.000E+00 0.000E+00 0.000E+00
133 10 0.000E+00 0.000E+00 0.000E+00
154 10 0.000E+00 0.000E+00 0.000E+00
155 10 0.000E+00 0.000E+00 0.000E+00
176 10 0.000E+00 0.000E+00 0.000E+00
177 10 0.000E+00 0.000E+00 0.000E+00
198 10 0.000E+00 0.000E+00 0.000E+00
199 10 0.000E+00 0.000E+00 0.000E+00
220 10 0.000E+00 0.000E+00 0.000E+00
221 10 0.000E+00 0.000E+00 0.000E+00
242 10 0.000E+00 0.000E+00 0.000E+00
243 10 0.000E+00 0.000E+00 0.000E+00
264 10 0.000E+00 0.000E+00 0.000E+00
265 10 0.000E+00 0.000E+00 0.000E+00
286 10 0.000E+00 0.000E+00 0.000E+00
287 10 0.000E+00 0.000E+00 0.000E+00
308 10 0.000E+00 0.000E+00 0.000E+00
309 10 0.000E+00 0.000E+00 0.000E+00
330 10 0.000E+00 0.000E+00 0.000E+00
331 10 0.000E+00 0.000E+00 0.000E+00
352 10 0.000E+00 0.000E+00 0.000E+00
353 10 0.000E+00 0.000E+00 0.000E+00
374 10 0.000E+00 0.000E+00 0.000E+00
375 10 0.000E+00 0.000E+00 0.000E+00
396 10 0.000E+00 0.000E+00 0.000E+00
397 10 0.000E+00 0.000E+00 0.000E+00
418 10 0.000E+00 0.000E+00 0.000E+00
22 2 0.100
27 28 29 30 31 32 33 25 26 41 42 34 35 36 37 38
39 40 23 24 43 44
22 2 0.100
115 116 117 118 119 120 113 114 121 122 123 124 125 126 127 128
129 130 111 112 131 132
22 2 0.100
230 231 223 224 225 226 227 228 229 234 235 236 237 238 239 232
233 221 222 240 241 242
22 2 0.100
393 394 395 396 385 386 387 388 389 390 391 392 379 380 381 382
383 384 377 378 375 376
0 1

```

GRAVITY LOAD

0 0 1 0 0 0  
0.0000E+00 1.4715E+06 0.0000E+00  
1.2500 2.6400 1.6500 7.8000 3.3350 2.6400  
5  
1.0000.0000.0000.0000.000  
0 0 0 0 0  
352.5000  
0  
0 1

APPLICATION OF COMBINED JOINTED MEDIA AND  
DISCRETE SLIP PLANE CHARACTERISTICS  
TO SUBSIDENCE PREDICTIONS

David W. Basinger

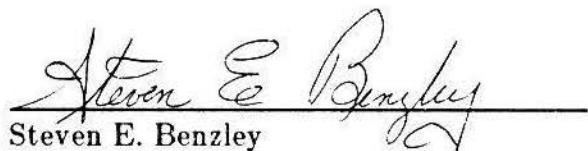
Department of Civil Engineering

M.S. Degree, December 1984

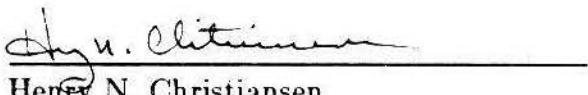
ABSTRACT

This thesis presents an application of a numerical formulation incorporating the effects of joints, cracks, and fractures to a soil subsidence prediction problem, and the extension of that formulation to combined discrete slip planes and jointed media continua formulations. The results obtained are compared to each other and to a physical centrifuge simulation performed previously on the same problem.

COMMITTEE APPROVAL:

  
\_\_\_\_\_  
Steven E. Benzley  
Committee Chairman

  
\_\_\_\_\_  
Reese J. Goodwin  
Committee Member

  
\_\_\_\_\_  
Henry N. Christiansen  
Graduate Coordinator

